

Outline of the talk

1 Introduction

- P Systems
- Behavioral Equivalences for P Systems

2 The P Algebra

- Syntax
- Semantics
- Behavioral Preorders and Equivalences

3 The PP Algebra

- Few Words

4 Conclusions and Future Work

Introduction

P Systems are distributed parallel computing devices inspired by the structure and the functioning of living cells

Recently, some operational semantics of P Systems have been defined (e.g. by Ciobanu et Al., Busi, and Freund et Al.)

The aim of this work is to introduce *behavioral equivalences* for P Systems

- We introduce a process algebraic representation of P Systems
- We define a compositional semantics as a *Labeled Transition System (LTS)*
- We study well-known behavioral equivalences over LTSs on our semantics

P Systems

A *P System* Π is given by

$$\Pi = (V, \mu, w_1, \dots, w_n, (R_1, \rho_1), \dots, (R_n, \rho_n))$$

where:

- V is an *alphabet* whose elements are called *objects*;
- $\mu \subset \mathbb{N} \times \mathbb{N}$ is a *membrane structure*, such that $(i, j) \in \mu$ denotes that the membrane labeled by j is contained in the membrane labeled by i ;
- w_i with $1 \leq i \leq n$ are strings from V^* representing multisets over V associated with the membranes $1, 2, \dots, n$ of μ ;
- R_i with $1 \leq i \leq n$ are finite sets of *evolution rules* associated with the membranes $1, 2, \dots, n$ of μ ;
- ρ_i is a partial order relation over R_i , specifying a *priority* relation between rules: $(r_1, r_2) \in \rho_i$ iff $r_1 > r_2$ (i.e. r_1 has a higher priority than r_2).

Evolution Rules

The products of a rule are denoted with a multiset of *messages* of the following forms:

- $(v, here)$: objects v remain in the same membrane;
- (v, out) : objects v are sent out;
- (v, in_l) : objects v are sent into the child membrane l .

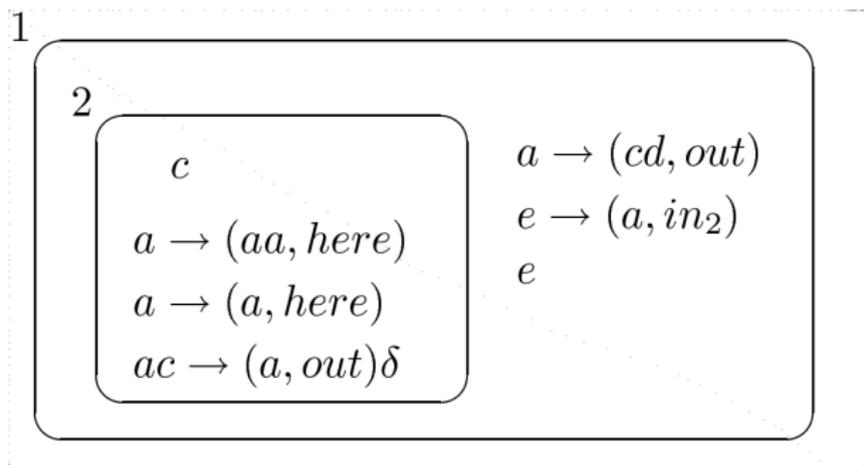
We can assume that all evolution rules have the following form, where $\{l_1, \dots, l_n\}$ is a set of membrane labels in \mathbb{N} .

$$u \rightarrow (v_h, here)(v_o, out)(v_1, in_{l_1}) \dots (v_n, in_{l_n})$$

A dissolving evolution rule is denoted by adding to the products the special message δ such that $\delta \notin V$:

$$u \rightarrow (v_h, here)(v_o, out)(v_1, in_{l_1}) \dots (v_n, in_{l_n})\delta$$

An Example



A P System that may send out of the skin membrane (if the computation terminates) a multiset of objects $c^n d^n$.

Maximal Parallelism

Evolution rules are applied with *maximal parallelism*:

*A **multiset of instances** of evolution rules is chosen non-deterministically such that **no other rule can be applied** to the system obtained by removing all the objects necessary to apply the chosen instances of rules.*

Priority relations between rules are such that:

*A rule with a priority smaller than another cannot be chosen for application if the one with greater priority **is applicable**.*

Observable Behavior

In order to define reasonable semantics and behavioral equivalences we have to characterize what is reasonable to observe of the behavior of a P System

- There are many choices...

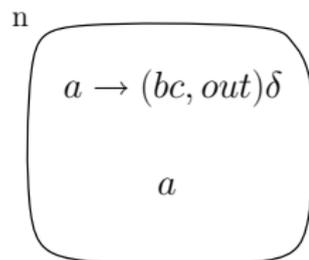
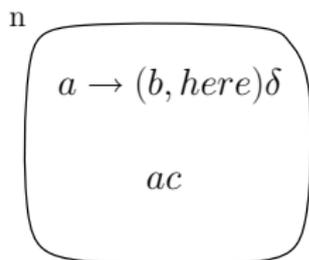
We choose to observe the input/output behavior of membranes:

Two membranes are equivalent if, at each step, they can:

