

ABSTRACT DIAGNOSIS

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Comini, Levi, Meo & Vitello, Abstract Diagnosis,
JLP ~~(to appear)~~ 39, 4-3 (1989)

THE DIAGNOSIS APPROACH TO PROGRAM VERIFICATION

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- declarative diagnosis (debugging) [of logic programs]
[Shepiro 83, Fenand 87, Lloyd 87]

P logic program

I specification α (intended declarative semantics of P)

$\llbracket P \rrbracket$ (actual) declarative semantics of P

- a method to prove the correctness and completeness of P w.r.t. I
 - comparison between I and $\llbracket P \rrbracket$
 - if they are different, locate the program bugs

- abstract diagnosis

[Comini, Levi & Vihello, META 84 - AADE BUG-85 - ILPS 85]

P logic program

d desirable property

- any abstraction of SLD-trees

I_d abstract specification (intended behavior w.r.t. d)

$\llbracket P \rrbracket_d$ (actual) behavior of P w.r.t. d

- more concrete than the declarative semantics
(e.g. when d is computed answers)
- less concrete than the declarative semantics

DECLARATIVE DIAGNOSIS

VS.

ABSTRACT DIAGNOSIS

2.1

• declarative diagnosis

- declarative semantics as reference semantics
- two steps method
 - symptoms detection (using testing techniques)
 - from symptoms to errors

• abstract diagnosis

- the reference semantics can be any abstract semantics (including the declarative one)
- no need to detect symptoms in advance
 - for some abstract semantics it may be non-effective

DIAGNOSIS AND THE S-SEMANTICS

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- The specification I is the intended s-semantics of P
- The actual semantics $\llbracket P \rrbracket$ is the semantics $\mathcal{O}\llbracket P \rrbracket = F\llbracket P \rrbracket = T_p \uparrow \omega$
- The two definition styles (bottom-up and top-down) of the s-semantics and its properties are relevant to diagnosis
 - The theory of diagnosis is based on the bottom-up characterization
 - The equivalent top-down characterization allows us to implement the diagnosis by means of simple meta-interpreters
 - The condensing property allows us to consider goal-independent specifications
 - if P is correct and complete w.r.t. the goal-independent specification I then it behaves correctly for all the goals
- The above properties hold for the abstractions of the s-semantics we will consider in abstract diagnosis
- our version of the s-semantics
 - wLP style, with equations on the abstract domain as constraints

A COLLECTING S-SEMANTICS FOR

CLP($H, =$)

⑥

- program representation (for the sake of simplicity)
pure atoms + constraints

example

$$p(s(x), y, [x|z]) :- q(x, s(w)), p(w, s(y), z)$$

is represented as

$$p(x, y, z) :- x = s(x_1), z = [x_1|z_1], w = s(w_1), y_1 = s(y) \\ q(x, w), p(w_1, y_1, z_1).$$

- constraints = sets of equations

E set of equations

$\text{soln}(E)$ set of solutions of E

(a solution is a grounding substitution σ such that all the equations in $E\sigma$ are identities)

E_1, E_2 sets of equations

$E_1 \preceq E_2$ iff $\text{soln}(E_1) \subseteq \text{soln}(E_2)$

\mathcal{E}

the set of all sets of equations
(modulo equivalence)

THE SEMANTIC DOMAIN

(7)

- the semantics maps each goal G to an element of $\mathcal{P}(\mathcal{E})$ (the set of answer constraints)
- partial order on $\mathcal{P}(\mathcal{E})$

$\mathcal{E}_1, \mathcal{E}_2$ elements of $\mathcal{P}(\mathcal{E})$

$\mathcal{E}_1 \sqsubseteq \mathcal{E}_2$ iff for each element $E \in \mathcal{E}_1$, there exists $E' \in \mathcal{E}_2$, such that $E \leq E'$

- $(\mathcal{P}(\mathcal{E}), \sqsubseteq)$ is a complete lattice

- top element: \mathcal{E}
- bottom element: \emptyset
- least upper bound lub: set union
- greatest lower bound glb

$$\text{glb}(\{E_1, E_2, \dots\}, \{E_1', E_2', \dots\}) = \{E_1 \cup E_1', E_1 \cup E_2', \dots, E_2 \cup E_2', \dots\}$$

- $E_1 \cup E_2$ corresponds to unification and is transformation to solved form
 - satisfiability check
 - "normal form" for the equivalence class

INTERPRETATIONS

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- partial functions from most general atomic goals to elements of $\mathcal{P}(E)$
- partial order on interpretations

I_1, I_2 interpretations $(\in \mathcal{Y})$

$I_1 \leq I_2$ iff, for any most general atomic goal A ,
 $I_1(A) \subseteq I_2(A)$

