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Rewriting Nested Graphs, through Term Graphs

Roberto Bruni, Andrea Corradini, Fabio Gadducci
Alberto Lluch Lafuente and Ugo Montanari

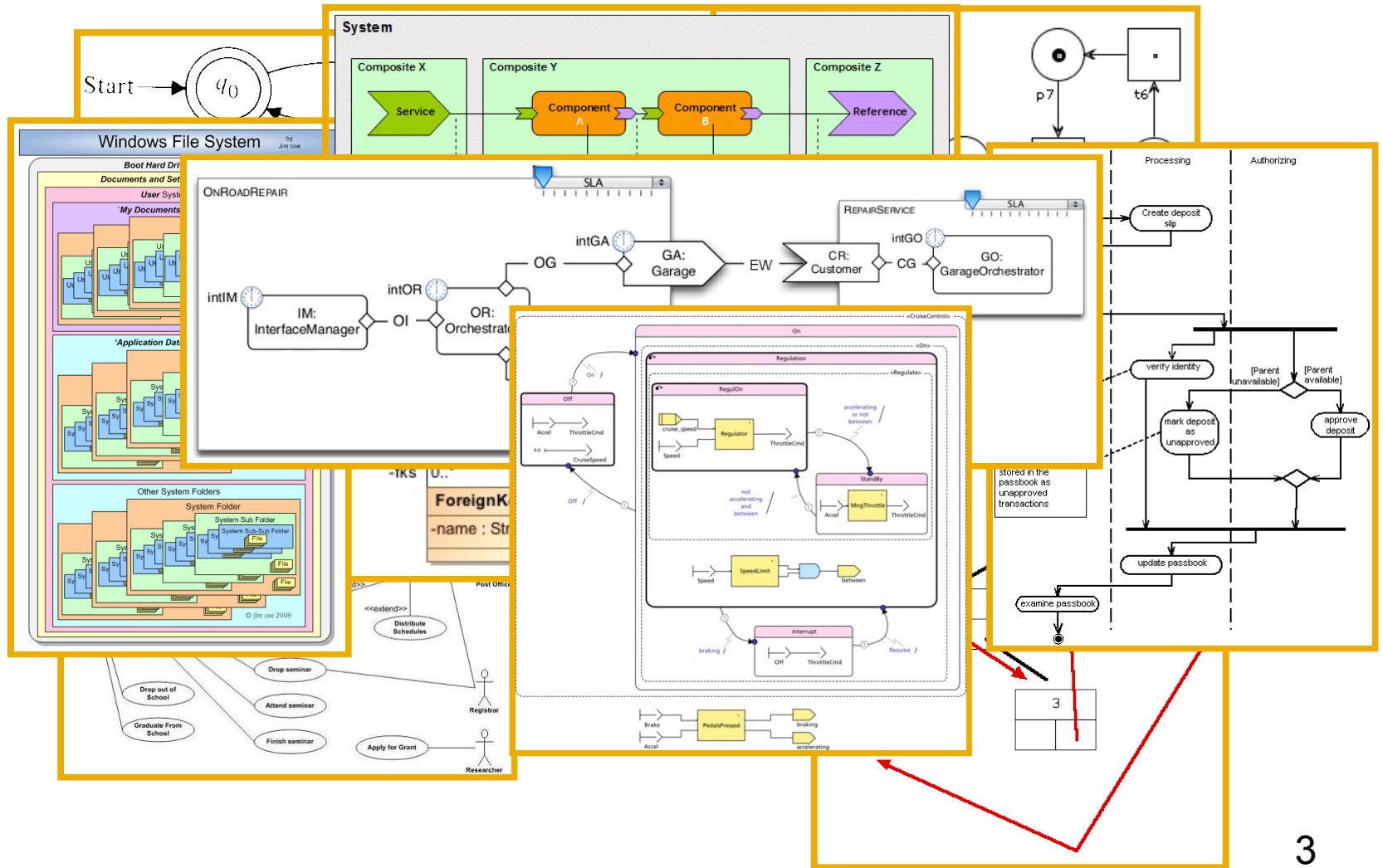
Dipartimento di Informatica, Pisa
IMT, Lucca

Outline

- Motivations: graphical modeling of process calculi (& other)
- A graph algebra as “intermediate language”
- Axiomatization of *NR-graphs* (graphs + nesting and restriction)
- Example: Encoding Ambient Calculus processes
 - This works for the *static part* of several calculi
- Extending the general approach to dynamics
- Encoding NR-graphs into Term Graphs: soundness, completeness and surjectivity on *well-scoped* term graphs
- Encoding Ambient Calculus rules as Term Graph rules
- What remains to be done...