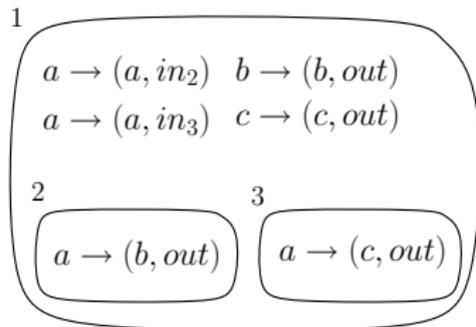
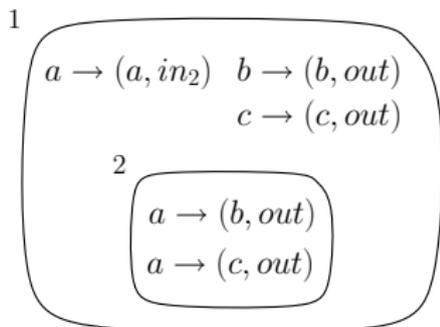
- *receive the same objects from outer and inner membranes*
- *send the same objects to the outer membrane (or to the external environment)*
- *send the same objects to the same inner membranes*

Examples of Equivalent Membranes

The following membranes could be considered as equivalent:



and also the following two:



Examples of Equivalent Membrane Contents

A *membrane content* is a pair (\mathcal{R}, u) where

- \mathcal{R} is a set of evolution rules
- u is a multiset of objects

that can be (a part of) the content of a membrane

These membrane contents should be considered pairwise equivalent:

$$(a \rightarrow (b, \textit{here})\delta, \emptyset) \quad \text{and} \quad (a \rightarrow (b, \textit{out})\delta, \emptyset)$$

$$(a \rightarrow (b, \textit{here})\delta, abc) \quad \text{and} \quad (a \rightarrow (b, \textit{out})\delta, abc)$$

$$(\mathcal{R}_1, \emptyset) \quad \text{and} \quad (\mathcal{R}_2, \emptyset)$$

$$\text{where } \mathcal{R}_1 = \{ a \rightarrow (b, \textit{here}) , a \rightarrow (c, \textit{here}) \} \text{ and} \\ \mathcal{R}_2 = \mathcal{R}_1 \cup \{ aa \rightarrow (bc, \textit{here}) \}.$$

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The P Algebra (for P Systems without Priorities)

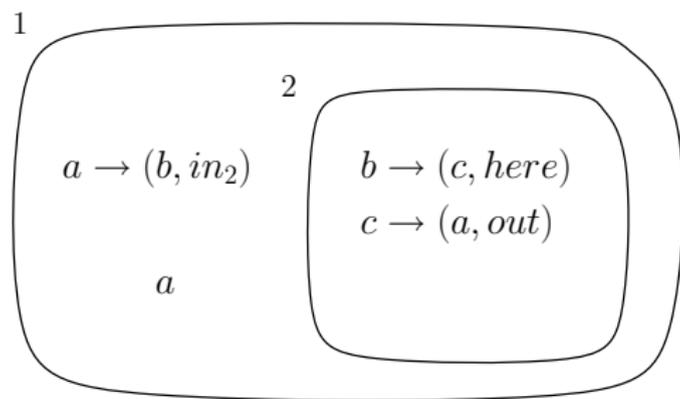
Def. (P Algebra) The syntax of *membrane contents* c , *membranes* m , and *membrane systems* ms is given by the following grammar:

$$\begin{aligned} c ::= & (\emptyset, \emptyset) \mid (u \rightarrow v_h v_o \{v_{l_i}\}, \emptyset) \mid (u \rightarrow v_h v_o \{v_{l_i}\} \delta, \emptyset) \mid (\emptyset, a) \mid c \cup c \\ m ::= & [l c]_l \qquad ms ::= m \mid ms \mid ms \mid \mu(m, ms) \mid \mathbf{v} \end{aligned}$$

where l and l_i range over \mathbb{N} and a ranges over V .

- $u \rightarrow v_h v_o \{v_{l_i}\}$ stands for $u \rightarrow (v_h, \text{here})(h_o, \text{out})(v_{l_1}, \text{in}_{l_1}) \dots (v_{l_n}, \text{in}_{l_n})$
- $c_1 \cup c_2$ denotes the membrane content obtained by merging the rules and the objects of c_1 and c_2
- $[l c]_l$ denotes a membrane whose content is c and whose label is l
- $ms | ms$ denotes *juxtaposition* of membranes
- $\mu(m, ms)$ denotes the containment of the membranes ms in m (hierarchical composition)
- \mathbf{v} represents the *dissolved* membrane

Example of Term of the P Algebra



corresponds to the term:

$$\mu\left([1 (a \rightarrow (b, in_2), \emptyset) \cup (\emptyset, a)]_1, [2 (b \rightarrow (c, here), \emptyset) \cup (c \rightarrow (a, out), \emptyset)]_2 \right)$$

that is (for short):

$$\mu\left([1 a \rightarrow (b, in_2), a]_1, [2 b \rightarrow (c, here), c \rightarrow (a, out)]_2 \right)$$

Semantics of the P Algebra

The semantics of the P Algebra is a Labeled Transition System (LTS)

- states are terms
- transitions are labeled by information about the input/output behavior of the system (observation)