- (\mathcal{Y}, \leq) is a complete lattice

THE BOTTOM-UP CONSTRUCTION OF THE S-SEMANTICS

9.9

• the immediate consequences operator

∀ most general atom $p(x_1, \dots, x_m)$

$$T_p(I)(p(x_1, \dots, x_m)) = \text{lub}(\{\varepsilon\})$$

$$p(x_1, \dots, x_m) :- e_1, \dots, e_k \square q_1(x_1^1, \dots, x_{m_1}^1), \dots, q_m(x_1^m, \dots, x_{m_m}^m)$$

renamed clause of P

$$I(q_1(x_1^1, \dots, x_{m_1}^1)) = \varepsilon_1,$$

⋮

$$I(q_m(x_1^m, \dots, x_{m_m}^m)) = \varepsilon_m,$$

$$E = \{e_1, \dots, e_k\},$$

$$\varepsilon = \text{glb}(\{\{E\}, \varepsilon_1, \dots, \varepsilon_k\} \mid x_1, \dots, x_m \})$$

• the S-semantic is the interpretation

$$F[[P]] = T_p \uparrow \omega$$

DIAGNOSIS W.R.T. COMPUTED ANSWERS

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P definite logic program
F[[P]] = $T_P \uparrow \omega$ actual S-semantics of P
S intended semantics of P

- P is partially correct w.r.t. S

$$F[[P]] \subseteq S$$

- P is complete w.r.t. S

$$S \subseteq F[[P]]$$

- termination issues are not addressed
 - the C-semantics is too abstract

- observation

$P(x_1, \dots, x_n)$
E

most general atom

set of equations (one answer constraint)

an observation is a partial function \mathcal{O} which maps $P(x_1, \dots, x_n)$ onto $\{E\}$

- observations are interpretations

- an observation \mathcal{O} is an incompleteness symptom

$$\mathcal{O} \subseteq F[[P]] \quad \text{and} \quad \mathcal{O} \neq S$$

an answer constraint computed by P not in the specification

- an observation \mathcal{O} is an incompleteness symptom

$$\mathcal{O} = S \quad \text{and} \quad \mathcal{O} \neq F[[P]]$$

an answer constraint in the specification which is not computed by P

SYMPTOMS AND ERRORS

- Some symptoms are not actual "bugs"
they are just consequences of other "basic symptoms"

P $q(x) := \neg p(x)$

$$S(p(x)) = \{ \{x=a\} \}$$

$$S(q(x)) = \{ \{x=a\} \}$$

$$F[[P]](p(x)) = \phi$$

$$F[[P]](q(x)) = \phi$$

$\mathcal{O}_2(p(x)) = \{ \{x=a\} \}$ and $\mathcal{O}_2(q(x)) = \{ \{x=a\} \}$
are both incompleteness symptoms, but \mathcal{O}_2 is just a
consequence of \mathcal{O}_2

- some bugs cannot be detected by looking at the symptoms
 - an invariant may be broken by an incompleteness and
vice versa

P $q(x) := \neg p(x)$
 $p(x) := \neg x=b$

$$S(q(x)) = \{ \{x=b\} \}$$

$$F[[P]](p(x)) = \{ \{x=b\} \}$$

$$F[[P]](q(x)) = \{ \{x=b\} \}$$

- there exists only one invariant symptom

$$\mathcal{O}_2(p(x)) = \{ \{x=b\} \}$$

- if we fix this bug (by removing the second clause), we get
an incompleteness symptom, since $F[[P]](q(x)) = \phi$

- symptom detection requires a fixpoint computation

INCORRECT CLAUSES AND UNCOVERED OBSERVATIONS

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- the problems with symptoms can be solved by basing the diagnosis on the detection of
 - incorrect clauses
 - uncovered observations
 - detects basic and hidden bugs
 - requires one application of T_P rather than a fixpoint computation
 - symptoms can be ignored

incorrect clause

The clause $c \in P$ is incorrect on the observation σ if

$$\sigma \not\models S \text{ and } \sigma \models T_{\{c\}}(S)$$

(the clause c derives a wrong answer constraint from the specification)

uncovered observation

The observation σ is uncovered if

$$\sigma \models S \text{ and } \sigma \not\models T_P(S)$$

(there are no clauses in P which can derive σ from the specification)

- we will show that the diagnosis can be based on the detection of incorrect clauses and uncovered observations

DIAGNOSIS OF CORRECTNESS : THEOREMS

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Theorem 1

if there are no incorrect clauses, then the program is partially correct

- if there are no incorrect clauses, $T_p(S) \subseteq S$
- S is a pre-fixpoint of T_p
- $F[[P]]$ is the least pre-fixpoint of $T_p \rightarrow F[[P]] \subseteq S$

(if the program is not partially correct, then there exists an incorrect clause)

Theorem 2

if the program is partially correct, then it is not always the case that there are no incorrect clauses

(an inconsistency may be hidden by an incompleteness)

Theorem 3

if the program is complete, then

if there exists an incorrect clause on \mathcal{Q} , then \mathcal{Q} is an inconsistency symptom

