

Secure Service Orchestration

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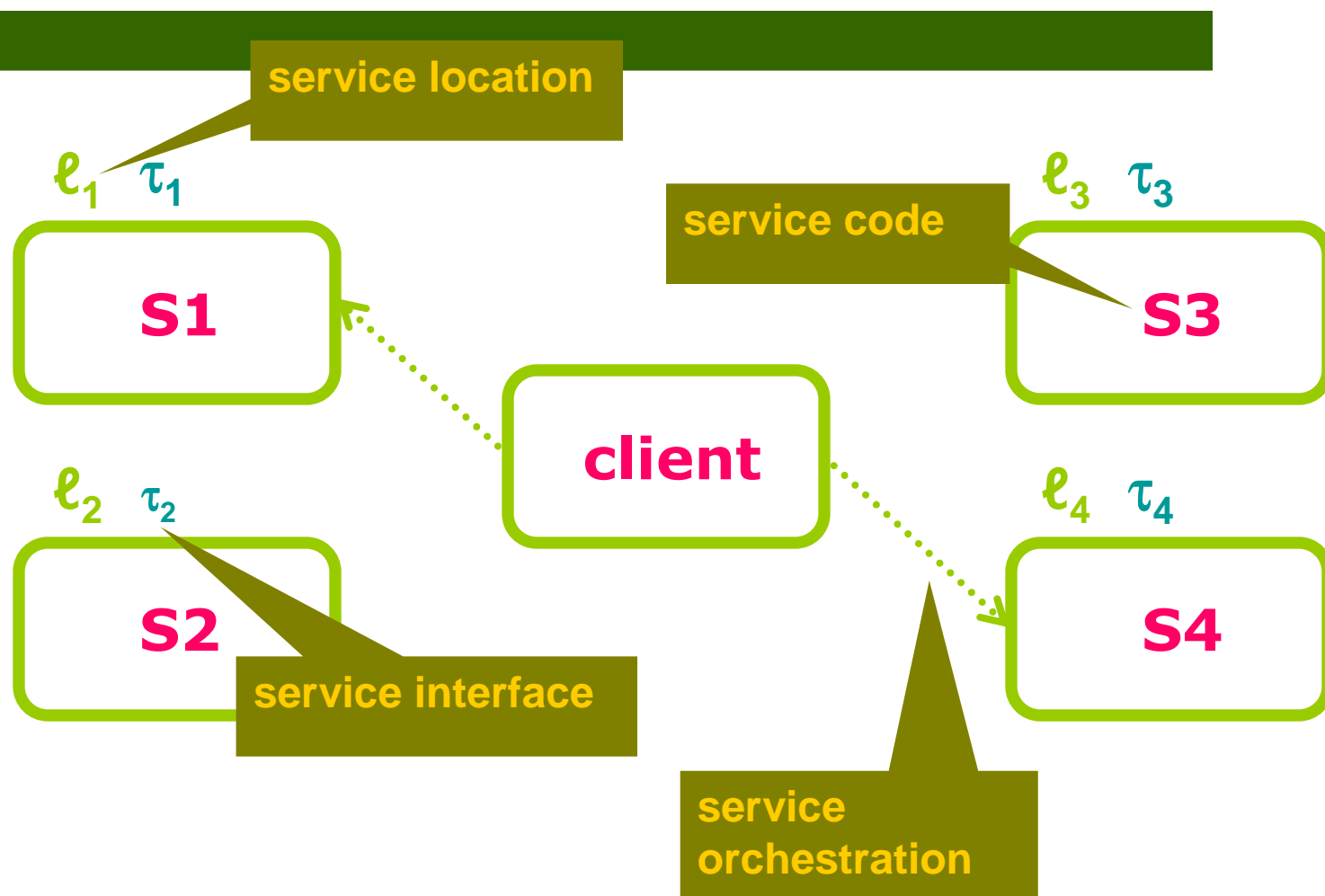
Summary

- **Overview**
 - **issues in secure service composition**
 - **security model: safety framings and policies**
 - **call-by-contract for service request**
 - **plans for secure orchestration**
- A calculus for service composition
 - syntax and operational semantics
 - type & effect system
- Plans & Orchestration
 - constructions of plans and linearization
 - model-checking viable plans