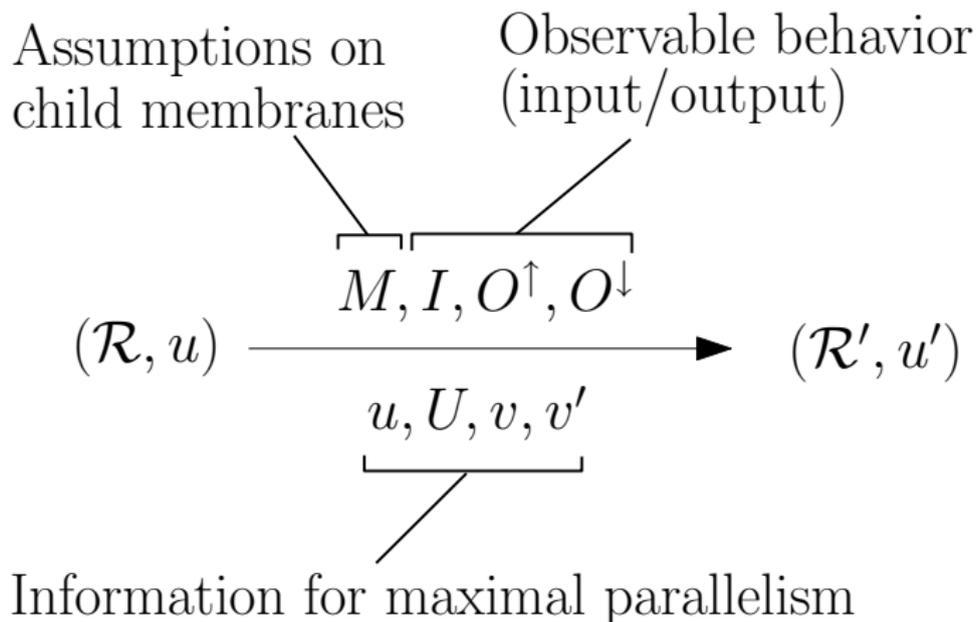
Let's start with membrane contents. We would like to

- define the behavior of individual evolution rules and objects
- infer the behavior of a membrane content from the behaviors of its rules and objects

Problem: it is hard to express the concept of maximal parallelism in a compositional way

Solution: we enrich transition labels with information concerning the (potential) application and non application of evolution rules

Transitions of Membrane Contents



Inference Rules for Membrane Contents

$$\frac{I \in V^*}{(\emptyset, \emptyset) \xrightarrow[\emptyset, \emptyset, \emptyset, \emptyset]{\emptyset, I, \emptyset, \emptyset} (\emptyset, I)} \quad (mc8)$$

$$\frac{I \in V^*}{(\emptyset, a) \xrightarrow[\emptyset, \emptyset, \emptyset, a]{\emptyset, I, \emptyset, \emptyset} (\emptyset, Ia)} \quad (mc7)$$

$$\frac{I \in V^*}{(\emptyset, a) \xrightarrow[\emptyset, \emptyset, a, \emptyset]{\emptyset, I, \emptyset, \emptyset} (\emptyset, I)} \quad (mc6)$$

$$\frac{I \in V^* \quad n \in \mathbb{N}}{(\emptyset, \emptyset) \xrightarrow[u^n, \{u\}, \emptyset, \emptyset]{\emptyset, I, v_o^n, \{(l_i, v_{l_i}^n)\}} (\emptyset, I v_h^n)} \quad (mc1_n)$$

Inference Rules for Membrane Contents (2)

$$\frac{I \in V^* \quad n \in \mathbb{N} \quad n > 0}{(u \rightarrow v_h v_o \{v_{l_i}\} \delta, \emptyset) \xrightarrow[u^n, \{u\}, \emptyset, \emptyset]{\emptyset, I, I v_o^n v_h^n \delta, \{(l_i, v_{l_i}^n)\}} \mathbf{v}} \quad (mc2_n)$$

$$\frac{I \in V^*}{(u \rightarrow v_h v_o \{v_{l_i}\} \delta, \emptyset) \xrightarrow[\emptyset, \{u\}, \emptyset, \emptyset]{\emptyset, I, \emptyset, \emptyset} (u \rightarrow v_h v_o \{v_{l_i}\} \delta, I)} \quad (mc3)$$

$$\frac{I \in V^* \quad M \subseteq \text{Labels}(\{v_{l_i}\}) \quad M \neq \emptyset}{(u \rightarrow v_h v_o \{v_{l_i}\}, \emptyset) \xrightarrow[\emptyset, \emptyset, \emptyset, \emptyset]{M, I, \emptyset, \emptyset} (u \rightarrow v_h v_o \{v_{l_i}\}, I)} \quad (mc4)$$

$$\frac{I \in V^* \quad M \subseteq \text{Labels}(\{v_{l_i}\}) \quad M \neq \emptyset}{(u \rightarrow v_h v_o \{v_{l_i}\} \delta, \emptyset) \xrightarrow[\emptyset, \emptyset, \emptyset, \emptyset]{M, I, \emptyset, \emptyset} (u \rightarrow v_h v_o \{v_{l_i}\} \delta, I)} \quad (mc5)$$