- incorrect clauses are more meaningful than inconsistency symptoms
- absence of incorrect clauses implies partial correctness
- an incorrect clause always corresponds to a bug, while this is not the case for symptoms

DIAGNOSIS OF COMPLETENESS

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- cannot in general be based on the detection of uncovered observations

Theorem

There exist a program P and a specification S , such that

- There are no uncovered observations
- P is not complete w.r.t. S

$$P \quad \boxed{p(x) := \neg p(x).}$$

$$S(p(x)) = \{\text{true}\}$$

$$F[[P]](p(x)) = \phi$$

$$T_P(S)(p(x)) = \{\text{true}\}$$

- S is a fixpoint of T_P different from the least fixpoint $F[[P]]$

- clearly related to loops

- a theorem similar to theorem 1 holds, if we assume T_P to have a unique fixpoint

DIAGNOSIS OF COMPLETENESS:

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THEOREMS

Theorem 4

if T_P has a unique fixpoint and there are no uncovered observations, then the program is complete

(if T_P has a unique fixpoint and P is not complete, then there exists an uncovered observation)

Theorem 5

if the program is complete, then it is not always the case that there are no uncovered observations

(an incompleteness may be hidden by an incorrectness)

Theorem 6

if the program is partially correct, then

if there exists an uncovered observation σ , then σ is an incompleteness symptom

- uncovered observations are more meaningful than incompleteness symptoms
- absence of uncovered observations implies completeness (if T_P has one fixpoint only)
- an uncovered observation always corresponds to a bug, while this is not the case for incompleteness symptoms!

T_P HAS ONE FIXPOINT ONLY, IF
 P IS AN ACCEPTABLE PROGRAM

(16)

acceptable programs were introduced to study the termination of pure PROLOG programs (Apt-Redieschi, 93)

- they are exactly the left-terminating programs (all the LD-derivations for ground goals are finite)
- acceptability is undecidable, but all sensible programs turn out to be acceptable
 - all the pure PROLOG programs in the Straling & Shapiro's book are acceptable
 - most wrong versions of sensible programs are acceptable (unless the bugs are just related to termination)
- the ground immediate consequence operator has one fixpoint only
- we have proved that the same result holds for the \subseteq semantics T_P

AN EXAMPLE

P

$ancestor(x, y) :- parent(z, y), ancestor(x, z).$
 $ancestor(x, y) :- parent(y, x).$
.... missing data base tuples

$$S(parent(x, y)) = \{ \{x=isaac, y=abraham\}, \{x=abraham, y=isaac\} \}$$

$$S(ancestor(x, y)) = \{ \{x=isaac, y=abraham\}, \{x=abraham, y=isaac\}, \{x=isaac, y=isaac\} \}$$

$$F[P](parent(x, y)) = \phi$$

$$F[P](ancestor(x, y)) = \phi$$

$$T_P(S)(parent(x, y)) = \phi$$

$$T_P(S)(ancestor(x, y)) = \{ \{x=abraham, y=isaac\}, \{x=isaac, y=abraham\}, \{x=isaac, y=isaac\} \}$$

• The second clause is incorrect on the observations

$$\begin{aligned} \mathcal{O}_1(ancestor(x, y)) &= \{ \{x=isaac, y=abraham\} \} \\ \mathcal{O}_2(ancestor(x, y)) &= \{ \{x=abraham, y=isaac\} \} \end{aligned}$$

• The uncovered observations are

$$\begin{aligned} \mathcal{O}_3(parent(x, y)) &= \{ \{x=isaac, y=abraham\} \} \\ \mathcal{O}_4(parent(x, y)) &= \{ \{x=abraham, y=isaac\} \} \\ \mathcal{O}_5(ancestor(x, y)) &= \{ \{x=isaac, y=abraham\} \} \\ \mathcal{O}_6(ancestor(x, y)) &= \{ \{x=abraham, y=isaac\} \} \end{aligned}$$

• There are no incompleteness symptoms, even if there is a wrong clause

• $\mathcal{O}_2(ancestor(x, y)) = \{ \{x=isaac, y=isaac\} \}$ is not uncovered, even if it is an incompleteness symptom

A MORE SYMMETRIC FORMULATION OF DIAGNOSIS

(7.1)

- proposed by (Fensel 1983) for diagnostic diagnosis
- extends to abstract diagnosis

- the specification is a pair (S^+, S^-)

- S^+ intended s-semantics ($\text{lfp}(T_P^S)$)
- S^- intended gfp(T_P^S)

- a new definition of completeness

P is complete w.r.t. (S^+, S^-) if
 $S^- \subseteq \text{gfp}(T_P^S)$

- the new definition of uncovered observation (conor)

the observation σ is uncovered if ...