Motivations: Graphs are everywhere

- Use of diagrams / graphs is pervasive to Computer Science



Graph-based approaches

- Some key features of graph-based approaches
 - help to convey ideas visually
 - ability to represent in a direct way relevant topological features
 - to make "links", "connection", "separation", ... explicit
 - ability to model systems at the “right” level of abstraction representing systems “up to isomorphism”
 - irrelevant details can be omitted (e.g. names of states in Finite State Automata, names of bound variables)
 - important body of theory available
 - Graph transformation approaches
 - DPO, SPO, SHR, ...
 - **Theory of parallelism/concurrency, unfolding, ...**
 - **Verification and analysis techniques**
 - Tools available

Encoding process calculi and the like: From algebraic to graph-based syntax

Algebraic

- ▶ Terms
 $a \mid b$
- ▶ Operations
 $\cdot : W \times W \rightarrow W$
- ▶ Axioms
 $x \mid y \equiv y \mid x$
- ▶ Rewrite rules
 $a \longrightarrow b$

elements

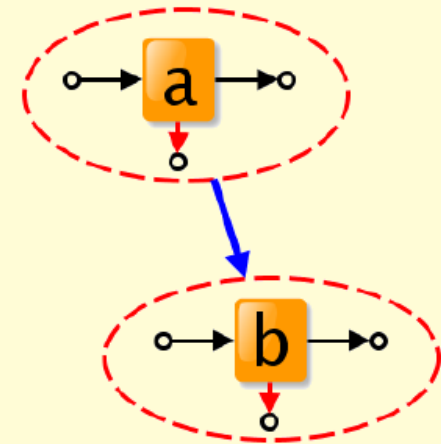
vocabulary

equivalence

dynamics

Graph-based

- ▶ Graphs (diagrams)
flat, hierarchical, etc.
- ▶ Graph compositions
Union, tensor, etc.
- ▶ Homomorphisms
isomorphism, etc.
- ▶ Transformation rules



Goal: **sound and complete encoding:**

given terms \mathbf{t} and \mathbf{s} ,

$[[\mathbf{t}]]$ is isomorphic to $[[\mathbf{s}]]$

iff

\mathbf{t} and \mathbf{s} are congruent

Main complication: the representation gap

Definition 15 (processes). Let \mathcal{U} be a set of names. A process P is a term generated by the syntax

$$\begin{aligned} P &::= 0 \mid M \mid (\nu a)P \mid P \mid P \\ M &::= M + M \mid A.P \end{aligned}$$

where $a, b \in \mathcal{U}$

Definition 15 (processes). Let \mathcal{U} be a set of names. A process P is a term generated by

grammar, structural congruence, etc.

very different syntax!

adjacency matrix, tuples, sets, morphisms

Definition 22 (bigraph)
where: $I = \langle m, X \rangle$ and

ordin
each
and 3

Definition 7
a triple $\langle E_G, \dots \rangle$
and $t_G : E_G \rightarrow \dots$

Let G, H be hypergraphs. A (hypergraph) morphism $f : G \rightarrow H$ is a pair of functions $f_E : E_G \rightarrow E_H, f_N : N_G \rightarrow N_H$ preserving the tentacle function.

$\tilde{I} = (V, ctrl, G^T, G^M) : I \rightarrow J$
ch combining a width (a finite

morphisms). A hypergraph G is
of edges, N_G is the set of nodes,

The proposed solution: graph algebras as intermediate language

Definition 15 (processes). Let \mathcal{U} be a set of names. A process P is a term generated by the syntax

$$P ::= \mathbf{0} \mid M \mid (\nu a)P \mid P \mid P$$

$$M ::= M + M \mid A.P$$

where $a, b \in \mathcal{U}$

Definition 17
generated by

where $a, b \in \mathcal{U}$

solution: graph algebras

$$\llbracket (\nu a)P \rrbracket_{\Gamma} = \begin{cases} \llbracket P \rrbracket_{\Gamma} & \text{if } a \notin \text{fn}(P) \\ (id_p \otimes \nu_c \otimes id_{\Gamma}) \circ \llbracket P\{c/a\} \rrbracket_{\{c\} \uplus \Gamma} & \text{otherwise} \end{cases}$$