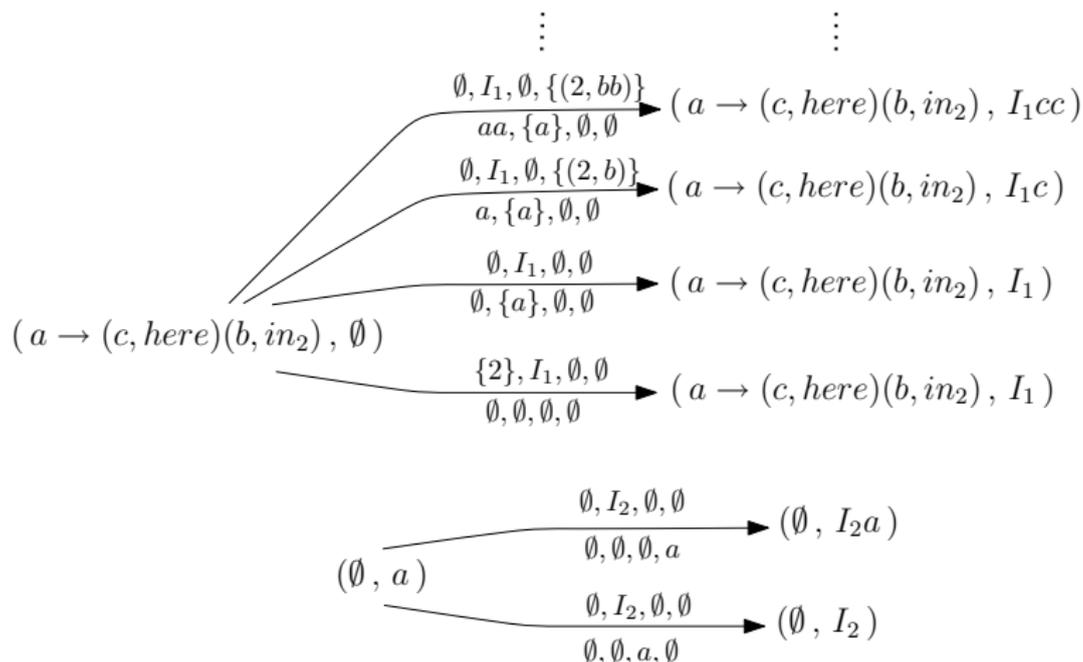
Inference Rules for Membrane Contents (3)

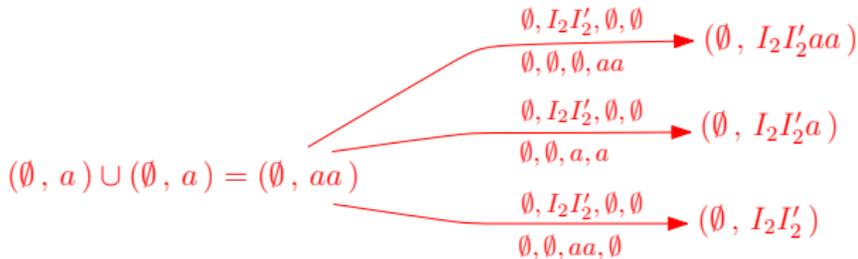
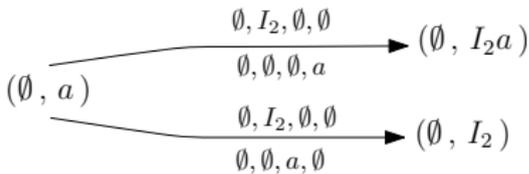
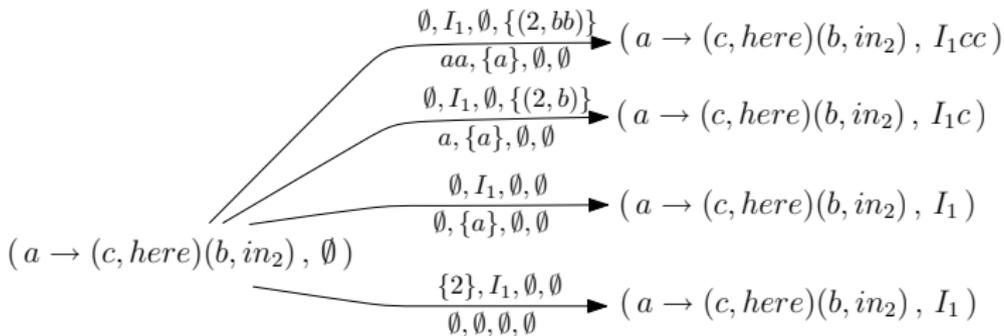
$$\frac{x_1 \xrightarrow[u_1, U_1, v_1, v'_1]{M_1, I_1, O_1^\uparrow, O_1^\downarrow} y_1 \quad x_2 \xrightarrow[u_2, U_2, v_2, v'_2]{M_2, I_2, O_2^\uparrow, O_2^\downarrow} y_2 \quad \begin{array}{l} M_1 M_2 \cap \text{Labels}(O_1^\downarrow \cup_{\mathbb{N}} O_2^\downarrow) = \emptyset \\ v'_1 v'_2 \not\subseteq U_1 \oplus U_2 \quad \delta \notin O_1^\uparrow O_2^\uparrow \end{array}}{x_1 \cup x_2 \xrightarrow[u_1 u_2, U_1 \oplus U_2, v_1 v_2, v'_1 v'_2]{M_1 M_2, I_1 I_2, O_1^\uparrow O_2^\uparrow, O_1^\downarrow \cup_{\mathbb{N}} O_2^\downarrow} y_1 \cup y_2}$$