$$\sigma \leq S^- \text{ and } \sigma \notin T_P^S(S^-)$$

- the completeness theorem

if there are no uncovered observations, then the program is complete

- no need for the unique fixpoint assumption

reduces to the standard definition under the unique fixpoint assumption

- requires a more complex specification

ORACLE-BASED TOP-DOWN DIAGNOSIS

(18)

Bottom-up diagnosis

- comparison between S and $Tp(S)$
- S must be specified in advance

top-down diagnosis

- S can be implemented by an oracle (querying the user)

$$\mathcal{R}(p(x_1, \dots, x_n)) = \{E \mid E \text{ is an intended answer constraint of } ?-p(x_1, \dots, x_n)\}$$

- the diagnosis is expressed in terms of oracle simulation
 - one resolution step with program clauses
 - answers for the remaining goals from the oracle

THE BOTTOM-UP CONSTRUCTION OF THE
S-SEMANTICS

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ORACLE SIMULATION

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• the immediate consequences operator

\mathcal{I}_p

resolution in \mathcal{P} {

answers from the oracle { \mathcal{A}
 \mathcal{A}

composition of answer constraints {

• the S-semantics is the interpretation

$$F[\mathcal{P}] = T_p \uparrow \omega$$

$$\mathcal{I}_p = T_p(\mathcal{A}) = T_p(S)$$

TOP-DOWN DIAGNOSIS : THEOREMS

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Theorem

The clause c is incorrect on the observation \mathcal{O} iff

$$\mathcal{O} \in \mathcal{I}_{\{c\}} \quad \text{and} \quad \mathcal{O} \notin \mathcal{R}$$

Theorem

The observation \mathcal{O} is uncovered iff

$$\mathcal{O} \in \mathcal{R} \quad \text{and} \quad \mathcal{O} \notin \mathcal{I}_P$$

- can be implemented as metainterpreters
 - one oracle only
 - no need to start from symptoms
 - we only need to start from (finitely many) most general atomic goals
 - more efficient interaction with the user is possible
 - oracles for conjunctive "instantiated" goals

EFFECTIVITY

(2)

- the diagnosis is not effective, unless the intended S -semantics S is finite
 - the bottom-up diagnosis is impossible, if S is infinite
 - in the top-down diagnosis, the oracle may return infinitely many answers to some queries
- we need finite approximations
 - partial specifications [Comini, Leni & Vitiello, IJPS 95]
 - widening techniques
 - finite abstract domains

ABSTRACT DIAGNOSIS

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• The property we consider

- in the specification S_{α}
- in the actual semantics of Δ

is an observable d

• any abstraction of SLD-trees

• abstract diagnosis is based on a semantic framework where observables (and the corresponding semantics) are related (and formally derived) using abstract interpretation theory [Comini, Levi 1995, Comini, Levi & Heo 1995]

• a taxonomy of observables

- each class has suitable precision and conformance properties

• the kernel semantics collects SLD-trees

- here we will take the (most abstract) S-semantics as collecting semantics

OBSERVABLES AND DIAGNOSIS

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- the observable α is a Galois insertion between $\mathcal{P}(\mathcal{E})$ and an abstract domain (D, \leq)
- the observable must have a correct abstract immediate consequences operator T_p^α , whose least fixpoint is the abstract semantics $F_\alpha[[P]]$
 - the theory of diagnosis is based on the fixpoint semantics
- the observable must be condensing, i.e. the abstract behavior for any goal G must be uniquely determined by the goal goal-independent observation $\alpha(F[[P]])$
 - if this is not the case, we cannot specify the goal-independent behavior only
- there exist two classes of observables for which the above properties hold
 - precise observables, for which $\alpha(F[[P]]) = F_\alpha[[P]]$
 - all the results of diagnosis w.r.t. computed answers hold
 - useful to reconstruct declarative diagnosis, where specifications can still be infinite

- approximate observables, for which $\alpha(F[[P]]) \leq F_\alpha[[P]]$
 - includes finite domains, such as $\text{depth}(K)$, POS (groundness) and various modes and types domains

FROM THE S-SEMANTICS TO THE ABSTRACT SEMANTICS

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- an abstract domain (D_α, \leq_α) complete lattice
- a Galois insertion (α, γ) between $(\mathcal{P}(E), \leq)$ and (D_α, \leq_α) satisfying the axioms of **approximate denotables**

9.1

- the abstract immediate congruence operator T_p^α

\forall most general atom $p(x_1, \dots, x_m)$

$$T_p^\alpha(I)(p(x_1, \dots, x_m)) =$$

$$\text{lub}_\alpha(\{\varepsilon\})$$

$$p(x_1, \dots, x_m) := e_1, \dots, e_k \square q_1(x_1^1, \dots, x_{n_1}^1), \dots, q_m(x_1^m, \dots, x_{n_m}^m)$$

k named atoms of P

$$I(q_1(x_1^1, \dots, x_{n_1}^1)) = \varepsilon_1,$$

⋮

$$I(q_m(x_1^m, \dots, x_{n_m}^m)) = \varepsilon_m,$$

$$E = \{\{e_1, \dots, e_k\}\}$$

$$\varepsilon = \text{glb}_\alpha(\{\{E\}, \varepsilon_1, \dots, \varepsilon_m\} \mid x_1, \dots, x_m \}$$