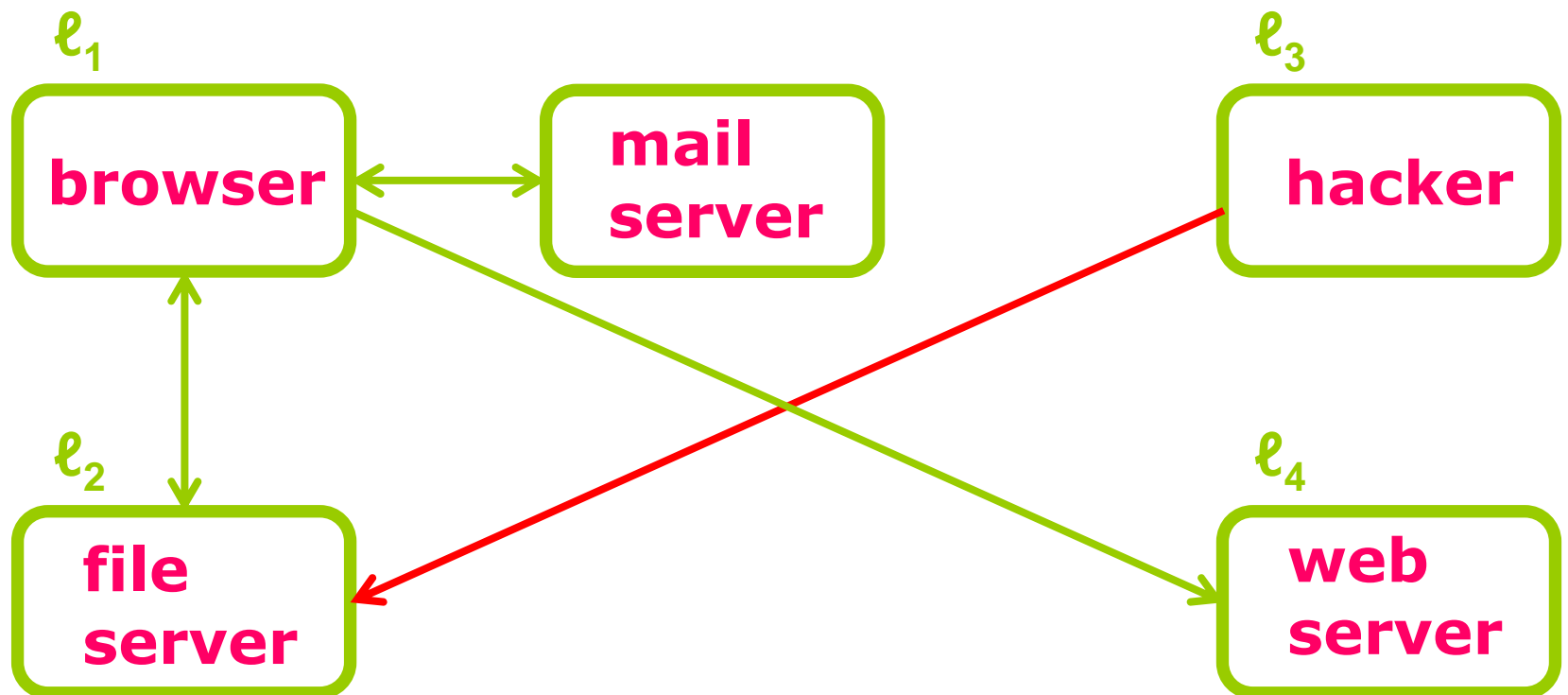
Programming in a world of services



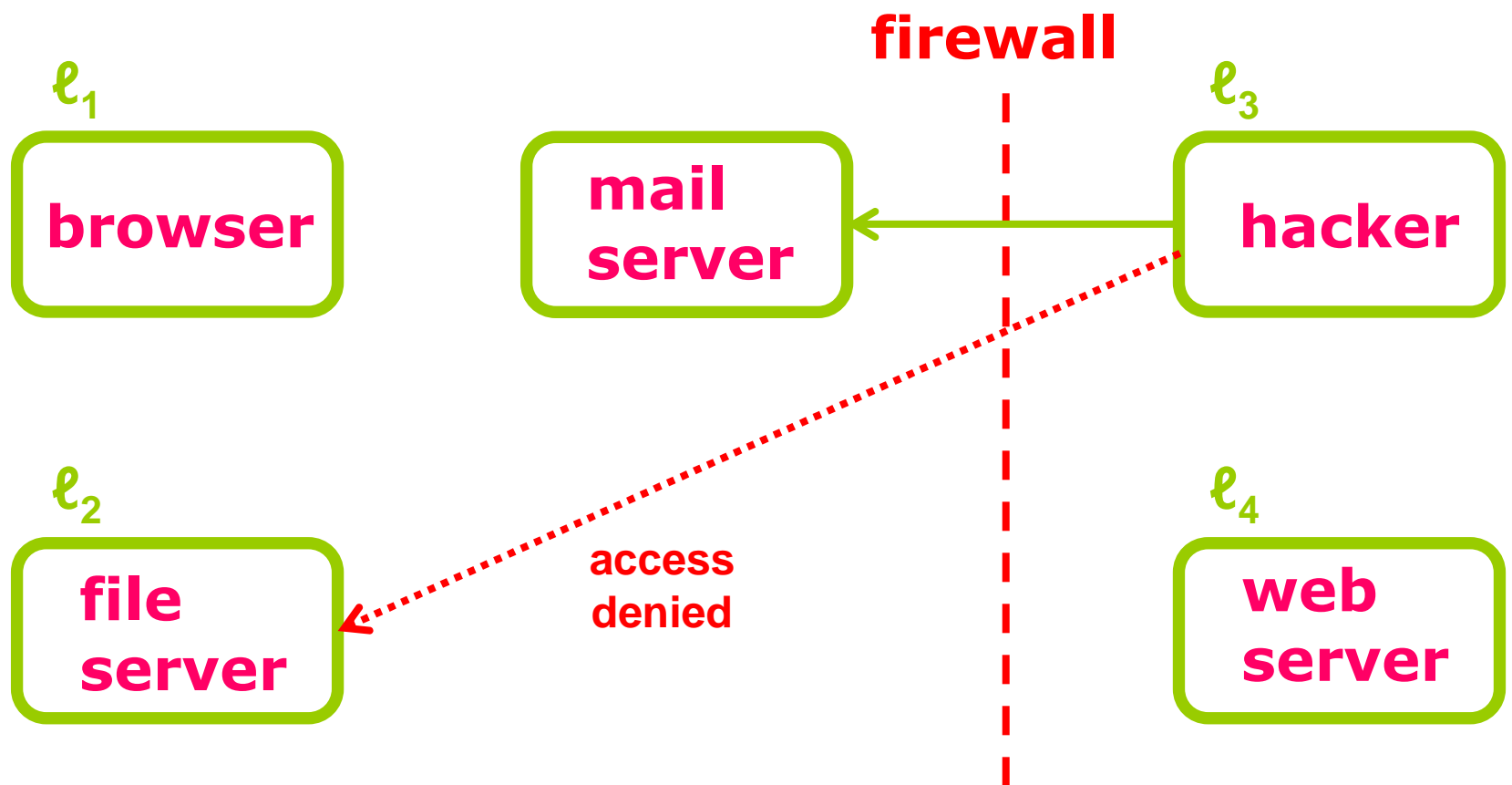
Programming in a world of services



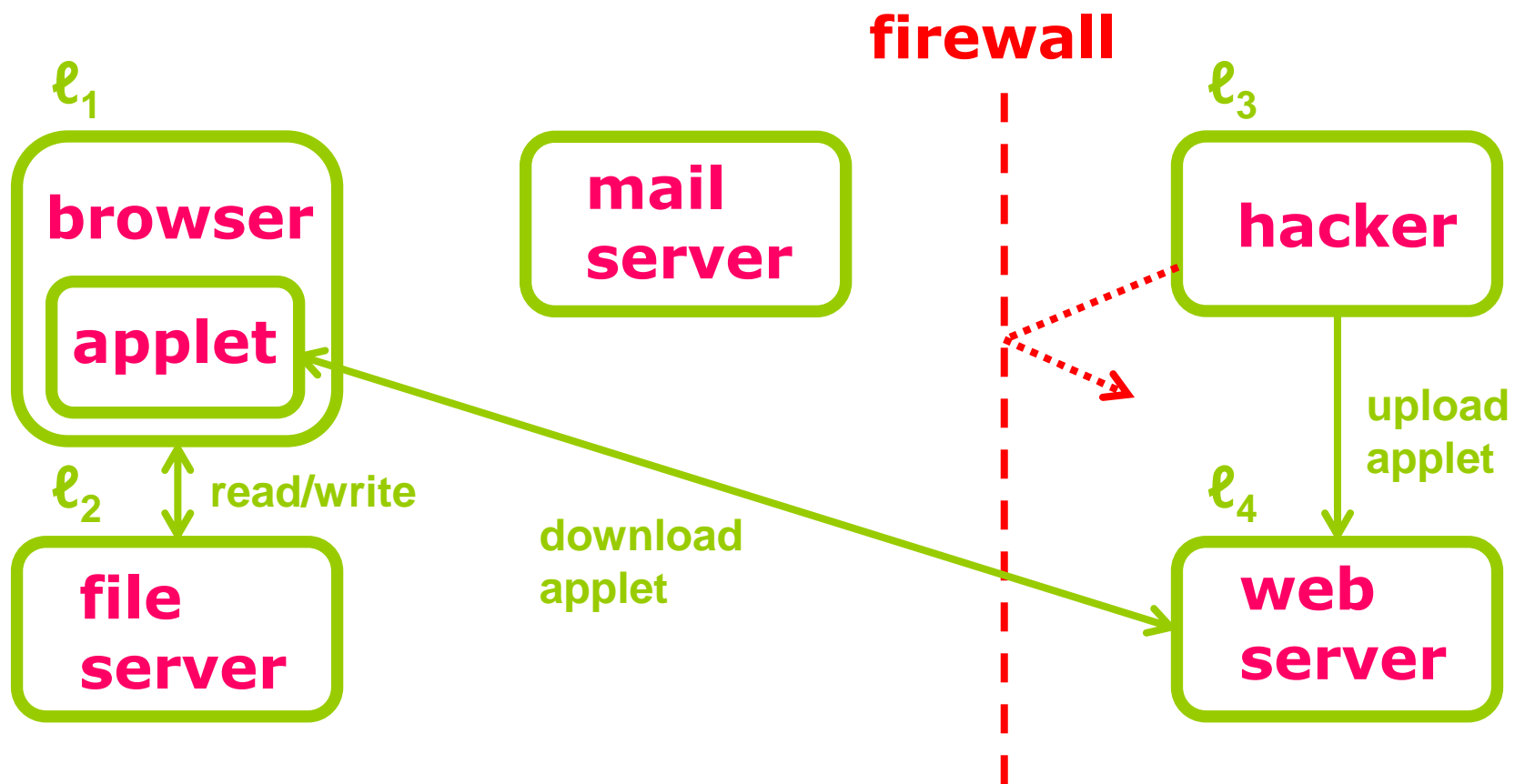
Traditional protection: firewalls



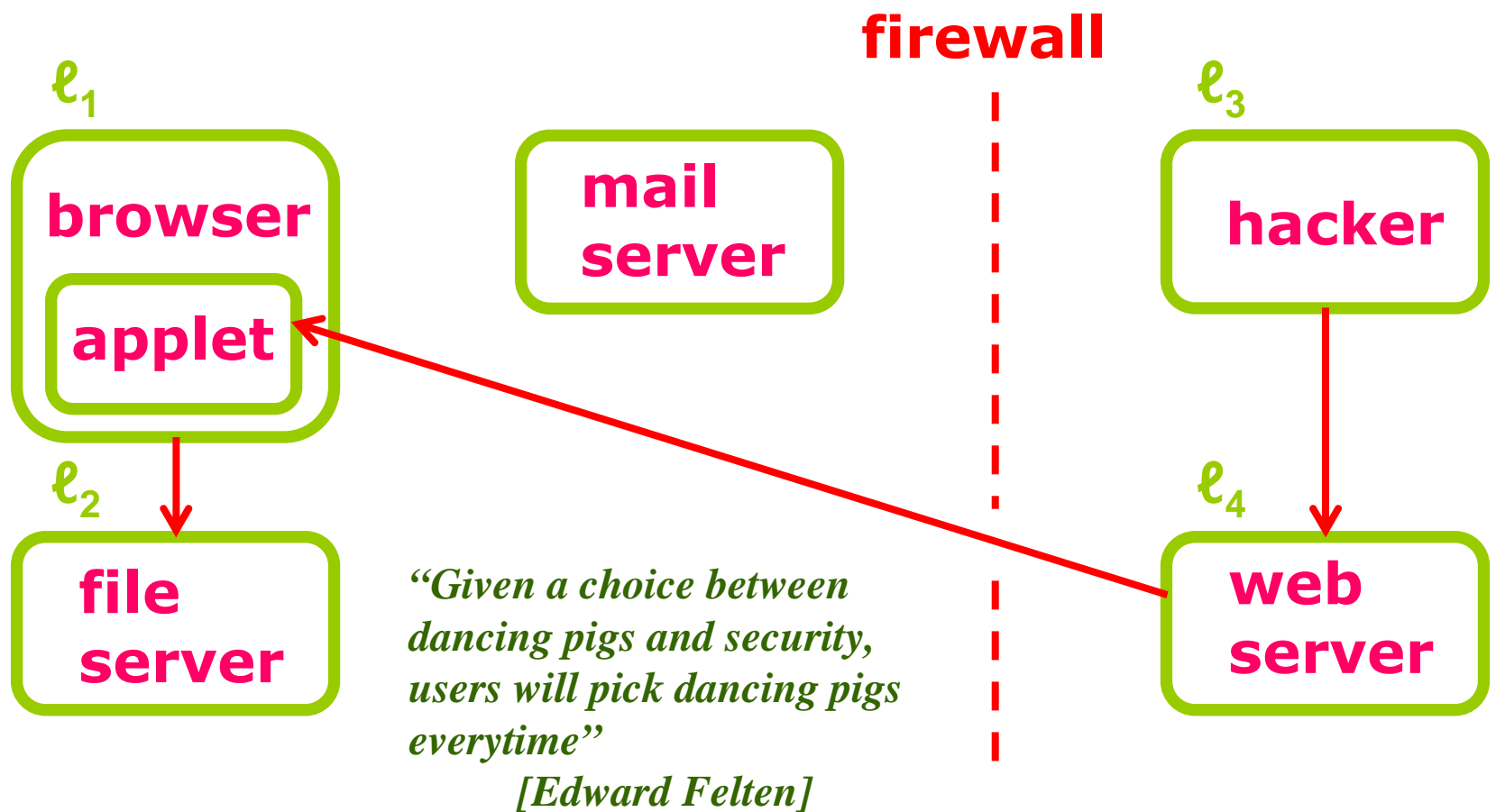
Traditional protection: firewalls



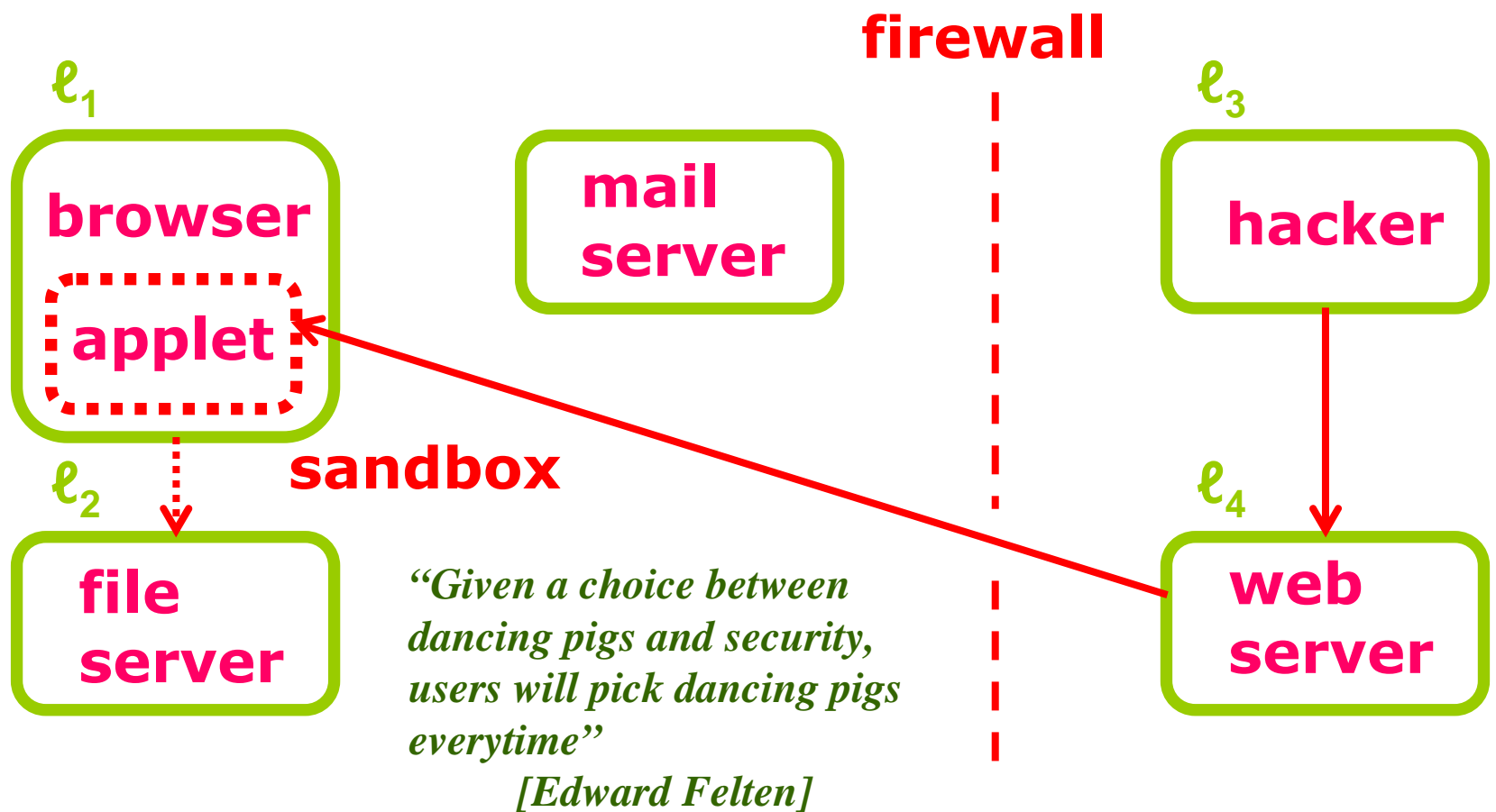
Trojan horses



Trojan horses



Trojan horses



Security and service composition

- two kinds of security concerns:
 - secrecy of transmitted data, authentication, etc
(protocol analysis techniques – first part of course)
 - control on computational resources
(access control, resource usage analysis, information flow control, etc)
- need for linguistic mechanisms that:
 - work in a distributed setting
 - assume no (or weak) trust relations among services
 - can also cope with *mobile code*

Checklist for secure service composition

We want to devise a framework that:

- is *expressive* enough to model with real-world (although simplified) scenarios
- allows for a *formal characterization* of what security property is actually obtained, under a reasonable trusted computing base
- is *simple* enough to allow for a clean formal treatment, and for mechanical analysis tools
- deal with security from system design to implementation
- abstracts from technological biz (no WS-* buzzwords)

Security and service composition: safety framings

Client wants to protect from untrusted results



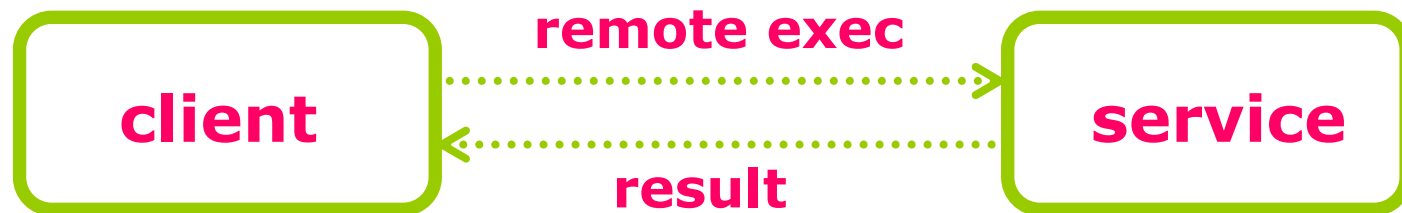
Linguistic mechanism: **safety framing**



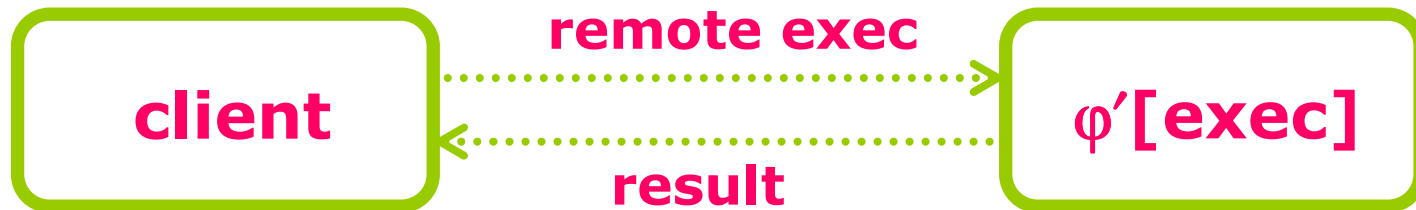
The **policy** φ is enforced stepwise within its **scope**

Security and service composition: safety framings

Similarly, services want to protect from clients



(now the **safety framing** belongs to the service)



Scoped policies check the **local execution histories**

Security and service composition: service selection

Call-by-name: request a *given* service among many



Why **S2** and not **S1** or **S3**, if all functionally equivalent ?

Security and service composition: service selection

Problems with “call by name”:

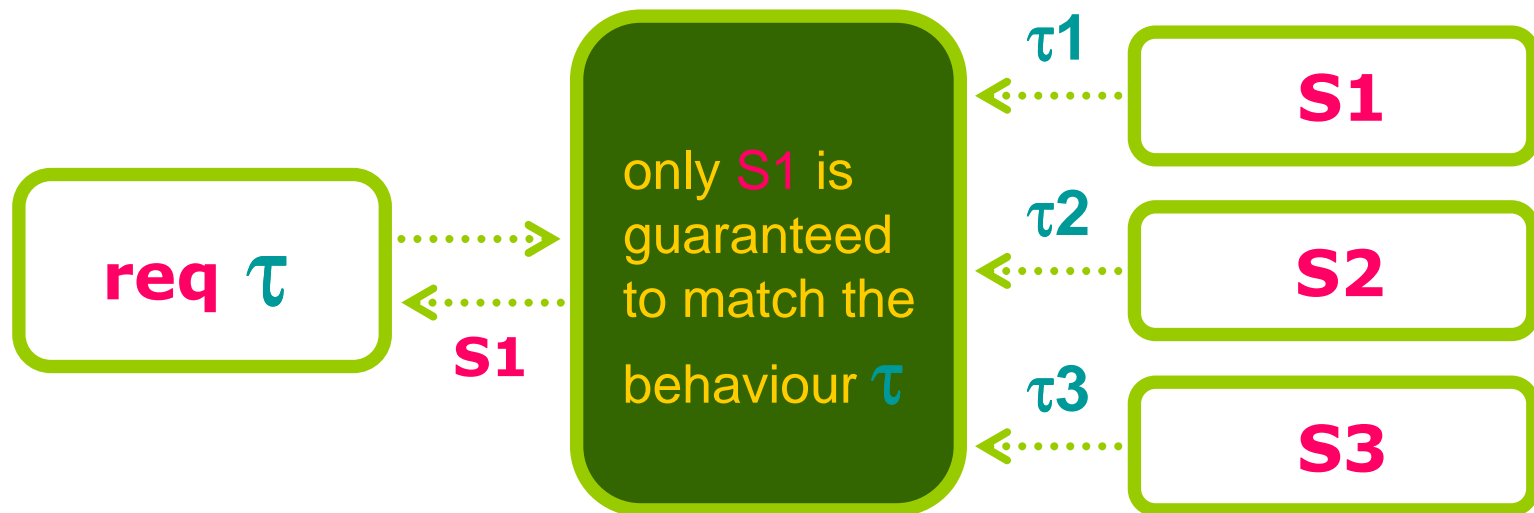
- what if named service **S2** becomes unavailable ?
- ...and if **S2** is outperformed by **S1** or **S3** ?
- hard reasoning about non-functional properties of services (e.g. security)
- security level independent of the execution context (unless hard-wired in the service code)

From syntax-based to semantics-based invocation

Service names ℓ, ℓ', \dots tell me nothing about the behaviour!