$$\llbracket P \mid Q \rrbracket_{\Gamma} = \llbracket P \rrbracket_{\Gamma} \otimes \llbracket Q \rrbracket_{\Gamma} \quad \llbracket a(b).P \rrbracket_{\Gamma} = (in_{a,c} \otimes id_{\Gamma}) \circ \llbracket P\{c/b\} \rrbracket_{\{c\} \uplus \Gamma}$$

$$\llbracket \mathbf{0} \rrbracket_{\Gamma} = 0_p \otimes 0_{\Gamma} \quad \llbracket \bar{a}b.P \rrbracket_{\Gamma} = (out_{a,b} \otimes id_{\Gamma}) \circ \llbracket P \rrbracket_{\Gamma}$$

$$\llbracket \mathbf{0} \rrbracket_X = 1 \wedge X \quad \llbracket P \mid Q \rrbracket_X = \llbracket P \rrbracket_X \wedge \llbracket Q \rrbracket_X \quad \llbracket (x)P \rrbracket_X = \blacktriangle_x \circ \llbracket P \rrbracket_{X \uplus \{x\}}$$

$$\llbracket zx.P \rrbracket_X = \text{get}^{x,z} \circ \llbracket P \rrbracket_X \quad \llbracket \bar{z}x.P \rrbracket_X = \text{send}^{x,z} \circ \llbracket P \rrbracket_X \quad \text{where } x, z \in X$$

$$\llbracket (\nu a)P \rrbracket_n^s = \text{hide}_n(\llbracket P\{c/a\} \rrbracket_{n+1}^s) \quad \llbracket (j)P \rrbracket_n^s = \text{out}_{i,j,n}(\llbracket P \rrbracket_n^s)$$

$$\llbracket P \mid Q \rrbracket_n^s = \text{par}_n(\llbracket P \rrbracket_n^s, \llbracket Q \rrbracket_n^s) \quad \llbracket i(y).P \rrbracket_n^s = \text{in}_{i,n}(\llbracket P\{n+1/y\} \rrbracket_{n+1}^s)$$

$$\llbracket \mathbf{0} \rrbracket_n^s = \text{nil}_n \quad \llbracket M + N \rrbracket_n^s = \text{choice}_n(\llbracket M \rrbracket_n^s, \llbracket N \rrbracket_n^s)$$

Definition 22 (bigraph)

where: $I = (m, X)$ and $J = (n, Y)$
ordin
each
and 3

Definition 7

a triple $\langle E_G, N_G, t_G \rangle$ such that E_G is the set of edges, N_G is the set of nodes, and $t_G : E_G \rightarrow N_G^*$ is the tentacle function.

Let G, H be hypergraphs. A (hypergraph) morphism $f : G \rightarrow H$ is a pair of functions $f_E : E_G \rightarrow E_H$, $f_N : N_G \rightarrow N_H$ preserving the tentacle function.