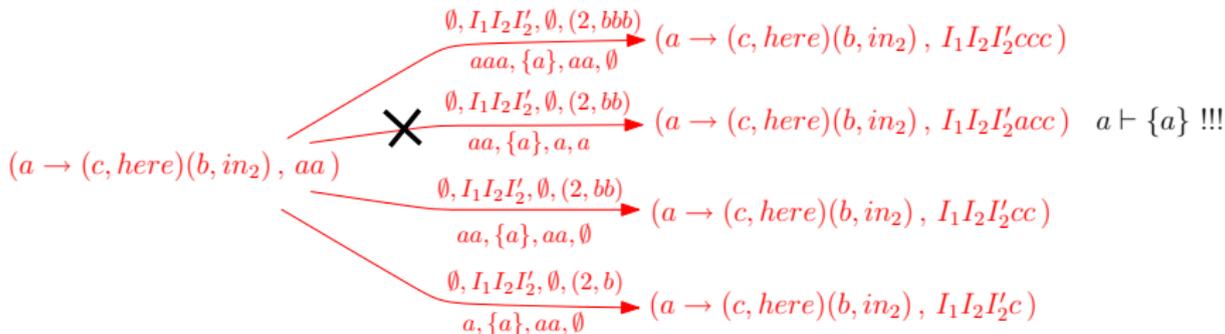
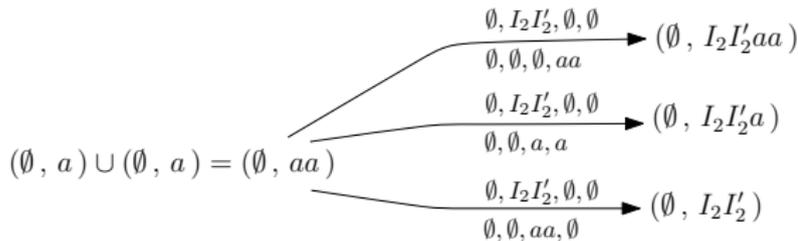
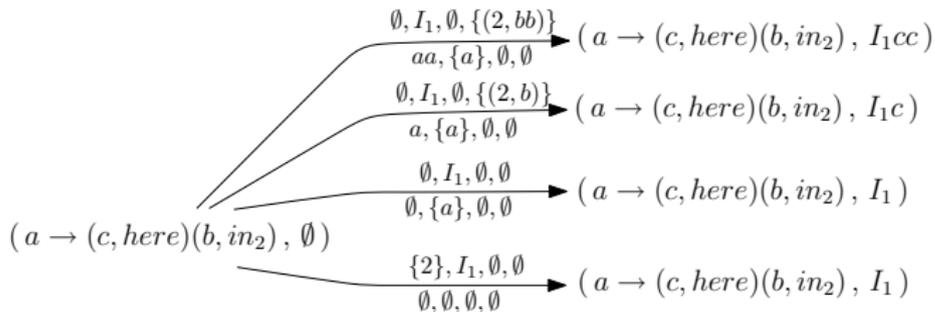
+ similar rules to handle dissolution of x_1 or/and x_2

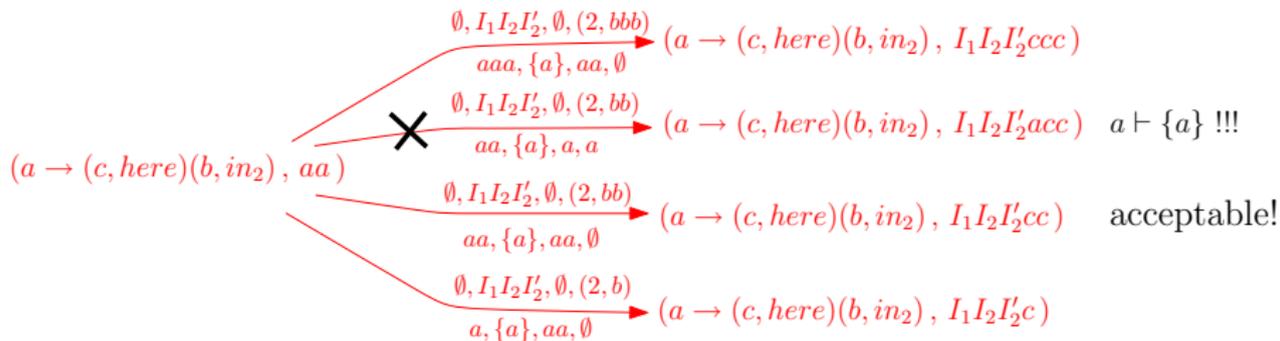
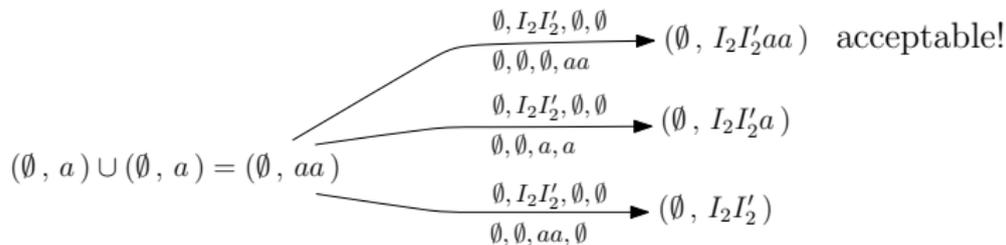
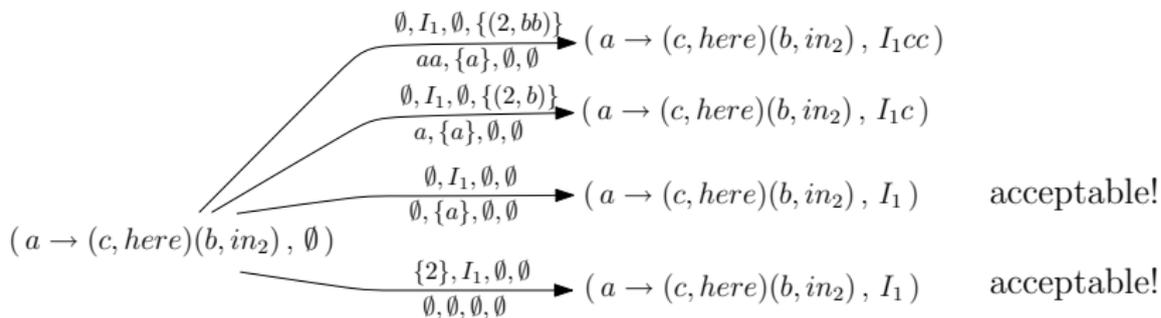
- $u_1 u_2$ is the union of multisets u_1 and u_2
- $v \vdash U$ means $\exists u. (u \subseteq v \wedge u \in U)$
- $\cup_{\mathbb{N}}$ groups objects sent to the same child membrane
- \oplus merges sets of multisets by removing redundant ones