Security and service composition: service selection

Call-by-contract: request a service respecting
the desired behaviour



τ imposes both functional and non-functional constraints

Use cases for call-by-contract

Example: download an applet that obeys the policy φ

$$\text{req } \tau_0 \longrightarrow (\tau_1 \xrightarrow{\varphi[\bullet]} \tau_2)$$

Example: a remote executer that obeys the policy φ'

$$\text{req } (\tau_0 \longrightarrow \tau_1) \xrightarrow{\varphi'[\bullet]} \tau_2$$

Observable behaviour

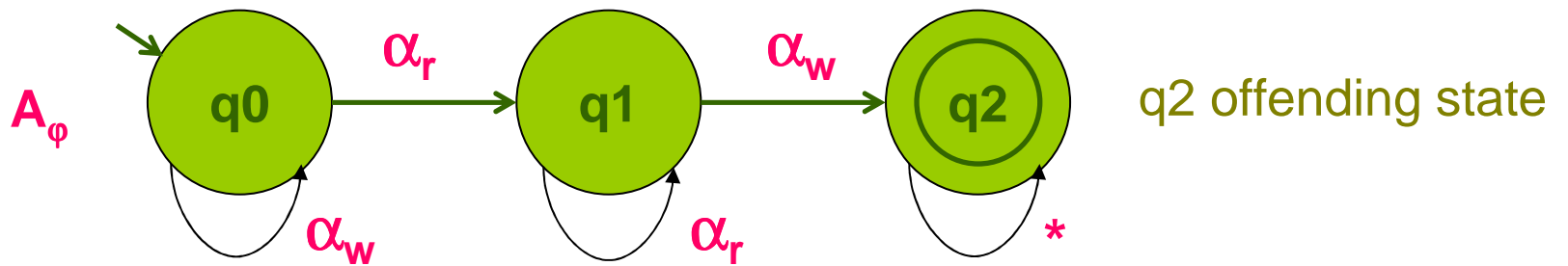
- **access events** are the actions relevant for security (e.g. read/write local files, invoke/be invoked by a given service, etc)
 - mechanically inferred, or inserted by programmer.
 - their meaning is fixed globally.
 - access events cannot be hidden.
- the **(abstract) behaviour** observable by the orchestrator over-approximates the **histories**, i.e. sequences of access events, obtainable at run-time **(type & effect system)**.

What kind of policies ?

- History-based security
- Policies φ are **regular** properties event histories (i.e. the language accepted by φ is recognizable by finite state automata)
- Policies φ, φ' have a **local scope**, possibly **nested** $\varphi[\dots\varphi'[\dots]\dots]$
- When the scope of φ is left, the history needs not to obey φ any longer.
- Parametric policies $\varphi(\mathbf{x})$ can be defined through *template usage automata*.

Example: the Chinese Wall policy

φ Chinese Wall: cannot write (α_w) after read (α_r)



$\alpha_w \alpha_r \alpha_w \neq \varphi$

Other expressible policies

- **Anti-phishing**: known phishers sites are black-listed (sensitive accesses are denied after you have visited a phisher site)
- **Chinese-Wall (tolerant version)**: you cannot connect to the network after you have read a file you have not created
- **Java sandbox**: an applet can only connect to the site it was downloaded from
- **Denial-of-service**: an applet cannot create more than k files.

A taxonomy of security aspects

- ***stateless / stateful services***. In the stateless case, each service invocation starts with an empty history, while stateful keeps histories through invocations.
- ***local / global histories***. In the local case, a policy can only inspect histories of a single site. This requires no trust among services.
- ***first order / higher order requests***. With higher-order requests, we can model mobile code.
- ***dependent / independent threads***. In the dependent case, threads share execution histories. Instead, independent threads keep histories separated.

Principle of Least Privilege

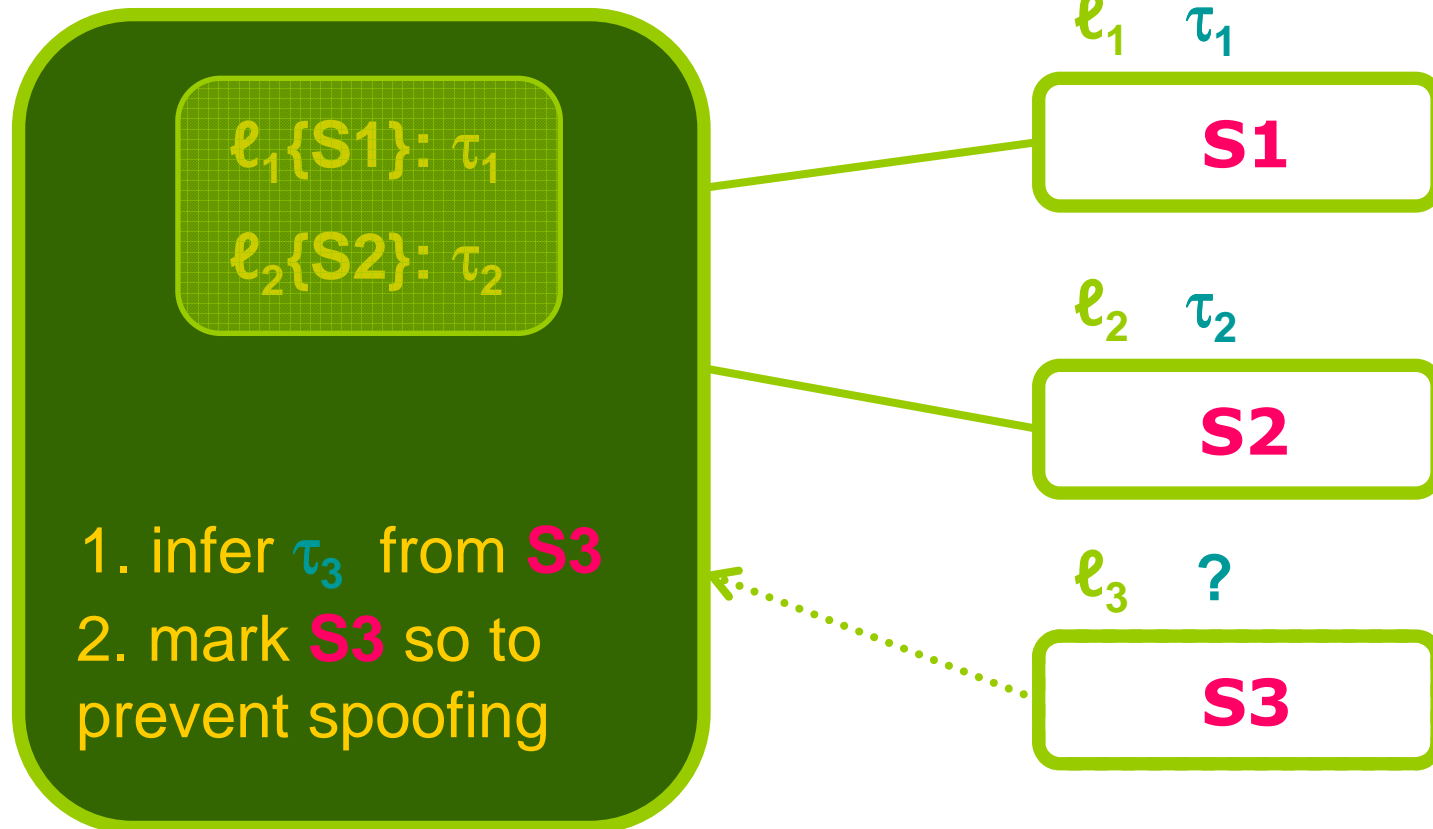
“Programs should be granted the minimum set of rights needed to accomplish their task”

- A service must always obey all the active policies (**no policy override**)
- Policies can always inspect the whole past history (**no event can be discarded**)
- “Privileged calls” implemented by policies that explicitly discard the past

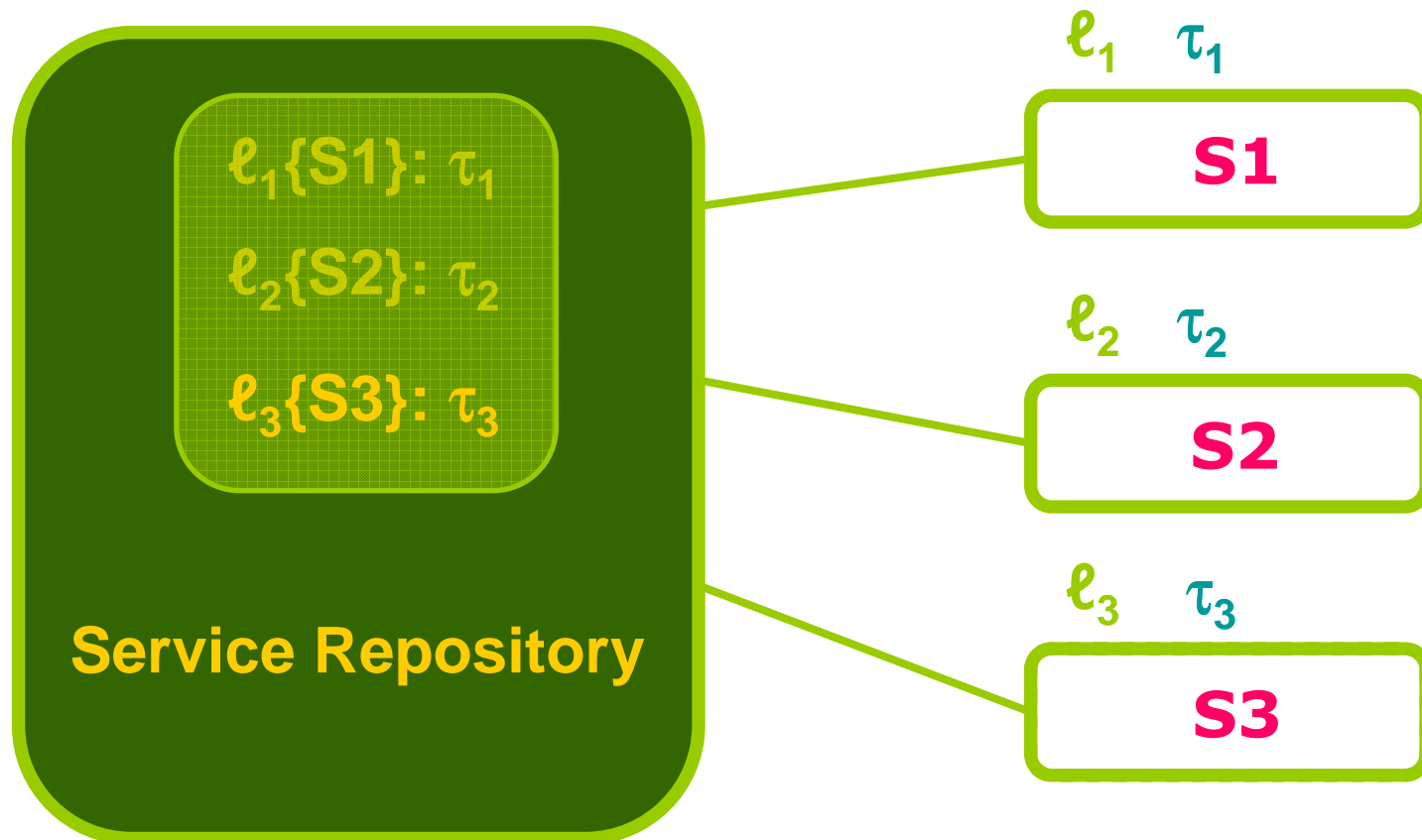
Roadmap to call-by-contract

- We have defined:
 - the form of requests: **req** τ
 - the observable behaviour: **event histories**
 - the security policies φ , and their enforcement mechanism A_φ
 - local policies: $\varphi[]$
- What's next:
 - service publication: $\ell\{S\}: \tau$
 - service orchestration: mapping **req** τ to **req** ℓ

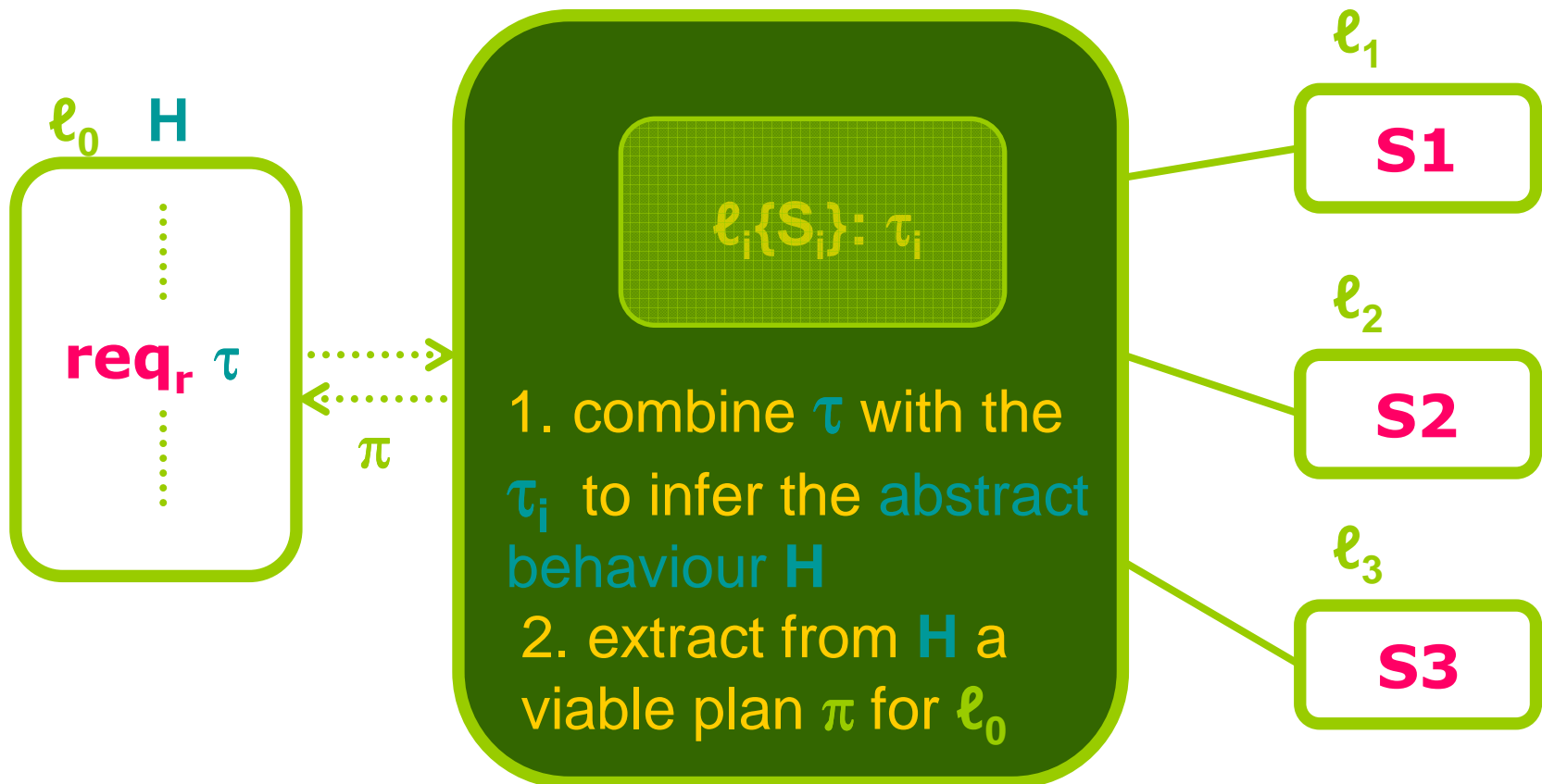
Service publication (1)