similar syntax

one to one

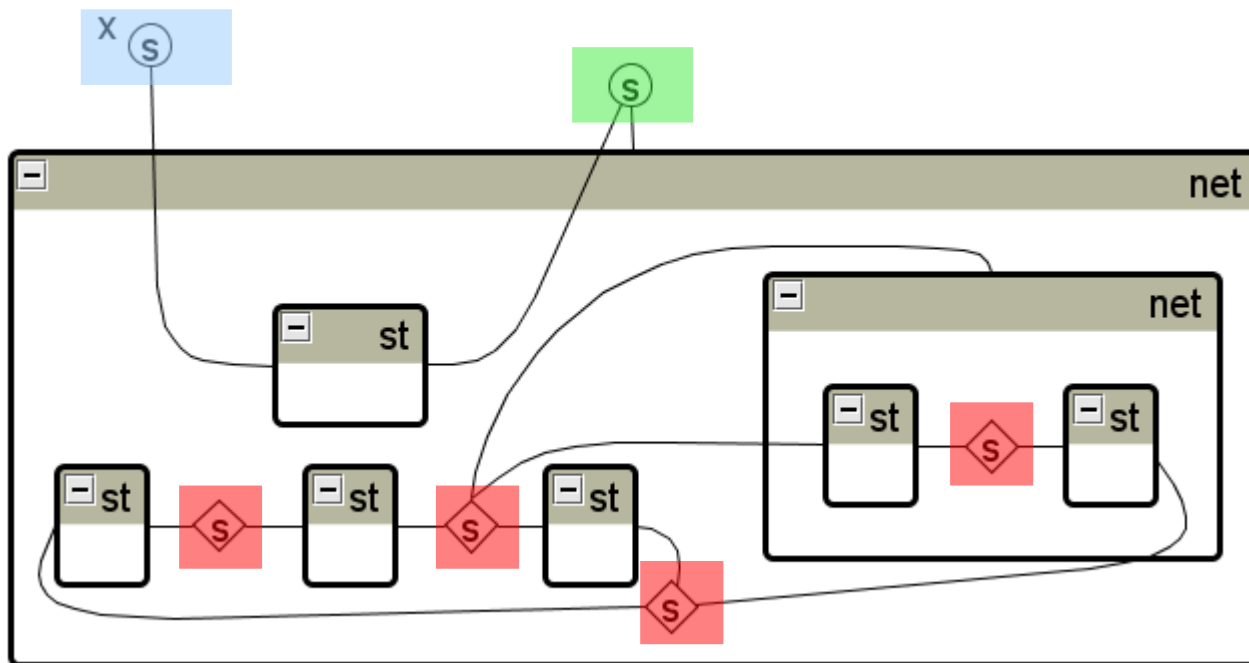
From graphs to graph algebras

- Start with a given class (category?) of graphs
- Define an equational signature,
 - operators correspond to operations on graphs
 - axioms describe their properties
- Prove *once and for all* soundness and completeness of the axioms with respect to the interpretation on graphs, as well as surjectivity
- Next, you can safely use the algebra as an alternative, more handy syntax for the graphs

Graphs with nesting and restriction (NR-graphs)

Hypergraphs where

- hyperedges may contain nested graphs
- nodes can be **global**, **globally restricted**, or **locally restricted**
- locally restricted nodes cannot be accessed “from outside”
- isomorphisms preserve names of free nodes



NR-graphs: the formal definition

[for Fernando only...]

Definition 1 (NR-graphs). An NR-graph $G \in \mathbf{NR-Graph}$ is a tuple $G = \langle FN, GR, H \rangle$, where FN is a set of free nodes, GR is a set of globally restricted nodes with $FN \cap GR = \emptyset$, and $H \in \mathbf{NR-Graph}[FN \cup GR]$. The set of global nodes of G is given by $FN \cup GR$.

An NR-graph H with external nodes X , $H \in \mathbf{NR-Graph}[X]$, is a tuple $H = \langle LR, E, l, c, \rho \rangle$, where LR is a set of locally restricted nodes (satisfying $LR \cap X = \emptyset$), E is a set of (hyper-)edges, $l: E \rightarrow B$ labels each edge with an element of B , $c: E \rightarrow (X \cup LR)^*$ is the connection function (satisfying $\tau(c(e)) = \text{rnk}(l(e))$ for all $e \in E$), and $\rho: E \rightarrow \mathbf{NR-Graph}[X \cup LR]$ maps each edge to a graph nested within it.

The Algebra of Graphs with Nesting: Axioms

$$\mathbb{G} ::= \mathbf{0} \mid x : s \mid b[\mathbb{G}](\bar{y}) \mid \mathbb{G} \mid \mathbb{G} \mid (\nu x : s)\mathbb{G} \mid (\mu x : s)\mathbb{G}$$

$$\mathbb{G} \mid \mathbb{H} \equiv \mathbb{H} \mid \mathbb{G} \quad (\text{A1})$$

$$\mathbb{G} \mid (\mathbb{H} \mid \mathbb{I}) \equiv (\mathbb{G} \mid \mathbb{H}) \mid \mathbb{I} \quad (\text{A2})$$

$$\mathbb{G} \mid \mathbf{0} \equiv \mathbb{G} \quad (\text{A3})$$

$$(\omega_1 x : s)(\omega_2 y : t)\mathbb{G} \equiv (\omega_2 y : t)(\omega_1 x : s)\mathbb{G} \quad \text{if } x : s \neq y : t \quad (\text{A4})$$

$$(\omega x : s)\mathbf{0} \equiv (\omega x : s)x : s \quad (\text{A5})$$

$$\mathbb{G} \mid (\omega x : s)\mathbb{H} \equiv (\omega x : s)(\mathbb{G} \mid \mathbb{H}) \quad \text{if } x : s \notin \text{fn}(\mathbb{G}) \quad (\text{A6})$$