Example of Semantics of Membrane Contents









Inference Rules for Membranes and Juxtapositions

$$\frac{x \xrightarrow[u, U, u, v']{M, I, O^\uparrow, O^\downarrow} y \quad \delta \notin O^\uparrow}{[lx]_l \xrightarrow{M, \{(l, I)\}, O^\uparrow, O^\downarrow} [ly]_l} \quad (m1)$$

$$\frac{x \xrightarrow[u, U, u, v']{M, I, O^\uparrow, O^\downarrow} y \quad \delta \in O^\uparrow}{[lx]_l \xrightarrow{M, \{(l, I)\}, O^\uparrow, O^\downarrow} \mathbf{v}} \quad (m2)$$

- information under the arrow is no longer necessary
- the transition from x to y must be *acceptable*
 - ▶ the first and the third label under the arrow are the same
 - ▶ this is important to ensure maximal parallelism

$$\frac{x_1 \xrightarrow{M_1, \mathcal{I}_1, O_1^\uparrow, \emptyset} y_1 \quad x_2 \xrightarrow{M_2, \mathcal{I}_2, O_2^\uparrow, \emptyset} y_2 \quad \delta \notin O_1^\uparrow O_2^\uparrow}{x_1 | x_2 \xrightarrow{\emptyset, \mathcal{I}_1 \mathcal{I}_2, O_1^\uparrow O_2^\uparrow, \emptyset} y_1 | y_2} \quad (jux1)$$

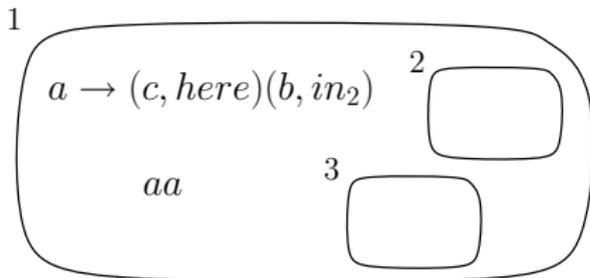
+ similar rules to handle dissolution of x_1 or/and x_2

Inference Rules for Hierarchical Compositions

$$\begin{array}{c} x_1 \xrightarrow{M_1, \{(l_1, I_1)\}, O_1^\uparrow, O_1^\downarrow} y_1 \quad x_2 \xrightarrow{M_2, \mathcal{I}_2, O_2^\uparrow, \emptyset} y_2 \\ \hline O_1^\downarrow \simeq \mathcal{I}_2 \quad O_2^\uparrow \subseteq I_1 \quad M_1 \cap \text{Labels}(\mathcal{I}_2) = \emptyset \quad \delta \notin O_1^\uparrow O_2^\uparrow \\ \mu(x_1, x_2) \xrightarrow{\emptyset, (l_1, I_1 \setminus O_2^\uparrow), O_1^\uparrow, \emptyset} \mu(y_1, y_2) \end{array} \quad (h1)$$

+ similar rules to handle dissolution of x_1 or/and x_2

- $O_1^\downarrow \simeq \mathcal{I}_2$ means that the two sets of pairs are the same apart from some (l_i, \emptyset)



$$(a \rightarrow (c, \text{here})(b, \text{in}_2), aa) \xrightarrow[\text{aa}, \{a\}, \text{aa}, \emptyset]{\emptyset, I_1, \emptyset, (2, bb)} (a \rightarrow (c, \text{here})(b, \text{in}_2), Icc)$$

$$[1(a \rightarrow c_{\text{here}}b_{\text{in}_2}, aa)]_1 \xrightarrow{\emptyset, \{(1, I_1)\}, \emptyset, (2, bb)} [1(a \rightarrow c_{\text{here}}b_{\text{in}_2}, Icc)]_1$$

$$[2(\emptyset, \emptyset)]_2 \xrightarrow{\emptyset, \{(2, bb)\}, \emptyset, \emptyset} [2(\emptyset, bb)]_2 \quad [3(\emptyset, \emptyset)]_3 \xrightarrow{\emptyset, \{(3, \emptyset)\}, \emptyset, \emptyset} [3(\emptyset, \emptyset)]_3$$

$$[2(\emptyset, \emptyset)]_2 \mid [3(\emptyset, \emptyset)]_3 \xrightarrow{\emptyset, \{(2, bb), (3, \emptyset)\}, \emptyset, \emptyset} [2(\emptyset, bb)]_2 \mid [3(\emptyset, \emptyset)]_3$$

$$\mu([1 \dots]_1, [2 \dots]_2 \mid [3 \dots]_3) \xrightarrow{\emptyset, \{(1, I_1)\}, \emptyset, \emptyset} \mu([1(-, Icc)]_1, [2(\emptyset, bb)]_2 \mid [3(\emptyset, \emptyset)]_3)$$