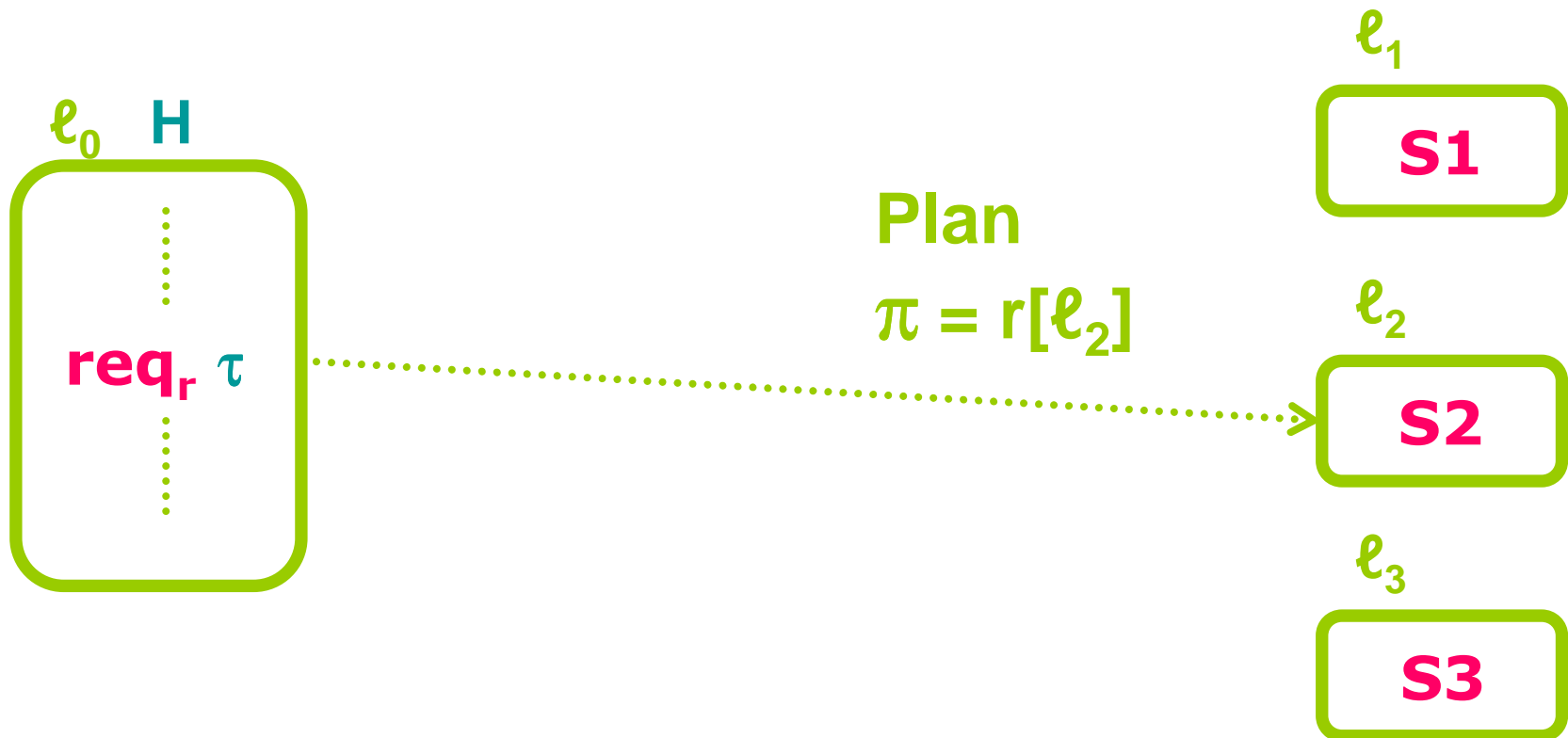
Service publication (2)



Service orchestration



Service orchestration



Names are only known by the orchestrator!

What is a plan ?

- A plan drives the execution of an application, by associating each service request with one (or more) appropriate services
- With a **viable plan**:
 - executions **never violate** policies
 - there are **no unresolved** requests
 - you can then **dispose** from any execution monitoring!
- Many kinds of plans:
 - **Simple**: one service for each request
 - **Multi-choice**: more services for each request
 - **Dependent**: one service, and a continuation plan
 - ...

Who do we trust ?

The orchestrator, that:

- certifies the behavioural descriptions of services (**types annotated with effects H**)
- composes the descriptions, and ensures that selected services match the requested types
- extracts the **viable plans** (through model-checking)

Also, we trust services not to change their code on-the-fly (trusted computer - corporate)

Summing up...

- a calculus for secure service composition:
 - **distributed** services
 - **safety framings** scoped policies on localized execution histories
 - **call-by-contract** service invocation
- static orchestrator:
 - certifies the **behavioural interfaces** of services
 - provides a client with the **viable plans** driving secure executions

What's next

- calculus: syntax and **operational semantics**
- static semantics: **type & effect system**
 - **types** carry annotations **H** about service behaviour
 - **effects H** are history expressions, which over-approximate the actual execution histories
- extracting viable plans:
 - **linearization**: unscrambling the structure of **H**
 - **model checking**: valid plans are viable

Services

| | | | |
|-------------------|---------------------------|---|-----------------|
| Services | $e ::=$ | x | variable |
| | | α | access event |
| | | if b then e else e' | conditional |
| | | $\lambda_z x. e$ | abstraction |
| | | $e e'$ | application |
| | | $\varphi[e]$ | safety framing |
| | | req_r τ | service request |
| (only in configs) | | wait ℓ | wait reply |

Networks

location

service code and
published interface

$N ::= \ell\{e:\tau\}:\eta, e'$

published service

$N \parallel N'$

composition

execution
history

running code

(Simple) Plans

A **plan** is a function from requests r to services ℓ

| | |
|-----------------|----------------|
| $\pi ::= 0$ | empty |
| $r[\ell]$ | service choice |
| $\pi \mid \pi'$ | composition |

Plans respect the partial knowledge $\ell < \ell'$ of services about the network ($<$ is a partial ordering)