- the abstract semantics $F_\alpha[P] = T_p^\alpha \uparrow \omega$ satisfies

$$d(F[P]) \leq F_\alpha[P]$$

- can be also computed as standard semantics of the "abstract program" (Grioban, Achray & Levi, JLP 94)

OBSERVABLES

approximate observable
definite logic program
abstract semantics of P

abstraction of the semantics of P
intended abstract behavior of P

D_α

$$F_\alpha[P] = T_{P^\alpha} \uparrow \omega$$

$$\alpha(F[P]) = \alpha(T_P \uparrow \omega) \in F_\alpha[P]$$

S_α

- P is partially correct w.r.t. S_α

$$\alpha(F[P]) \leq_\alpha S_\alpha$$

- P is complete w.r.t. S_α

$$S_\alpha \leq_\alpha \alpha(F[P])$$

- incorrect clause

The clause $c \in P$ is incorrect on the (abstract) observation \mathcal{Q} if

$$\mathcal{Q} \not\leq_\alpha S_\alpha \text{ and } \mathcal{Q} \leq_\alpha T_{\{c\}}^\alpha(S_\alpha)$$

(c derives a wrong abstract constraint from the specification)

- uncovered observation

The (abstract) observation \mathcal{Q} is uncovered if

$$\mathcal{Q} \leq_\alpha S_\alpha \text{ and } \mathcal{Q} \not\leq_\alpha T_P^\alpha(S_\alpha)$$

(no clause in P derives \mathcal{Q} from the specification)

THE DIAGNOSIS THEOREMS

(26)

Theorem 1

if there are no incorrect clauses, then the program is partially correct

- if there are no incorrect clauses, $T_P^d(S_d) \subseteq S_d$
- S_d is a prefixpoint of T_P^d
- $FA[P] \subseteq_d S_d \rightarrow a(F[P]) \subseteq_d S_d$

• Theorem 3 does not hold for approximate observables

if the program is complete, then

if there exists an incorrect clause on \mathcal{Q} , then

\mathcal{Q} is not always an incorrectness symptom

- the incorrectness might be generated by the approximation of the abstract semantics

• Theorem 4 does not hold for approximate observables

absence of uncovered observations, even under the unique fixpoint assumption, does not imply program completeness

- incompleteness bugs might be hidden by the approximation of the abstract semantics

Theorem 6

if the program is partially correct, then

if there exists an uncovered observation \mathcal{Q} , then

\mathcal{Q} is an incompleteness symptom

• weaker results

- absence of incorrect clauses implies partial correctness
- uncovered observations correspond to bugs
- equivalent top-down characterization

AN APPROXIMATE OBSERVABLE:
DEPTH (κ)

• the abstract domain of the observable τ_κ

• the concrete domain, where

an equation $x = E$ is replaced by

an equation $x = E'$

every subterm of τ at depth $\geq \kappa$ is replaced by a fresh variable

• the abstract immediate consequences operator

$$T_P^{\tau_\kappa}(\mathcal{I})(P(x_1, \dots, x_n)) = \bigcup \{ \mathcal{E} \mid$$

$P(x_1, \dots, x_n) :- e_1, \dots, e_k \sqcup g_1(x_1', \dots, x_{n_1}') \wedge \dots \wedge g_m(x_{n_1}^m, \dots, x_{n_m}^m)$
is a minimal clause of P

$$\mathcal{I}(g_1(x_1', \dots, x_{n_1}')) = \mathcal{E}_1,$$

$$\mathcal{I}(g_m(x_1^m, \dots, x_{n_m}^m)) = \mathcal{E}_m,$$

$$\mathcal{E} = \tau_\kappa \left(\text{glb} \left(\left\{ \tau_\kappa(\{e_1, \dots, e_k\}) \right\}, \mathcal{E}_1, \dots, \mathcal{E}_m \right) \right) \upharpoonright_{x_1, \dots, x_n}$$

glb is the one of the concrete domain

• τ_κ is an approximate observable \rightarrow

• it is soundness

$$\tau_\kappa(F[[P]]) \subseteq T_P^{\tau_\kappa} \uparrow \omega = F_{\tau_\kappa}[[P]]$$

AN EXAMPLE WITH DEPTH(K) - ANSWERS

27.1

P

$\text{accept}([a|x]) :- \text{acc}(x).$
 $\text{accept}([]).$
 $\text{acc}([b|x]) :- \text{accept}(x).$