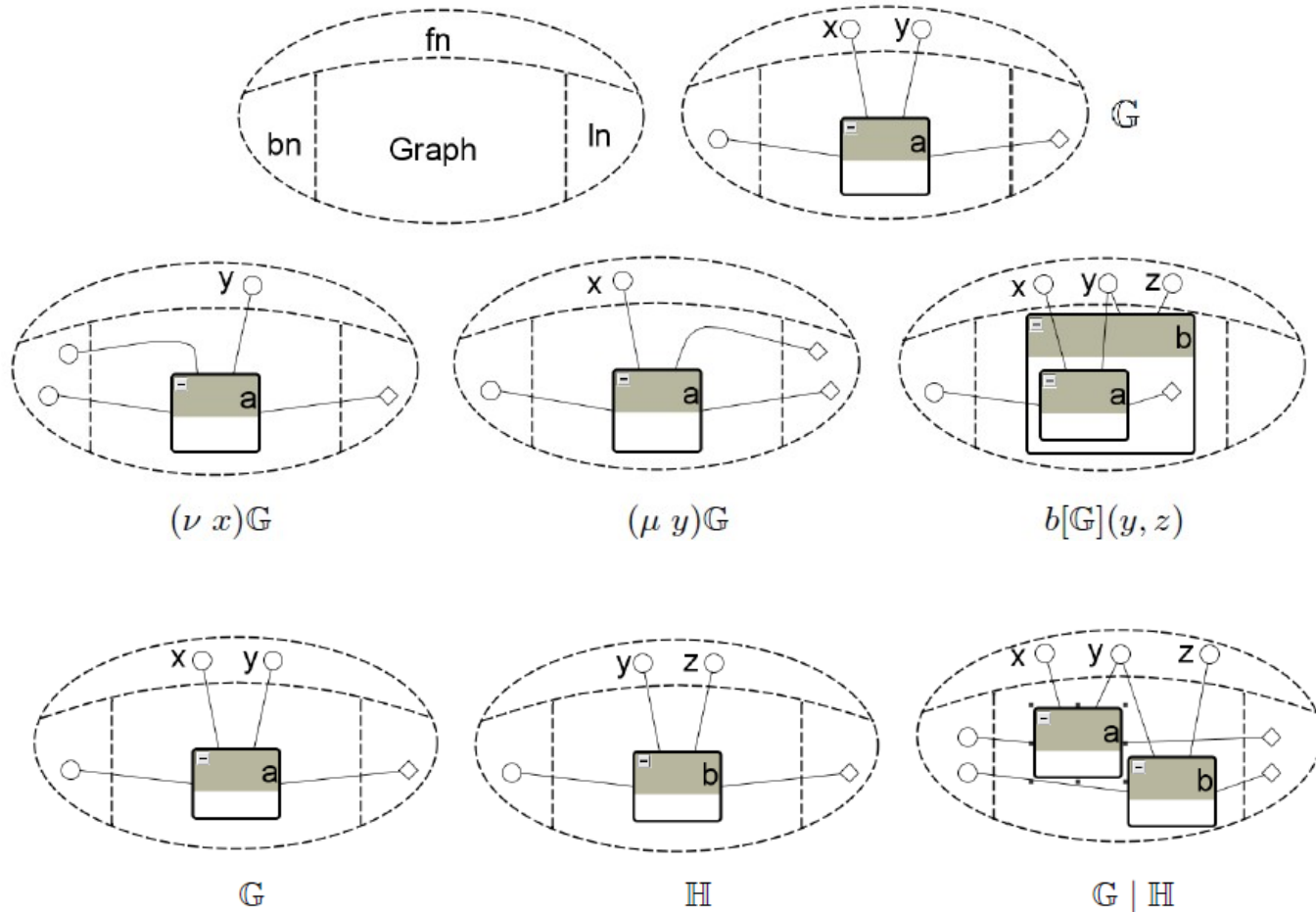
$$(\omega x : s)\mathbb{G} \equiv (\omega y : s)(\mathbb{G}\{y:s/x:s\}) \quad \text{if } y : s \notin \text{fn}(\mathbb{G}) \quad (\text{A7})$$