Example: delegating code execution

ℓ_1

$\lambda x. \varphi[\alpha_r; \dots]$

ℓ_2

$\alpha_c; (\lambda x. \alpha_r; \dots; \alpha_w)$

$f = \text{req}_{r1}()$

$\text{req}_{r2}(f)$

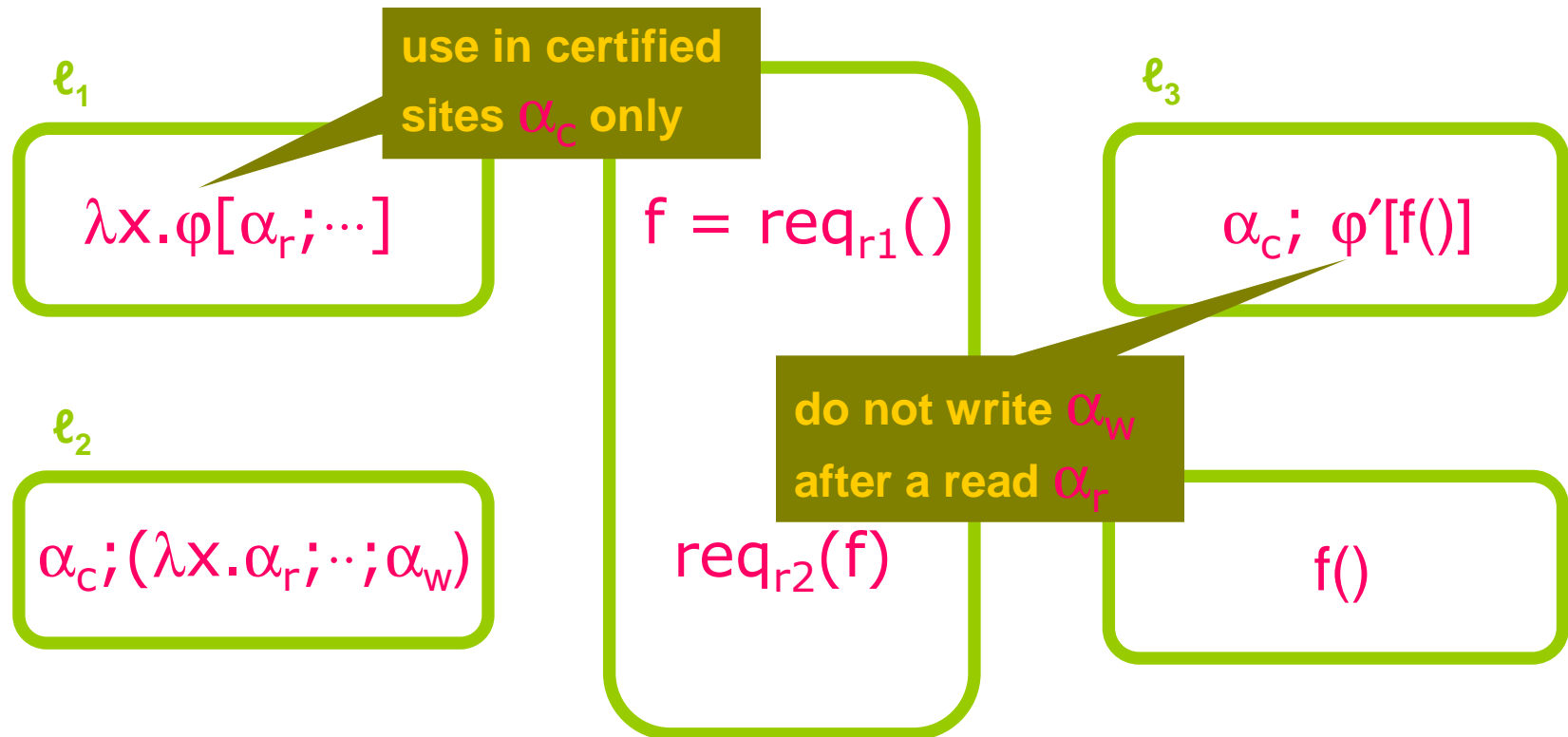
ℓ_3

$\alpha_c; \varphi'[f()]$

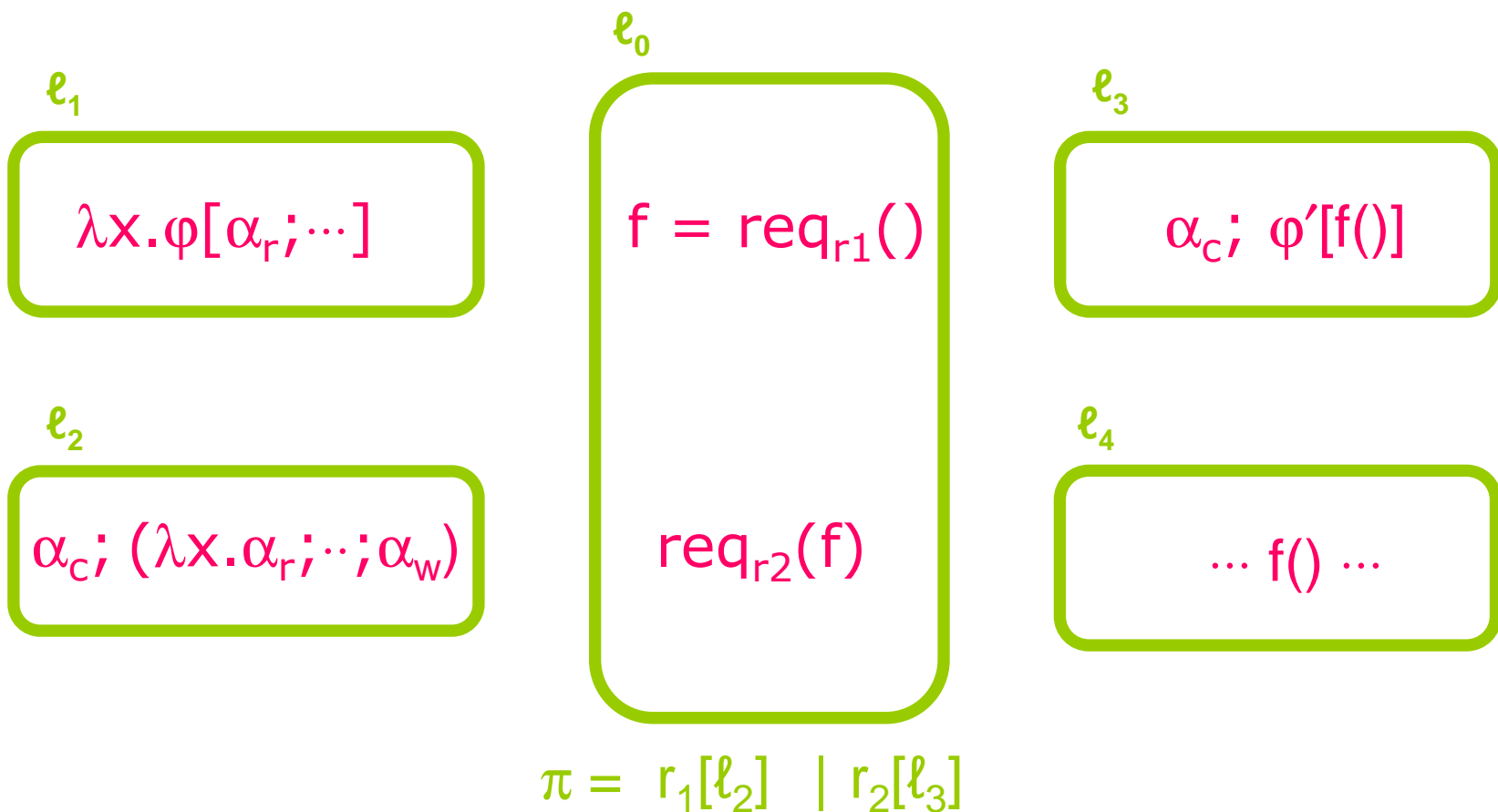
ℓ_4

$f()$

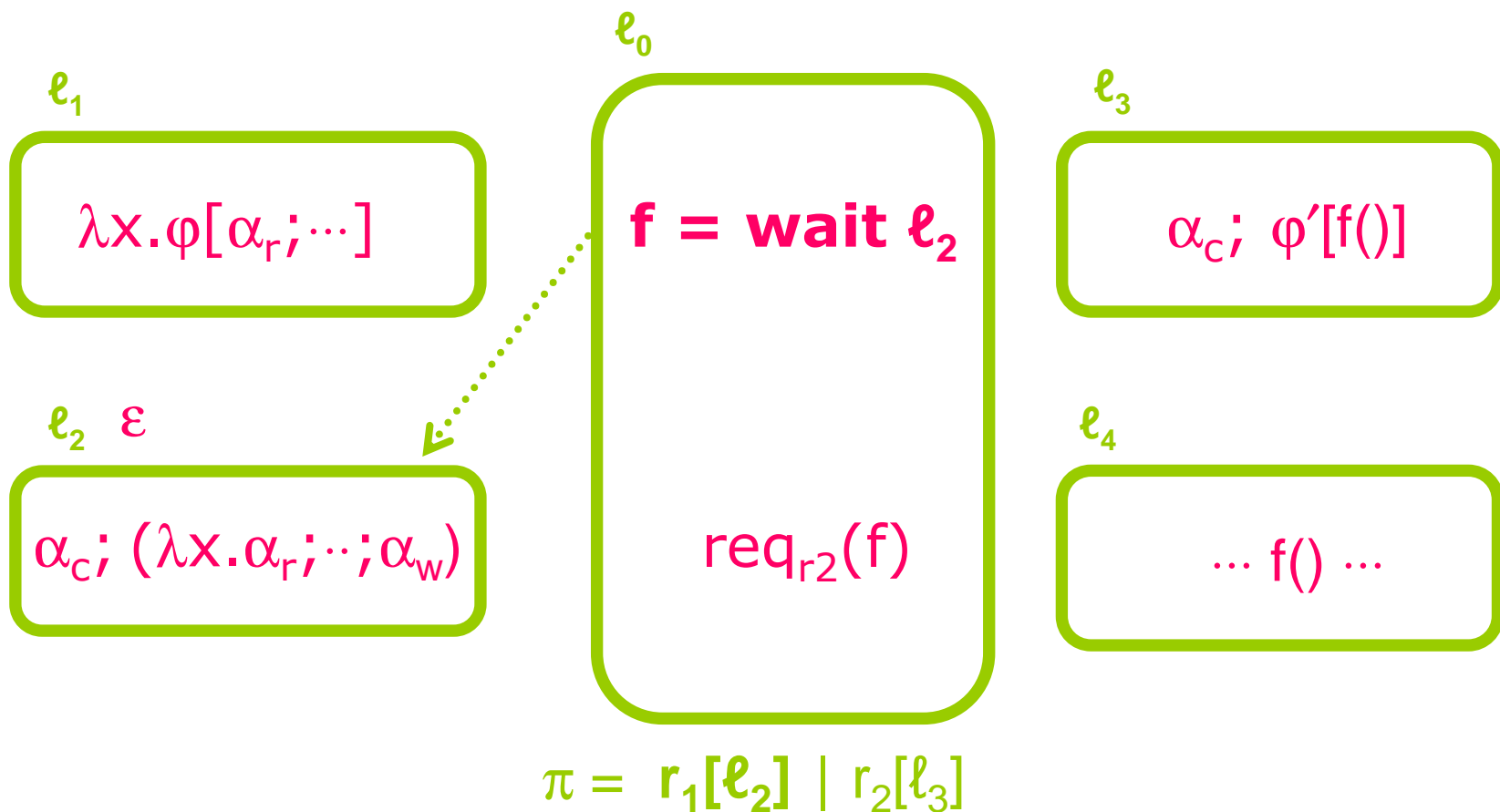
Example: delegating code execution



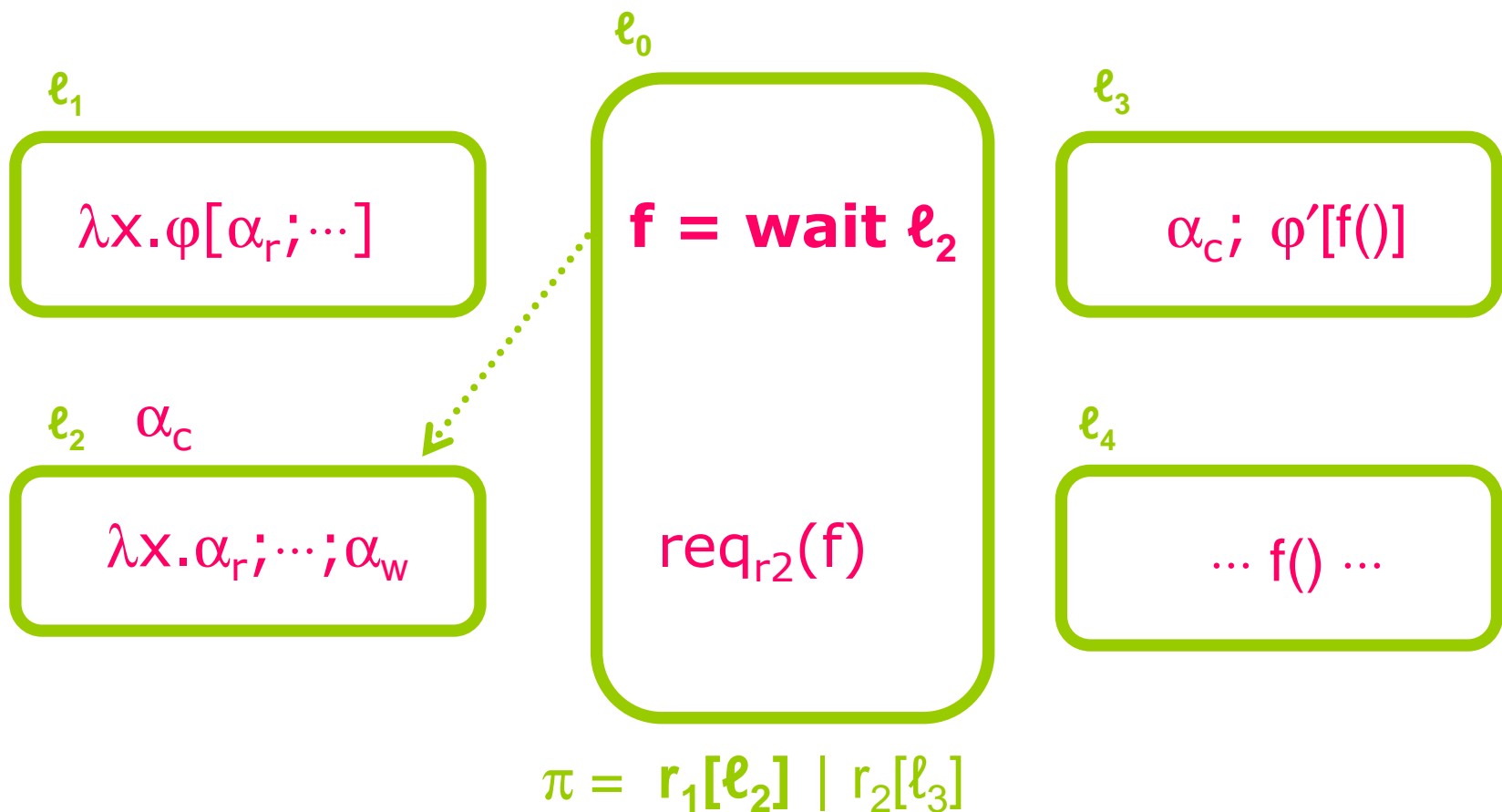
Executing a network of services



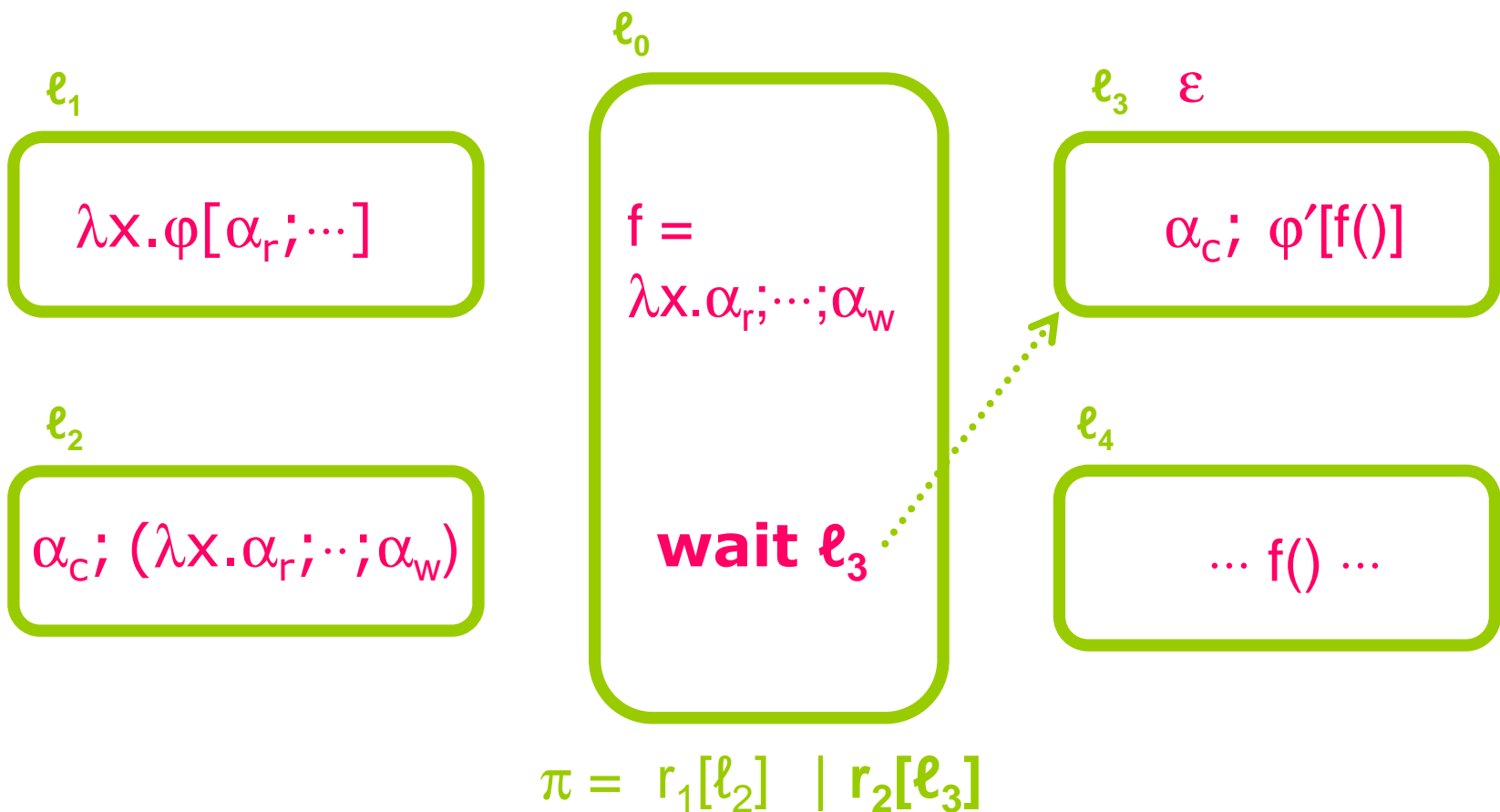
Executing a network of services



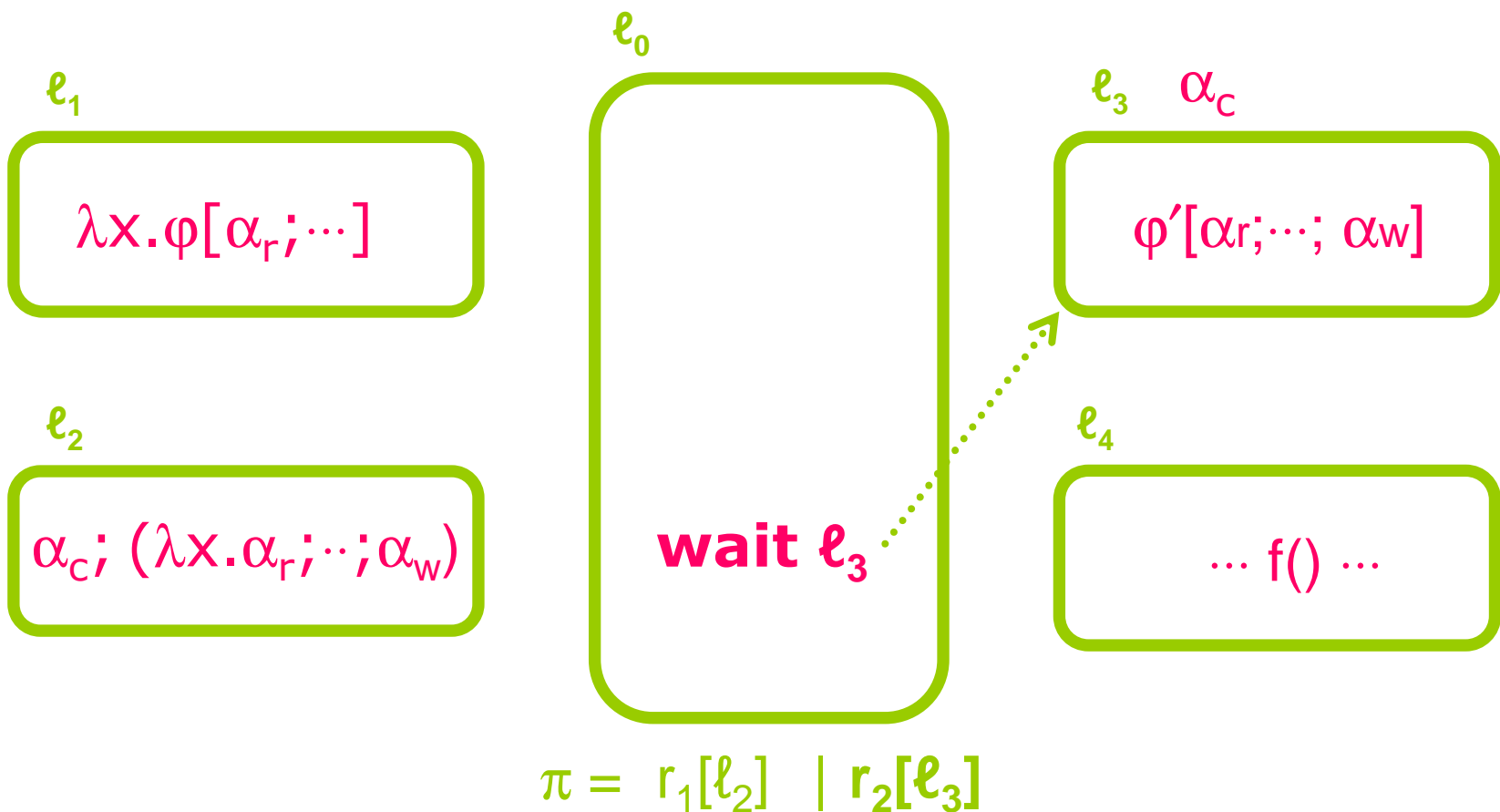
Executing a network of services



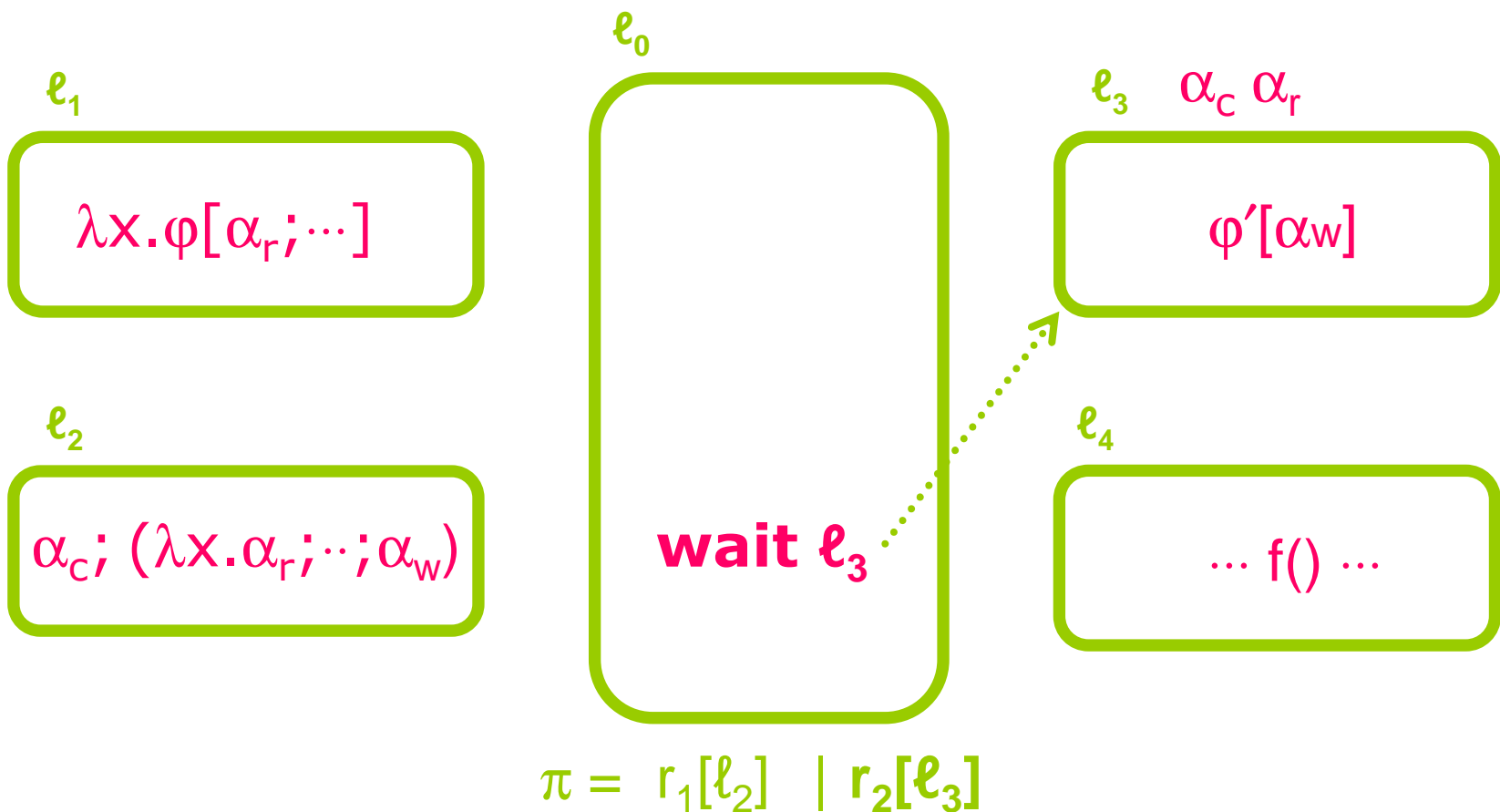
Executing a network of services



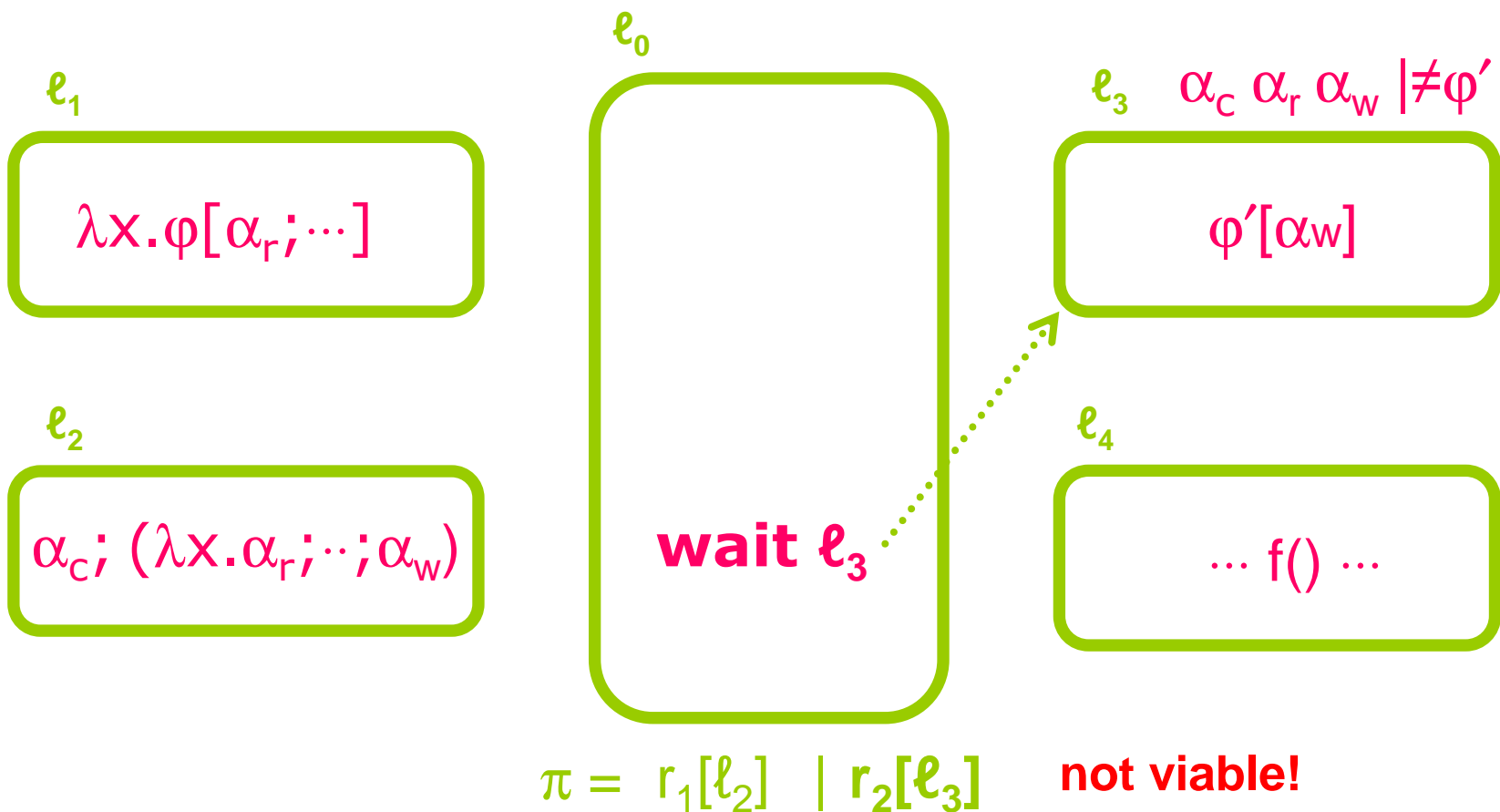
Executing a network of services



Executing a network of services



Executing a network of services



Semantics of services (1)

[App1]

$$\frac{\eta, e_1 \rightarrow \eta', e_1'}{\eta, e_1 e_2 \rightarrow \eta', e_1' e_2}$$

[App2]

$$\frac{\eta, e_2 \rightarrow \eta', e_2'}{\eta, v e_2 \rightarrow \eta', v e_2'}$$

[AbsApp]

$$\eta, (\lambda_z x. e) v \rightarrow \eta, e\{v/x, \lambda_z x. e/z\}$$

[If]

$$\eta, \text{if } b \text{ then } e_{\text{true}} \text{ else } e_{\text{false}} \rightarrow \eta, e_{\mathcal{B}(b)}$$

Semantics of services (2)

[Event]

$$\eta, \alpha \rightarrow \eta\alpha, ()$$

[Framing In]

$$\frac{\eta, e \rightarrow \eta', e' \quad \eta' \models \varphi}{\eta, \varphi[e] \rightarrow \eta', \varphi[e']}$$

[Framing Out]

$$\frac{\eta \models \varphi}{\eta, \varphi[v] \rightarrow \eta, v}$$

Semantics of networks (1)

[Inject]

$$\eta, e \rightarrow \eta', e'$$

$$\ell: \eta, e \rightarrow_{\pi} \ell: \eta', e'$$

[Par]

$$N_1 \rightarrow_{\pi} N_1'$$

$$N_1 \parallel N_2 \rightarrow_{\pi} N_1' \parallel N_2$$

Semantics of networks (2)

[Request]

$$\pi = r[\ell'] \mid \pi'$$

$\ell: \eta, \text{req}_r \ v \ \parallel \ \ell'\{e'\}: \varepsilon, \star$

$\xrightarrow{\pi}$

$\ell: \eta, \text{wait } \ell' \ \parallel \ \ell'\{e'\}: \varepsilon, e'v$

[Reply]

$\ell: \eta, \text{wait } \ell' \ \parallel \ \ell'\{e'\}: \eta', v$

$\xrightarrow{\pi}$

$\ell: \eta, v \ \parallel \ \ell'\{e'\}: \varepsilon, \star$

Other kinds of plans

- **Simple plans** $\pi ::= 0 \mid \pi \mid \pi \mid r[\ell]$
 $\ell: \text{req}_r \parallel \ell': \{e\} \rightarrow_{r[\ell']} \ell: \text{wait } \ell' \parallel \ell': e$
- **Multi-choice plans** $\pi ::= 0 \mid \pi \mid \pi \mid r[\ell_1 \dots \ell_k]$
 $\ell: \text{req}_r \parallel \ell': \{e\} \rightarrow_{r[\ell', \ell'']} \ell: \text{wait } \ell' \parallel \ell': e$
- **Dependent plans** $\pi ::= 0 \mid \pi \mid \pi \mid r[\ell. \pi]$
 $\ell: r[\ell'. \pi] \triangleright \text{req}_r \parallel \ell': \{e\} \rightarrow \ell: r[\ell'. \pi] \triangleright \text{wait } \ell' \parallel \ell': \pi \triangleright e$
- ...many others: multi+dependent, regular, dynamic,...

Static semantics

Type & effect system

- **types** carry annotations **H** about service abstract behaviour
- **effects H**, namely *history expressions*, over-approximate the actual execution histories
- the type & effect inferred for a service depends on its **partial knowledge** \prec of the network

Types

(pretty standard)

$$\tau ::= \text{int} \mid \text{bool} \mid 1 \mid \dots \mid \tau \xrightarrow{H} \tau'$$