Maximal Parallelism Theorem

Theorem (Maximality)

$$(\mathcal{R}, u) \xrightarrow[u', U, u', v']{M, I, O_1^\uparrow, O_1^\downarrow} x \quad \text{implies} \quad (\mathcal{R}, v') \xrightarrow[u'', U', u'', v'']{M, I', O_2^\uparrow, O_2^\downarrow} /$$

for any $u'' \neq \emptyset$

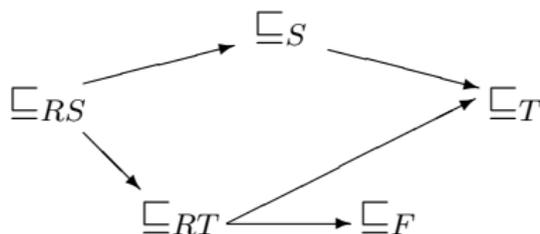
Well-known Behavioral Preorders (1)

Let $(\mathcal{S}, \mathcal{L}, \{\xrightarrow{\ell} \mid \ell \in \mathcal{L}\})$ be an LTS. A relation $R \subseteq \mathcal{S} \times \mathcal{S}$

- is a *simulation* (\sqsubseteq_S the largest) if, for each pair $s_1 R s_2$, if $s_1 \xrightarrow{\ell} s'_1$ then there is a transition $s_2 \xrightarrow{\ell} s'_2$ such that $s'_1 R s'_2$;
- is a *ready simulation* (\sqsubseteq_{RS} the largest) if it is a simulation and, for each pair $s_1 R s_2$, if $s_1 \not\xrightarrow{\ell}$ then $s_2 \not\xrightarrow{\ell}$;
- is a *ready trace preorder* (\sqsubseteq_{RT} the lar.) if, for each pair $s_1 R s_2$, any ready trace of s_1 is a ready trace of s_2 (a sequence $L_0 \ell_1 L_1 \dots \ell_n L_n$ with $L_i \subseteq \mathcal{L}$ and $\ell_i \in \mathcal{L}$ is a *ready trace* of a state s_0 if $s_0 \xrightarrow{\ell_1} s_1 \xrightarrow{\ell_2} \dots s_{n-1} \xrightarrow{\ell_n} s_n$ and $\text{Initials}(s_i) = L_i$ for $i = 0, \dots, n$);
- is a *failure preorder* (\sqsubseteq_F the largest) if, for each pair $s_1 R s_2$, any failure of s_1 is a failure of s_2 (a pair $(\ell_1 \dots \ell_n, L)$ with $\ell_1 \dots \ell_n \in \mathcal{L}$ and $L \subseteq \mathcal{L}$ is a *failure* of a state s if $s \xrightarrow{\ell_1} \dots \xrightarrow{\ell_n} s'$ for some state s' such that $\text{Initials}(s') \cap L = \emptyset$);
- is a *trace preorder* (\sqsubseteq_T the largest) if, for each pair $s_1 R s_2$, any trace of s_1 is a trace of s_2 (a sequence $\ell_1 \dots \ell_n$ with $\ell_i \in \mathcal{L}$ is a *trace* of a state s_0 if $s_0 \xrightarrow{\ell_1} \dots \xrightarrow{\ell_n} s_n$ for some state s_n).

Well-known Behavioral Preorders (2)

It is well-known that the considered preorders are structured as follows (where \rightarrow is \subseteq)



In the case of the P Algebra all the inclusions are strict

Well-known Behavioral Equivalences

The kernels of the preorders (the largest equivalence each of them contains) are well-known behavioral equivalences

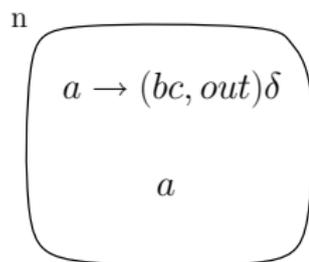
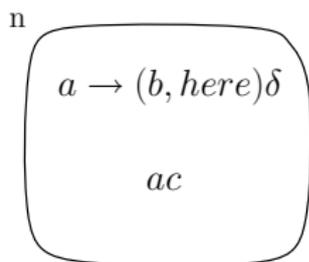
- bisimulation \approx is the kernel of \sqsubseteq_S
- trace equivalence \approx_T is the kernel of \sqsubseteq_T

The inference rules of the semantics of the P Algebra satisfy *de Simone* format.

Theorem All of the considered preorders are precongruences

Corollary All of the kernels of the considered preorders are congruences

Examples of Equivalent Membranes (1)



Their semantics are

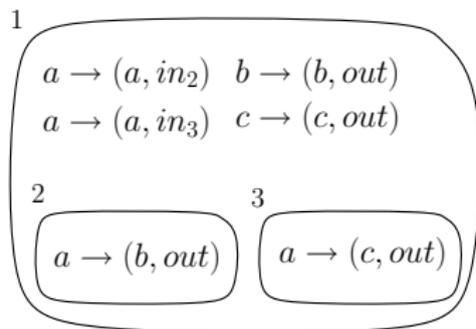
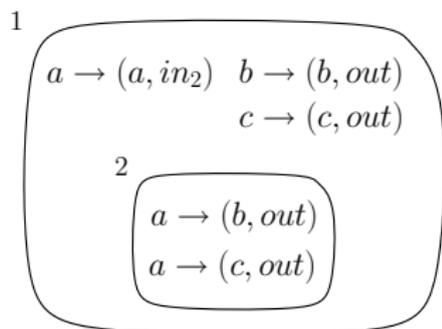
$$[{}_n (a \rightarrow (b, \text{here})\delta, ac)]_n \xrightarrow{\emptyset, I, bc, \emptyset} \mathbf{v}$$