- wrong version (missing clause) of an automaton which recognizes the language $L = \{(ab)^n \mid n \geq 0\} \cup \{(ab)^n a \mid n \geq 0\}$
- the specification of the intended depth(2)-answers

$$S(\text{accept}(x)) = \{ \{x = []\}, \{x = [a]\}, \{x = [a, b]\}, \{x = [a, b | Y]\} \}$$

$$S(\text{acc}(x)) = \{ \{x = []\}, \{x = [a]\}, \{x = [a, a]\}, \{x = [b, a | Y]\} \}$$

- by applying the $T_P^{\uparrow 2}$ operator we find out that

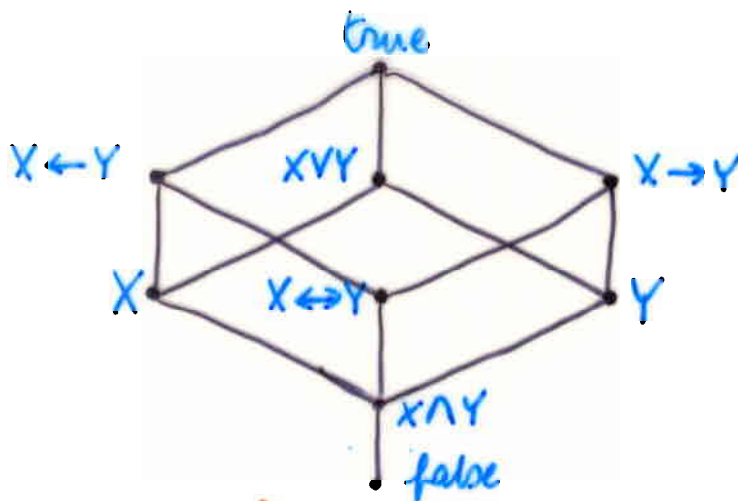
- P is partially correct w.r.t. S
- There exists an uncovered element

$$\text{acc}(x) \mapsto \{x = []\}$$

which shows that there is a missing clause for acc

ANSI APPROXIMATE OBSERVABLE: REPRESENTING GROUNDNESS BY POS

- The abstract domain (POS, \leq_{POS}) [propositional formulas] (shown for two variables)



$$\alpha_{POS} : \mathcal{P}(E) \rightarrow POS$$

$$\gamma_{POS} : POS \rightarrow \mathcal{P}(E)$$

$$false \rightarrow \emptyset$$

(no values)

$$true \rightarrow E$$

(no groundness information)

$$X \rightarrow \{E \mid \exists t \text{ ground}, X=t \in E\}$$

(X is ground)

$$X \wedge Y \rightarrow \{E \mid \exists t_1, t_2 \text{ ground}, \{X=t_1, Y=t_2\} \subseteq E\}$$

(both X and Y are ground)

$$X \vee Y \rightarrow \{E \mid \exists t \text{ ground}, X=t \in E \text{ or } Y=t \in E\}$$

(either X or Y is ground)

$$X \rightarrow Y \rightarrow \{E \mid \exists t, Y \text{ occurs in } t, X=t \in E\}$$

(if X is ground, then Y is ground)

$$X \leftrightarrow Y \rightarrow \{E \mid \exists t, Y \text{ is the only variable in } t, X=t \in E\}$$

(X is ground iff Y is ground)

- (POS, \leq_{POS}) is an approximate observable

OPERATOR

\forall most general atom $p(x_1, \dots, x_n)$

$$T_P^{POS}(\mathcal{I})(p(x_1, \dots, x_n)) =$$

$$\text{lub}^{POS}(\{ \varepsilon \mid$$

$$p(x_1, \dots, x_n) :- e_1, \dots, e_k \square q_1(x_1^1, \dots, x_{n_1}^1), \dots, q_m(x_1^m, \dots, x_{n_m}^m)$$

(renamed clause of P)

$$\mathcal{I}(q_1(x_1^1, \dots, x_{n_1}^1)) = \varepsilon_1,$$

$$\vdots$$

$$\mathcal{I}(q_m(x_1^m, \dots, x_{n_m}^m)) = \varepsilon_m,$$

$$\varepsilon = \text{glb}^{POS}(\{ \text{dpos}(\{ e_1, \dots, e_k \}), \varepsilon_1, \dots, \varepsilon_m \} \uparrow_{x_1, \dots, x_n}^{POS})$$

• this is the only occurrence of "concrete constraints" in the definition

• it can be eliminated by considering the abstract program, where, in each clause,

$$e_1, \dots, e_k \quad \text{is replaced by} \quad \text{dpos}(\{ e_1, \dots, e_k \})$$

• since POS is an approximate observable, we know that it is condensing

$$\text{dpos}(F_{\#}[P]) \leq_{POS} T_P^{POS} \uparrow W = F_{POS}[P]$$

ABSTRACT DIA GNOSIS:

EXAMPLE 2

$p(x) :- x = f(y) \square q(y).$
 $q(x) :- x = a.$
 $r(x) :- y = g(x) \square p(y).$
 $s(x, y) :- r(x).$
 $s(x, y) :- y = a.$

$F[P](p(x)) = \{ \{ x = f(a) \} \}$
 $F[P](q(x)) = \{ \{ x = a \} \}$
 $F[P](r(x)) = \emptyset$
 $F[P](s(x, y)) = \{ \{ y = a \} \}$

$\alpha_{pos}(F[P])(p(x)) = X$
 $\alpha_{pos}(F[P])(q(x)) = X$
 $\alpha_{pos}(F[P])(r(x)) = false$
 $\alpha_{pos}(F[P])(s(x, y)) = Y$

$F_{pos}[P](p(x)) = X$
 $F_{pos}[P](q(x)) = X$
 $F_{pos}[P](r(x)) = X$
 $F_{pos}[P](s(x, y)) = X \vee Y$

• The abstract summary is not precise, i.e. $F_{pos}[P] \neq \alpha_{pos}(F[P])$

ABSTRACT DIAGNOSIS:

EXAMPLE 2

$p(x) :- x = f(y) \square q(y).$
 $q(x) :- x = a.$
 $r(x) :- y = g(x) \square p(y).$
 $s(x, y) :- r(x).$
 $s(x, y) :- y = a.$

$F[P](p(x)) = \{ \{ x = f(a) \} \}$
 $F[P](q(x)) = \{ \{ x = a \} \}$
 $F[P](r(x)) = \emptyset$
 $F[P](s(x, y)) = \{ \{ y = a \} \}$

$\alpha_{pos}(F[P])(p(x)) = X$
 $\alpha_{pos}(F[P])(q(x)) = X$
 $\alpha_{pos}(F[P])(r(x)) = false$
 $\alpha_{pos}(F[P])(s(x, y)) = Y$

$F_{pos}[P](p(x)) = X$
 $F_{pos}[P](q(x)) = X$
 $F_{pos}[P](r(x)) = X$
 $F_{pos}[P](s(x, y)) = X \vee Y$

• The abstract semantics is not precise, i.e. $F_{pos}[P] \neq \alpha_{pos}(F[P])$

$S_{pos}(p(x)) = X$
 $S_{pos}(q(x)) = X$
 $S_{pos}(r(x)) = false$
 $S_{pos}(s(x, y)) = Y$

$T_p^{pos}(S_{pos})(p(x)) = X$
 $T_p^{pos}(S_{pos})(q(x)) = X$
 $T_p^{pos}(S_{pos})(r(x)) = X$
 $T_p^{pos}(S_{pos})(s(x, y)) = Y$

- P is partially correct and complete
- however, the third clause is incorrect on $\mathcal{Q}_2(H(x)) = X$ (because of the approximation in the abstract T_p)

DIAGNOSIS AND VERIFICATION OF PARTIAL CORRECTNESS

- a specification like

$$S(+ (x, y, z)) = x \wedge y \wedge z$$

reads as

"every successful computation of $?-+(x, y, z)$ binds $x, y,$ and z to ground terms"

- it looks like an assertion (postcondition)
- diagnosis can be compared to techniques for verifying partial correctness

(Apr 83, 84, 86)

WHAT IS AN ASSERTION?

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verification

- an intensional set of concrete atoms

- closed under instantiation

- the intensional definition is given in terms of concepts (being a list, being ground, ...)

which have to be defined elsewhere (e.g. the theory of "groundness")

$$\{+(x, y, z) \mid x \text{ is ground} \wedge y \text{ is ground} \wedge z \text{ is ground}\}$$

- infinitely many concrete atoms

diagnosis

- an extensional set of abstract atoms

$$\{+(x, y, z) :- x \wedge y \wedge z\}$$

- one abstract atom

- the constraint on being closed under instantiation rules out some interesting properties (e.g. computed answers, freeness, ...)

- in the case of precise observables (e.g. correct answers) intensional equations can lead to finite equations, but

"no additional concepts, apart from the abstract observables, are needed in abstract diagnosis"

WHAT IS A SPECIFICATION?

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• verification

- 2 pair of assertions
 - precondition and postcondition
 - the precondition specifies the class of goals we are interested in

• disproof

- one assertion
 - postcondition only
 - "pre-independent" verification, or verification for "most general atomic power"

WHAT IS PARTIAL CORRECTNESS?

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verification

- There exist two different formulations
 - The first one corresponds to our notion of partial correctness
(\approx the actual execution is included in the specification)
 - The second one ^(strongest postcondition) corresponds to our notion of partial correctness and completeness
(\approx the actual execution is the same as the specification)

Verification

- The definition of well-entailed (goal and) programs w.r.t. a specification
 - a simple inductive definition which generates a set of formulas which have to be proved in the theory which formalized the "external" concepts used in the operations

Disproofs

- The application of the abstract T_p to the specification
 - abstract computation instead of theorem proving.