Effects (history expressions)

| | |
|--|--------------------------|
| $H ::= \varepsilon$ | empty |
| h | variable |
| α | access event |
| $H \cdot H'$ | sequence |
| $H + H'$ | choice |
| $\mu h.H$ | recursion |
| $\varphi[H]$ | safety framing |
| $\ell: H$ | localization |
| $\{\pi_1 \triangleright H_1 \cdots \pi_k \triangleright H_k\}$ | planned selection |

Semantics of history expressions

$$[[\alpha]]^{\pi} = (? : \alpha)$$

$$[[\ell : H]]^{\pi} = [[H]]^{\pi} \{ \ell / ? \}$$

$$[[\{ \pi_1 \triangleright H_1 \cdots \pi_k \triangleright H_k \}]]^{\pi} = \bigcup_{i=1..k} [[\{ \pi_i \triangleright H_i \}]]^{\pi}$$

$$[[\{ \pi' \triangleright H \}]]^{\pi} = [[H]]^{\pi} \quad \text{if } \pi' \leq \pi \quad \text{plan } \pi' \text{ resolves the requests as } \pi$$

$$0 \leq \pi \quad r[\ell] \leq r[\ell] \mid \pi \quad \pi_0 \mid \pi_1 \leq \pi \text{ if } \pi_0 \leq \pi \ \& \ \pi_1 \leq \pi$$

Semantics of history expressions

$$[[H \cdot H']]\pi = [[H]]\pi \cdot [[H']]\pi$$

$$[[H + H']]\pi = [[H]]\pi + [[H']]\pi$$

$$[[\mu h.H]]\pi = \bigcup_{n>0} f^n(\perp)$$

$$\text{where } f(X) = [[H]]\pi \{X / h\}$$

Example

$$H = \{r[\ell] \triangleright \{r'[\ell_1] \triangleright \alpha_1, r'[\ell_2] \triangleright \alpha_2\}, \\ r[\ell'] \triangleright \beta\}$$

$$\pi = r[\ell] \mid r'[\ell_2]$$

$$\begin{aligned} [[H]]^\pi &= [[\{r[\ell] \triangleright \{r'[\ell_1] \triangleright \alpha_1, r'[\ell_2] \triangleright \alpha_2\} \}]]^\pi \\ &\quad \cup [[\{r[\ell'] \triangleright \beta\}]]^\pi \\ &= [[\{r'[\ell_1] \triangleright \alpha_1, r'[\ell_2] \triangleright \alpha_2\}]]^\pi \\ &= [[\{r'[\ell_1] \triangleright \alpha_1\}]]^\pi \cup [[\{r'[\ell_2] \triangleright \alpha_2\}]]^\pi \\ &= [[\alpha_2]]^\pi = (? : \alpha_2) \end{aligned}$$

Example

$$H = \ell: \{r[\ell_1] \triangleright \ell_1: \alpha_1, r[\ell_2] \triangleright \ell_2: \alpha_2\} \cdot \beta$$

$$\pi = r[\ell_1]$$

$$\begin{aligned} [[H]]^\pi &= [[\{r[\ell_1] \triangleright \ell_1: \alpha_1, r[\ell_2] \triangleright \ell_2: \alpha_2\} \cdot \beta]]^\pi \{ \ell / ? \} \\ &= [[\{r[\ell_1] \triangleright \ell_1: \alpha_1, r[\ell_2] \triangleright \ell_2: \alpha_2\}]]^\pi \cdot (\ell: \beta) \\ &= [[\ell_1: \alpha_1]]^\pi \cdot (\ell: \beta) \\ &= (? : \alpha_1) \{ \ell_1 / ? \} \cdot (\ell: \beta) \\ &= (\ell: \beta, \ell_1: \alpha_1) \end{aligned}$$

Typing rules (1)

[T-Ev]

$$\Gamma, \alpha \vdash_e \alpha : 1$$

[T-Var]

$$\Gamma, \varepsilon \vdash_e x : \Gamma(x)$$

[T-Loc]

$$\frac{\Gamma, H \vdash_e e : \tau}{\Gamma, \ell : H \vdash e : \tau}$$

[T-Wk]

$$\frac{\Gamma, H \vdash_e e : \tau}{\Gamma, H+H' \vdash_e e : \tau}$$

Typing rules (2)

[T-Fr]

$$\frac{\Gamma, H \vdash_e e : \tau}{\Gamma, \varphi[H] \vdash_e \varphi[e] : \tau}$$

[T-If]

$$\frac{\Gamma, H \vdash_e e : \tau \quad \Gamma, H \vdash_e e' : \tau}{\Gamma, H \vdash_e \text{if } b \text{ then } e \text{ else } e' : \tau}$$

Typing rules (3)

[T-Abs]

$$\frac{\Gamma; x:\tau; z:\tau \xrightarrow{H} \tau', H \vdash_e e : \tau'}{\Gamma, \varepsilon \vdash_e \lambda_z x. e : \tau \xrightarrow{H} \tau'}$$

[T-App]

$$\frac{\Gamma, H \vdash_e e : \tau \xrightarrow{H''} \tau' \quad \Gamma, H' \vdash_e e' : \tau}{\Gamma, H \cdot H' \cdot H'' \vdash_e e e' : \tau'}$$