and

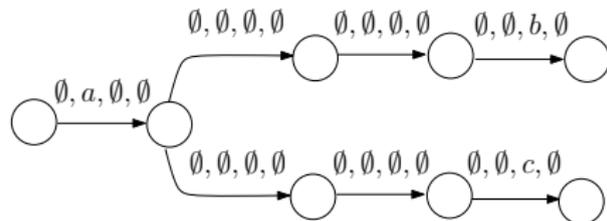
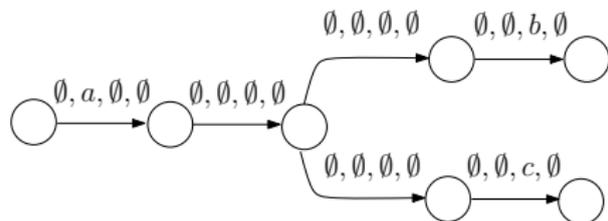
$$[{}_n (a \rightarrow (bc, \text{out})\delta, a)]_n \xrightarrow{\emptyset, I, bc, \emptyset} \mathbf{v}$$

that are (obviously) both trace equivalent \approx_T and bisimilar \approx

Examples of Equivalent Membranes (2)



Portions of their semantics are



that are trace equivalent \approx_T but not bisimilar \approx

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Priorities

As for maximal parallelism, rule priorities are difficult to be described compositionally

The definition becomes easier if we choose a different notation

$$a \rightarrow (b, in_2) > c \rightarrow (d, out)$$

becomes

$$a \rightarrow (b, in_2) \quad \{(a, 2)\} c \rightarrow (d, out)$$

where $(a, 2)$ is called *priority pair* and contains information on the applicability of the rule with higher priority

The PP Algebra

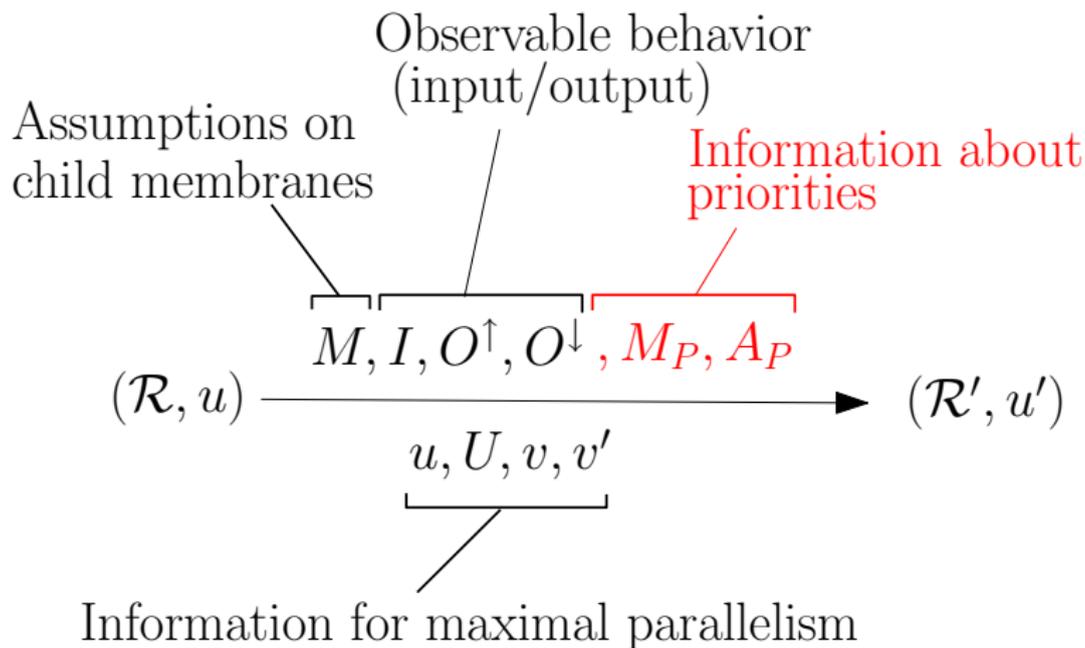
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$$\begin{aligned}c &::= (\emptyset, \emptyset) \mid (\{(u_i, M_i)\} u \rightarrow v_h v_o \{v_{l_i}\}, \emptyset) \\ &\quad \mid (\{(u_i, M_i)\} u \rightarrow v_h v_o \{v_{l_i}\} \delta, \emptyset) \mid (\emptyset, a) \mid c \cup c \\ m &::= [l c]_l \\ ms &::= m \mid ms \mid ms \mid \mu(m, ms) \mid \mathbf{v}\end{aligned}$$

where l and l_i range over \mathbb{N} and a ranges over V .

- $\{(u_i, M_i)\} u \rightarrow v_h v_o \{v_{l_i}\}$ stands for $\{(u_1, M_1), \dots, (u_n, M_n)\} u \rightarrow (v_h, \text{here})(h_o, \text{out})(v_{l_1}, \text{in}_{l_1}) \dots (v_{l_m}, \text{in}_{l_m})$

Transitions with Priorities



Conclusions and Future Work

We defined a compositional semantics of P Systems

- we proved that it correctly describes maximal parallelism (and priorities)

We considered some well-known behavioral preorders and equivalences

- we proved that they are different relations in the case of P Systems
- we proved them to be (pre)congruences

As future work we will develop *axiomatic semantics*

- syntactical transformations between terms being correct and complete w.r.t. a behavioral equivalence