HOW DO WE PROVE PARTIAL CORRECTNESS?

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• partial correctness 1

verification

- partial correctness is essentially proving the well-structuredness

diagnoses

- absence of incorrect clauses

• partial correctness 2 (= partial correctness + completeness)

verification

- requires the construction of a concrete semantics (least Herbrand model of a suitable program, obtained from P and the preconditions)

diagnosis

- absence of uncovered elements
 - if the observable is precise and the abstract T_p has one fixpoint only
 - if the observable is "precise for P " and the abstract T_p has one fixpoint only

WHAT IF THE PARTIAL CORRECTNESS PROOF FAILS?

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Verification

- no useful information

diagnosis

- uncovered elements always correspond to incompleteness bugs
- incorrect clauses correspond to inconsistency bugs, if the domain is precise

Verification

- the ability to handle specifications given in terms of pre- and post-conditions

Diagnosis

- generates information useful for debugging
- one step of abstract computation instead of theorem proving
- possibly better for proving completeness
- can use tools from abstract interpretation theory (domain composition, domain refinement) to improve the precision and the expressive power of specifications



extension of diagnosis to
handle pre and post-conditions

MODULAR DIAGNOSIS

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- the program is splitted into n

predicate - disjoint modules

- any predicate is fully defined by a single module
- it is not a hierarchical decomposition
(mutual recursion across modules is allowed)

- each module P_i has a specification I_{α}^i

- $use(P_i) = \{ I_{\alpha}^j \mid \text{the body of a clause in } P_i \text{ contains a predicate defined in module } P_j \}$

- two different (strongly related) techniques

1. (modular diagnosis)

- all the program components are known
- the diagnosis is performed component-wise

2. (modular development and diagnosis)

- we have one component only (and all the related specifications)
- we perform the diagnosis of a single module

MODULAR DIAGNOSIS AND COMPOSITIONALITY

- modular analysis is usually based on OR-compositional semantics
 - for example, [Codish, Debray, Giacobazzi, POPL 93] use the OR-compositional version of the S-semantics [Bossi, Cabbibelli, Leni, Meo, TCS 94]
- our semantics are not OR-compositional
- abstract diagnosis does not require to actually compute the abstract semantics
 - both top-down and bottom-up diagnosis just use the abstract immediate consequence operators TP^d , which are indeed OR-compositional.
- we do not need any modification in the basic framework

MODULAR DIAGONALIZATION

$$P = P^2 U \dots U P^m = P^m$$

$$I^a = I^a U \dots U I^a = I^a$$

$$I^a \geq \alpha(F \mathbb{F}^n)$$

$$I^a \geq \alpha(F \mathbb{F}^n)$$

completeness

completeness

m-invariant lattice

if α is m -invariant on the (split) element α of the class $\alpha \in P_i$ and $\alpha \neq 0$ then $\alpha \geq \alpha T^a (I^a U \text{vec}(P_i))$

m-invariant element

if α is m -invariant on the (split) element α and $\alpha \neq 0$ then $\alpha \geq \alpha T^a (I^a U \text{vec}(P_i))$

the units

- if there are no m -invariant classes, P is correct
- if P and α are correct, m -invariant classes are correct and multiplication of conditions
- if P is correct, m -invariant elements are correct and multiplication of conditions
- if α is correct and $\alpha \neq 0$ then $\alpha \geq \alpha T^a (I^a U \text{vec}(P_i))$, then if there are no m -invariant elements, P is correct

MODULAR DEVELOPMENT AND DIAGNOSIS

P_i
use(P_i)

• we want to perform the diagnosis of P_i under the assumption that all the other (possibly not yet implemented) modules are correct and complete (w.r.t. their specifications)

- we cannot construct the concrete semantics of P_i since the other components are unknown
- we can take as concrete semantics of the unknown modules the concretization of their abstract specifications

$$T_{P_i}^{I_\alpha} (I) = T_{P_i} (I \cup \gamma(\text{use}(P_i)))$$

$$F^{I_\alpha} [P_i] = T_{P_i}^{I_\alpha} \uparrow \omega$$

module correctness

$$d(F^{I_\alpha} [P_i]) \leq_{\alpha} I_\alpha^i$$

module completeness

$$I_\alpha^i \leq_{\alpha} d(F^{I_\alpha} [P_i])$$

• the results

$$P = P_1 \cup \dots \cup P_m$$

- if all the P_i 's are correct (complete), then P is correct (complete)
- if there are no m -incorrect classes in P_i , then P_i is m -correct
- if P_i and d are complete, then if there exists an m -incorrect class in P_i , P_i is not m -correct
- if P_i is correct, and there exists an m -uncovered element in P_i , P_i is not m -complete
- if d is complete (and ~~if~~ the suitable T_{P_i} 's have a unique fixpoint), then if there are no m -uncovered elements in P_i , P_i is m -complete