Typing Example (1)

$\alpha \vdash_e \alpha:1$

$? \vdash_e (\lambda y.zx)\beta:1$

$z:1 \xrightarrow{H} 1, \alpha+? \vdash_e \text{if } b \text{ then } \alpha \text{ else } (\lambda y.zx)\beta:1$

Typing Example (2)

$$\frac{\alpha \vdash_e \alpha:1 \quad \frac{\varepsilon \vdash_e (\lambda y.zx):1 \xrightarrow{H} 1 \quad \beta \vdash_e \beta:1}{H \cdot \beta \vdash_e (\lambda y.zx)\beta:1}}{z:1 \xrightarrow{H} 1, \alpha + H \cdot \beta \vdash_e \text{if } b \text{ then } \alpha \text{ else } (\lambda y.zx)\beta:1}$$

Typing Example (3)

$$\frac{\frac{\frac{x:1; z:1 \xrightarrow{H} 1, H \vdash_e zx:1}{\varepsilon \vdash_e (\lambda y.zx):1 \xrightarrow{H} 1} \quad \beta \vdash_e \beta:1}{\alpha \vdash_e \alpha:1 \quad H \cdot \beta \vdash_e (\lambda y.zx)\beta:1}}{z:1 \xrightarrow{H} 1, \alpha + H \cdot \beta \vdash_e \text{if } b \text{ then } \alpha \text{ else } (\lambda y.zx)\beta:1}$$

Typing Example (4)

$$\begin{array}{c}
 \frac{z:1 \xrightarrow{H} 1, \varepsilon \vdash_e z:1 \xrightarrow{H} 1 \quad x:1, \varepsilon \vdash_e x:1}{x:1; z:1 \xrightarrow{H} 1, \varepsilon \cdot \varepsilon \cdot H \vdash_e zx:1} \\
 \frac{\varepsilon \vdash_e (\lambda y. zx):1 \xrightarrow{H} 1 \quad \beta \vdash_e \beta:1}{\alpha \vdash_e \alpha:1 \quad \beta \cdot H \vdash_e (\lambda y. zx)\beta:1} \\
 \hline
 z:1 \xrightarrow{H} 1, \alpha + \beta \cdot H \vdash_e \text{if } b \text{ then } \alpha \text{ else } (\lambda y. zx)\beta:1
 \end{array}$$

Typing Example

$$z:1 \xrightarrow{H} 1, \alpha + \beta \cdot H \vdash_e \text{if } b \text{ then } \alpha \text{ else } (\lambda y. zx)\beta : 1$$

$$\varepsilon \vdash_e \lambda_z x. \text{if } b \text{ then } \alpha \text{ else } (\lambda y. zx)\beta : \tau \xrightarrow{H} \tau'$$

To use rule **[T-Abs]** the latent and actual effects must be unified, i.e. $H = \alpha + \beta \cdot H$

A history expression that satisfies the above is:

$$H = \mu h. \alpha + \beta \cdot h$$

Typing requests (an example)

We want to type at ℓ : $\text{req}_r \text{ int} \xrightarrow{\varphi[\]} \text{int}$

$$\ell_1 \quad \text{int} \xrightarrow{\alpha} \text{int}$$

$$\ell_2 \quad \text{int} \xrightarrow{\alpha \cdot \alpha} \text{int}$$

$$\ell_3 \quad \text{int} \xrightarrow{\alpha} \text{bool}$$

$$\varepsilon \mid\!-\!_{\ell} \text{req}_r \text{ int} \xrightarrow{\{ r[\ell_1] \triangleright \ell_1 : \varphi[\alpha], r[\ell_2] \triangleright \ell_2 : \varphi[\alpha \cdot \alpha] \}} \cdot} \text{int}$$

Typing rules (3)

[T-Req]

$$\tau = U \{ \rho +_{r[e]} \tau' \mid A \& B \& C \}$$

$$A \equiv \emptyset, \varepsilon \vdash_{\ell'} e : \tau' \quad B \equiv \rho \approx \tau'$$

$$C \equiv \ell < \ell' \{ e : \tau' \}$$

$$\Gamma, \varepsilon \vdash_{\ell} \text{req}_r \rho : \tau$$

Typing rules (3)

[T-Req]

certified interface

$$\frac{\begin{array}{l} \tau = U \{ \rho +_{r[e]} \tau' \mid A \& B \& C \} \\ A \equiv \emptyset, \varepsilon \vdash_{\ell'} e : \tau' \quad B \equiv \rho \approx \tau' \\ C \equiv \ell < \ell' \{ e : \tau' \} \end{array}}{\Gamma, \varepsilon \vdash_{\ell} \text{req}_r \rho : \tau}$$

Typing rules (3)

[T-Req]

compatible types

$$\tau = U \{ \rho +_{r[e]} \tau' \mid A \& B \& C \}$$

$$A \equiv \emptyset, \varepsilon \vdash_{\ell'} e : \tau' \quad B \equiv \rho \approx \tau'$$

$$C \equiv \ell < \ell' \{ e : \tau' \}$$

$$\Gamma, \varepsilon \vdash_{\ell} \text{req}_r \rho : \tau$$

Typing rules (3)

[T-Req]

$$\tau = U \{ \rho +_{r[e]} \tau' \mid A \& B \& C \}$$

$$A \equiv \emptyset, \varepsilon \vdash_{\ell'} e : \tau' \quad B \equiv \rho \approx \tau'$$

$$C \equiv \ell < \ell' \{ e : \tau' \} \quad \text{visibility}$$

$$\Gamma, \varepsilon \vdash_{\ell} \text{req}_r \rho : \tau$$

Certified published interfaces

$$\ell_1 \quad 1 \longrightarrow (1 \xrightarrow{\varphi[\alpha_r]} 1)$$

$\lambda x. \varphi[\alpha_r; \dots]$

$$\ell_2 \quad 1 \xrightarrow{\alpha_c} (1 \xrightarrow{\alpha_r \cdot \alpha_w} 1)$$

$\alpha_c; \lambda x. \alpha_r; \dots; \alpha_w$

$f = \text{req}_{r1}()$

$\text{req}_{r2}(f)$

$$\ell_3 \quad (1 \xrightarrow{h} 1) \xrightarrow{\alpha_c \cdot \varphi'[h]} 1$$

$\alpha_c; \varphi'[f()]$

$$\ell_4 \quad (1 \xrightarrow{h} 1) \xrightarrow{h} 1$$

$f()$

$$\frac{\Gamma, H \vdash_{\ell} e : \tau}{\Gamma, \ell : H \vdash e : \tau} \quad \text{if } e \text{ is published at } \ell$$

$$\Gamma, \varepsilon \vdash_{\ell} * : \textit{unit} \quad \Gamma, \alpha \vdash_{\ell} \alpha : \textit{unit} \quad \Gamma, \varepsilon \vdash_{\ell} x : \Gamma(x)$$

$$\frac{\Gamma, H \vdash_{\ell} e : \tau \xrightarrow{H''} \tau' \quad \Gamma, H' \vdash_{\ell} e' : \tau}{\Gamma, H \cdot H' \cdot H'' \vdash_{\ell} e e' : \tau}$$

$$\frac{\Gamma; x : \tau; z : \tau \xrightarrow{H} \tau', H \vdash_{\ell} e : \tau' \quad \Gamma, H \vdash_{\ell} e : \tau}{\Gamma, \varepsilon \vdash_{\ell} \lambda_{z x}. e : \tau \xrightarrow{H} \tau'} \quad \frac{\Gamma, H \vdash_{\ell} e : \tau \quad \Gamma, \varphi[H] \vdash_{\ell} \varphi[e] : \tau}{\Gamma, \varphi[H] \vdash_{\ell} \varphi[e] : \tau}$$

$$\frac{\tau = \mathbb{W}\{\rho \oplus_{\tau[\ell]} \tau' \mid \emptyset, \varepsilon \vdash_{\ell} e : \tau' \wedge \ell \preceq \ell'_{\{\varepsilon, \tau'\}} \wedge \rho \approx \tau'\}}{\Gamma, \varepsilon \vdash_{\ell} \text{req}_{\rho} : \tau}$$

$$\frac{\Gamma, H \vdash_{\ell} e : \tau \quad \Gamma, H \vdash_{\ell} e' : \tau}{\Gamma, H \vdash_{\ell} e : \tau} \quad \frac{\Gamma, H \vdash_{\ell} e : \tau \quad \Gamma, H + H' \vdash_{\ell} e : \tau}{\Gamma, H \vdash_{\ell} \text{if } b \text{ then } e \text{ else } e' : \tau}$$

Abstracting client behaviour

$$e_1 \quad 1 \xrightarrow{\varepsilon} (1 \xrightarrow{\varphi[\alpha_r]} 1)$$

$\lambda X. \varphi[\alpha_r; \dots]$

$$e_2 \quad 1 \xrightarrow{\alpha_c} (1 \xrightarrow{\alpha_r \cdot \alpha_w} 1)$$

$\alpha_c; \lambda X. \alpha_r; \dots; \alpha_w$

$f = \mathbf{req}_{r1}()$

$\mathbf{req}_{r2}(f)$

$$e_3 \quad (1 \xrightarrow{h} 1) \xrightarrow{\alpha_c \cdot \varphi'[h]} 1$$

$\alpha_c; \varphi'[f()]$

$$e_4 \quad (1 \xrightarrow{h} 1) \xrightarrow{h} 1$$

$f()$

$\{ r_1[e_1] \triangleright e_1: \varepsilon, r_1[e_2] \triangleright e_2: \alpha_c \} \cdot$

Abstracting client behaviour

$$\ell_1 \quad 1 \xrightarrow{\varepsilon} (1 \xrightarrow{\varphi[\alpha_r]} 1)$$

$\lambda x. \varphi[\alpha_r; \dots]$

$$\ell_2 \quad 1 \xrightarrow{\alpha_c} (1 \xrightarrow{\alpha_r \cdot \alpha_w} 1)$$

$\alpha_c; \lambda x. \alpha_r; \dots; \alpha_w$

$$\ell_3 \quad (1 \xrightarrow{h} 1) \xrightarrow{\alpha_c \cdot \varphi'[h]} 1$$

$\alpha_c; \varphi'[f()]$

$$\ell_4 \quad (1 \xrightarrow{h} 1) \xrightarrow{h} 1$$

$f()$

$f = \text{req}_{r1}()$

$\text{req}_{r2}(f)$

$\{ r_2[\ell_3] \triangleright \ell_3: \alpha_c \cdot \varphi'[\{ r_1[\ell_1] \triangleright \varphi[\alpha_r], r_1[\ell_2] \triangleright \alpha_r \cdot \alpha_w \}],$

$r_2[\ell_4] \triangleright \ell_4: \{ r_1[\ell_1] \triangleright \varphi[\alpha_r], r_1[\ell_2] \triangleright \alpha_r \cdot \alpha_w \} \}$

Summing up ...

Calculus: **operational semantics** and
type & effect system

- **effects** are history expressions, and over-approximate the actual execution histories
- **planned selections** therein hinder information about which plans to choose for secure compositions

What's next: the road to viable plans

- **linearization:** extracting plans and their “pure” effects by unscrambling the structure of history expressions
- **validity:** defining when an effect denotes histories that “*never go wrong*”
- **model checking:** valid plans are viable
 - transform **history expression** into BPAs
 - transform **policies** into FSAs
- **orchestrator:** uses viable plans to drive safe service composition

Which are the viable plans ?

$\{ r_1[\ell_1] \triangleright \ell_1: \varepsilon, r_1[\ell_2] \triangleright \ell_2: \alpha_c \} \cdot$

$\{ r_2[\ell_3] \triangleright \ell_3: \alpha_c \cdot \varphi'[\{ r_1[\ell_1] \triangleright \varphi[\alpha_r], r_1[\ell_2] \triangleright \alpha_r \cdot \alpha_w \}],$

$r_2[\ell_4] \triangleright \ell_4: \{ r_1[\ell_1] \triangleright \varphi[\alpha_r], r_1[\ell_2] \triangleright \alpha_r \cdot \alpha_w \} \}$

Difficult to tell: the planned selections are nested!

$\{ r_1[\ell_1] \mid r_2[\ell_3] \triangleright \ell_3: \alpha_c \cdot \varphi'[\varphi[\alpha_r]],$

viable

$\{ r_1[\ell_2] \mid r_2[\ell_4] \triangleright \ell_2: \alpha_c, \ell_4: \alpha_r \cdot \alpha_w,$

viable

$\{ r_1[\ell_1] \mid r_2[\ell_4] \triangleright \ell_4: \varphi[\alpha_r],$

not viable

$\{ r_1[\ell_2] \mid r_2[\ell_3] \triangleright \ell_2: \alpha_c, \ell_3: \alpha_c \cdot \varphi'[\alpha_r \cdot \alpha_w] \}$

not viable

Linearization

- transform H into an equivalent $H' \equiv H$ such that H' is in linear form, i.e.:

$$H' = \{\pi_1 \triangleright H_1 \cdot \dots \cdot \pi_k \triangleright H_k\}$$

and the H_i have no planned selections.

- defined through oriented equations \equiv that groups $r[\ell]$ in topmost position

Linearization

$$H \equiv \{0 \triangleright H\}$$

$$\{\pi_i \triangleright H_i\}_i \cdot \{\pi'_j \triangleright H'_j\}_j \equiv \{\pi_i \mid \pi'_j \triangleright H_i \cdot H'_j\}_{i,j}$$

$$\{\pi_i \triangleright H_i\}_i + \{\pi'_j \triangleright H'_j\}_j \equiv \{\pi_i \mid \pi_j \triangleright H_i + H'_j\}_{i,j}$$

$$\varphi[\{\pi_i \triangleright H_i\}_i] \equiv \{\pi_i \triangleright \varphi[H_i]\}_i$$

$$\mu h. \{\pi_i \triangleright H_i\}_i \equiv \{\pi_i \triangleright \mu h. H_i\}_i$$

$$\{\pi_i \triangleright \{\pi'_{i,j} \triangleright H_{i,j}\}_j\}_i \equiv \{\pi_i \mid \pi'_{i,j} \triangleright H_{i,j}\}_{i,j}$$

Example

H

$\varphi[\lambda_z x. \text{req}_r \rho; z x]$

ℓ_1

α

ℓ_2

β

$H = \varphi[\mu h. \{ r[\ell_1] \triangleright \alpha, r[\ell_2] \triangleright \beta \} \cdot h]$

Example

$$\begin{aligned} H &= \varphi[\mu h. \{ r[\ell_1] \triangleright \alpha, r[\ell_2] \triangleright \beta \} \cdot h] \\ &\equiv \varphi[\mu h. \{ r[\ell_1] \triangleright \alpha, r[\ell_2] \triangleright \beta \} \cdot \{ 0 \triangleright h \}] \\ &\equiv \varphi[\mu h. \{ r[\ell_1] \mid 0 \triangleright \alpha \cdot h, r[\ell_2] \mid 0 \triangleright \beta \cdot h \}] \\ &= \varphi[\mu h. \{ r[\ell_1] \triangleright \alpha \cdot h, r[\ell_2] \triangleright \beta \cdot h \}] \\ &\equiv \varphi[\{ r[\ell_1] \triangleright \mu h. \alpha \cdot h, r[\ell_2] \triangleright \mu h. \beta \cdot h \}] \\ &\equiv \{ r[\ell_1] \triangleright \varphi[\mu h. \alpha \cdot h], r[\ell_2] \triangleright \varphi[\mu h. \beta \cdot h] \} \end{aligned}$$

Simple vs multi-choice plans

With simple plans:

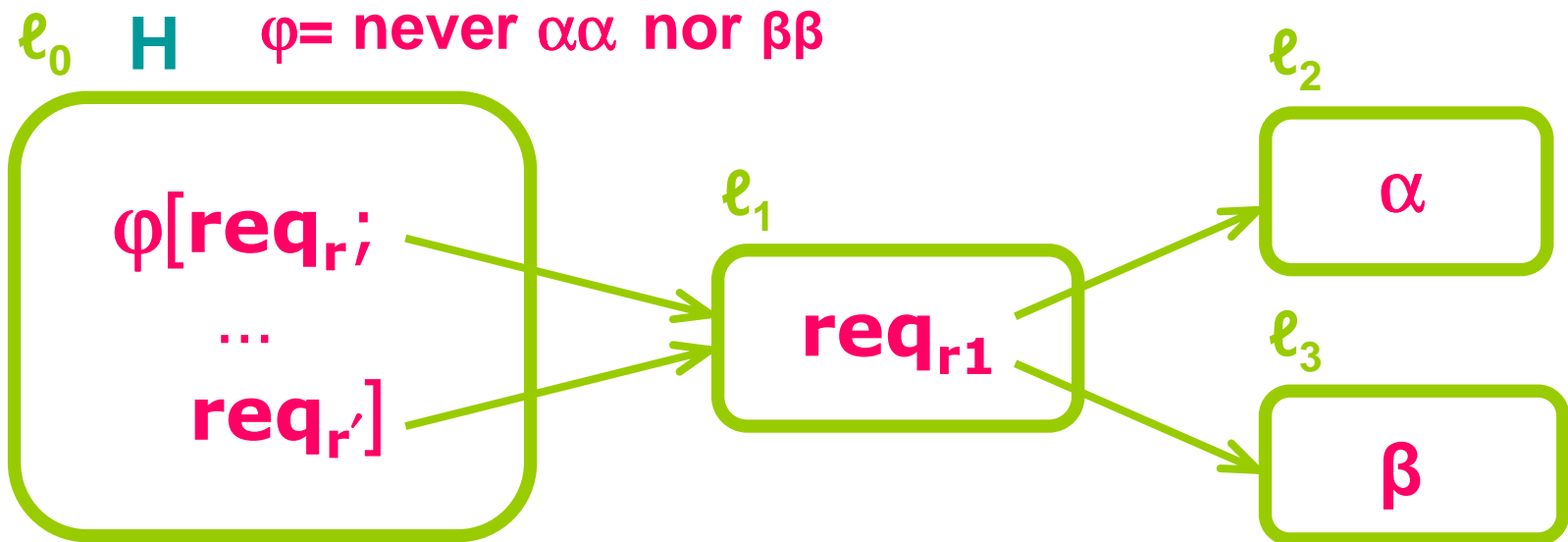
$$H \equiv \{ r[\ell_1] \triangleright \varphi[\mu h. \alpha \cdot h], r[\ell_2] \triangleright \varphi[\mu h. \beta \cdot h] \}$$

With multi-choice plans:

$$H \equiv \{ r[\ell_1] \triangleright \varphi[\mu h. \alpha \cdot h], r[\ell_2] \triangleright \varphi[\mu h. \beta \cdot h], \\ r[\ell_1, \ell_2] \triangleright \varphi[\mu h. (\alpha + \beta) \cdot h] \}$$

Plan $r[\ell_1, \ell_2]$ useful when ℓ_1 or ℓ_2 unavailable

Example: bottleneck service



$$H = \varphi[\{ r[\ell_1] \triangleright \{ r_1[\ell_2] \triangleright \alpha, r_1[\ell_3] \triangleright \beta \} } \} \cdot \{ r'[\ell_1] \triangleright \{ r_1[\ell_2] \triangleright \alpha, r_1[\ell_3] \triangleright \beta \} }]$$

Simple vs dependent plans

With simple plans:

$H \equiv \{ r[\ell_1] \mid r_1[\ell_2] \mid r'[\ell_1] \triangleright \varphi[\alpha \cdot \alpha],$

not viable

$r[\ell_1] \mid r_1[\ell_3] \mid r'[\ell_1] \triangleright \varphi[\beta \cdot \beta] \}$

not viable

With dependent plans:

$H \equiv \{ r[\ell_1, r_1[\ell_2]] \mid r'[\ell_1, r_1[\ell_2]] \triangleright \varphi[\alpha \cdot \alpha],$

not viable

$r[\ell_1, r_1[\ell_2]] \mid r'[\ell_1, r_1[\ell_3]] \triangleright \varphi[\alpha \cdot \beta],$

viable

$r[\ell_1, r_1[\ell_3]] \mid r'[\ell_1, r_1[\ell_2]] \triangleright \varphi[\beta \cdot \alpha],$

viable

$r[\ell_1, r_1[\ell_3]] \mid r'[\ell_1, r_1[\ell_3]] \triangleright \varphi[\beta \cdot \beta] \}$

not viable

Validity

- **histories** are enriched with $[_{\varphi}$ and $]_{\varphi}$ to point out the scope of policies.
- a **history** is **valid** when all the policies are respected, within their scopes
 - φ = you cannot write (α_w) after you have read (α_r)
 - ex: $\alpha_w \alpha_r [_{\varphi} \alpha_w]_{\varphi}$ not valid (write after read)
 - ex: $\alpha_w [_{\varphi} \alpha_r]_{\varphi} \alpha_w$ valid (write outside scope of φ)
- a history expression **H** is π -valid when all the histories in $[[\mathbf{H}]]$ ^{π} are valid.

Validity, formally

- **Safe sets:**

- $S(\varepsilon) = 0$ $S(\eta \ \alpha) = S(\eta)$
- $S(\eta_0 \ [_{\varphi} \ \eta_1 \]_{\varphi}) = S(\eta_0 \ \eta_1) \cup \varphi[\text{flat}(\eta_0) \ \text{flat} \ \text{pref}(\eta_1)]$

- **Example:**

$$\begin{aligned} S([_{\varphi} \ \alpha \ [_{\psi} \ \beta \]_{\psi} \ \gamma \]_{\varphi}) &= S(\alpha \ [_{\psi} \ \beta \]_{\psi} \ \gamma) \cup \varphi[\{\varepsilon, \alpha, \alpha\beta, \alpha\beta\gamma\}] \\ &= \Psi[\{\alpha, \alpha\beta\}], \varphi[\{\varepsilon, \alpha, \alpha\beta, \alpha\beta\gamma\}] \end{aligned}$$

- η is *valid* if, for each $\varphi[\{\eta_1, \dots, \eta_k\}]$ in $S(\eta)$:

$$\eta_i \models \varphi \quad \text{for } 1 \leq i \leq k$$

Verifying validity

Model checking: valid plans are viable
(drive executions that never go wrong)

- transform linearized **history expression** into **BPAs** (Basic Process Algebras)
- transform **policies** into **scoped policies** (in the form of Finite State Automata)

Basic Process Algebras **BPA**s

- A BPA **P** is a pair (p, Δ) where:

- **p** is a BPA process:

$$p, p' ::= 0 \mid \beta \mid p \cdot p' \mid p + p' \mid X$$

- Δ is a set of BPA definitions:

$$\{ X_1 = p_1 \dots X_k = p_k \}$$

- Standard LTS semantics. If $P = (p, \Delta)$

$$[[P]] = \{ \beta_1 \dots \beta_k \mid p \xrightarrow{\beta_1} p_1 \rightarrow \dots \xrightarrow{\beta_k} p_k \rightarrow \dots \}$$

- Example: $P = (X, \{X = \beta \cdot X\})$

$$X \rightarrow \beta \cdot X \xrightarrow{\beta} 0 \cdot X \rightarrow X \rightarrow \beta \cdot X \xrightarrow{\beta} \dots$$

From history expressions to BPAs

Example

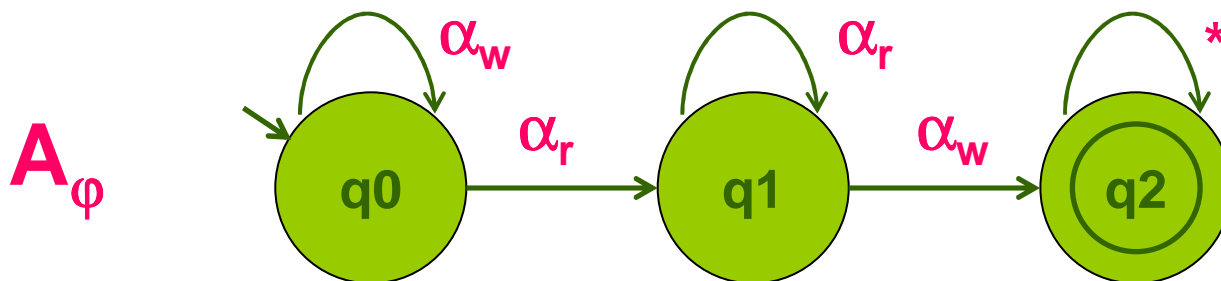
$$H = \beta \cdot (\mu h. \alpha + h \cdot h + \varphi[h])$$

$$\text{BPA}(H) = \beta \cdot X,$$
$$\{ X = \alpha + X \cdot X + [\varphi \cdot X \cdot]_{\varphi} \}$$

Theorem: $[[H]] = [[\text{BPA}(H)]]$

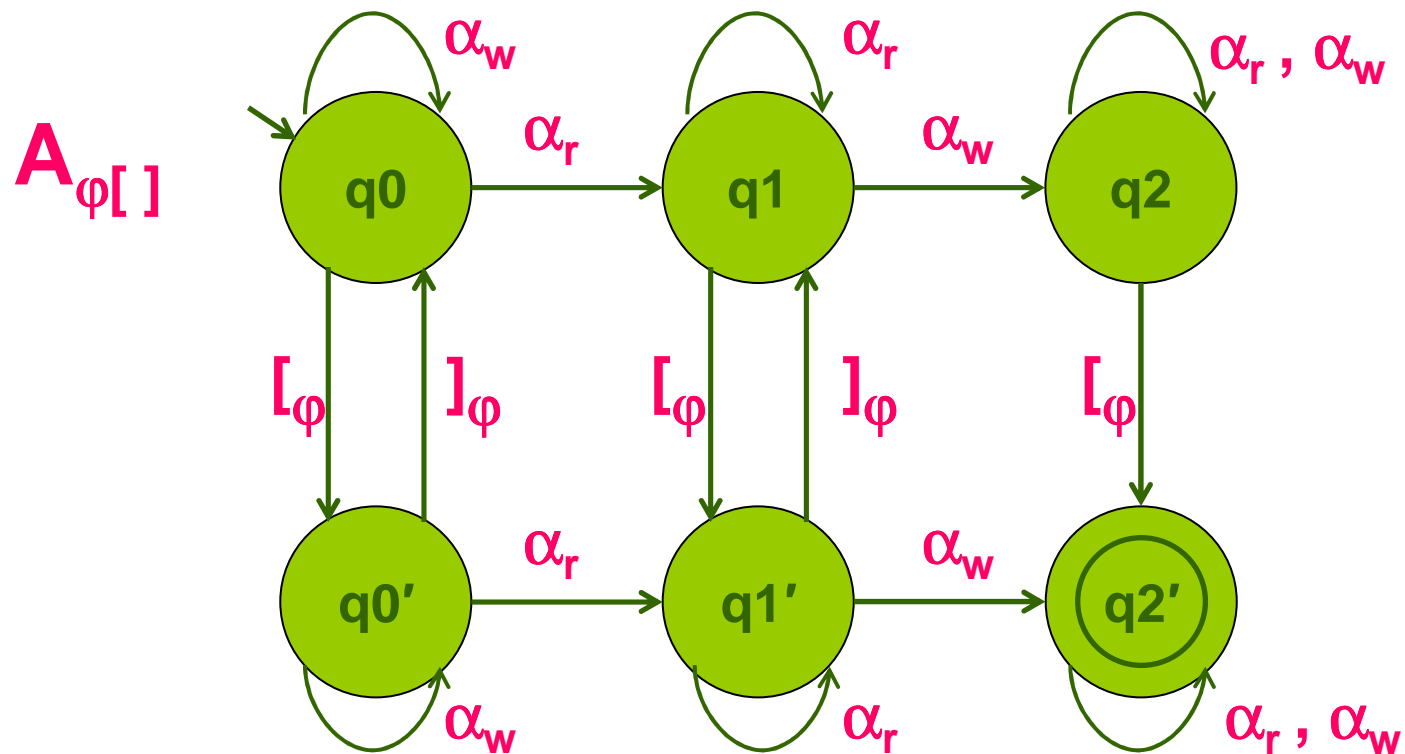
From policies to scoped policies

Example



Chinese Wall policy: no write after read

From policies to scoped policies



$\alpha_w L_\varphi \alpha_r \alpha_w$ not valid

From policies to scoped policies

Theorem:

η valid iff

η recognized by $A_{\varphi[\]}$
for all φ occurring in η

η w/o “redundant” framings $\varphi[\varphi[\dots]] = \varphi[\dots]$

Model- checking **BPA**s with **FSA**s

Theorem:

H valid iff

$$[[\text{BPA}(H)]] \models \bigwedge_{\varphi \text{ in } H} A_{\varphi}$$

Main result

Network $N = \ell_1\{e_1 : \tau_1\} \parallel \dots \parallel \ell_k\{e_k : \tau_k\}$

$0, H_i \vdash e_i : \tau_i$ for $1 \leq i \leq k$

If H_i is π -valid then π is viable for e_i

Summing up ...

- **hypothesis:** client with history expression H
- **linearization:** transform H into an equivalent H' in linear form, i.e.:

$$H' = \{\pi_1 \triangleright H_1 \cdots \pi_k \triangleright H_k\}$$

and the H_i have no planned selections.

- **verification:** model-check the H_i for validity
- **theorem:** if H_i is valid, then π_i is viable

Conclusions

A linguistic framework for secure service composition

- safety framings, policies, req-by-contract
- type & effect system
- verification of effects, to extract viable plans



The orchestrator securely composes and runs service-based applications

Other issues considered

- **instrumentation:** how to compile local policies into local checks, in case that some policy may fail
- **resource creation:** how to create fresh resources
- **liveness:** how to deal with properties of the form “something good will happen”
- **multi-choice and dependent plans**

Future work

- other kinds of plans (e.g. dynamic)
- other kinds of effects (e.g. sessions)
- safety framings and security protocols
- safety framings for information flow
- incremental analysis, when new services can be discovered at run-time
- trust relations between services
- spatial types and logics

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