$$b[(\nu x : s)\mathbb{G}](\bar{y}) \equiv (\nu x : s)b[\mathbb{G}](\bar{y}) \quad \text{if } x : s \notin |\bar{y}| \quad (\text{A8})$$

$$x : s \mid \mathbb{G} \equiv \mathbb{G} \quad \text{if } x : s \in \text{fn}(\mathbb{G}) \quad (\text{A9})$$

$$b[x : s \mid \mathbb{G}](\bar{y}) \equiv x : s \mid b[\mathbb{G}](\bar{y}) \quad (\text{A10})$$

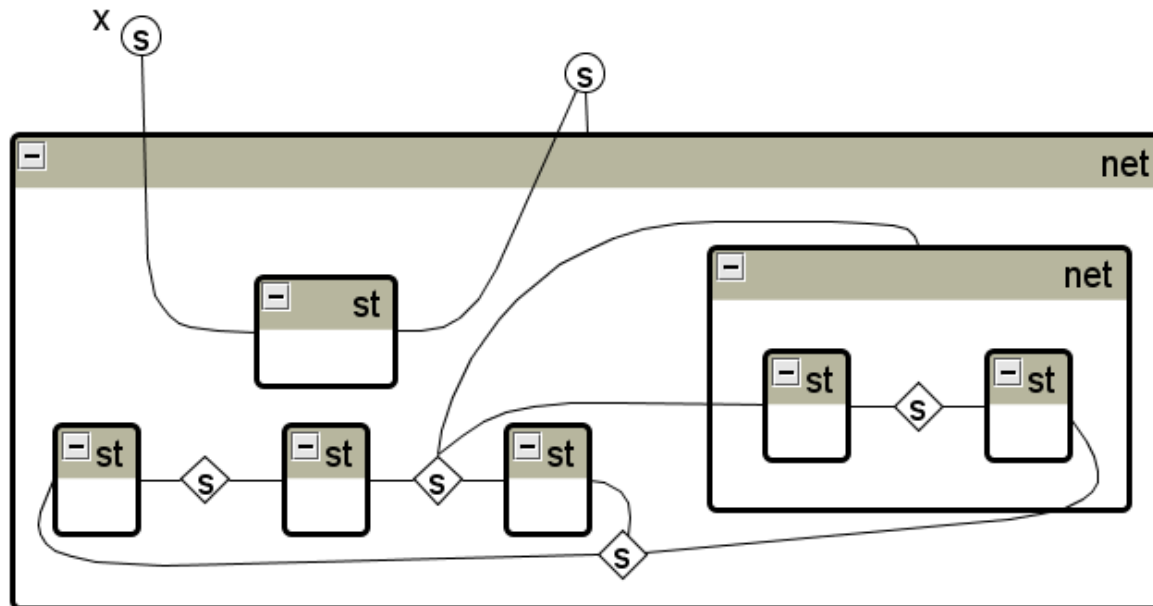
From terms of AGN to NR-graphs, informally



Properties of the axiomatization

- The axiomatization of NR-graphs is **sound**, **complete** and **surjective**
- An AGN term and the corresponding NR-graph:

$$(\nu y)\text{net}[\text{st}(x, y) \mid (\mu z_1, z_2, z_3)(\text{st}(z_3, z_1) \mid \text{st}(z_1, z_2) \mid \text{st}(z_2, z_3) \mid \text{net}[(\mu z_4)(\text{st}(z_2, z_4) \mid \text{st}(z_4, z_3))](z_2))](y)$$



The simplest example: encoding the Ambient Calculus as AGN terms

- The syntax of the Ambient Calculus:

$$\begin{aligned} P & ::= \mathbf{0} \mid (\nu n)P \mid P \mid P \mid M.P \mid n[P] \\ M & ::= \text{in } n \mid \text{out } n \mid \text{open } n \end{aligned}$$

- box labels: “[]” for ambients; **M.P** for each process $M.P$

$$\begin{aligned} \llbracket \mathbf{0} \rrbracket & \stackrel{\text{def}}{=} \mathbf{0} \\ \llbracket M.P \rrbracket & \stackrel{\text{def}}{=} \underline{M.P}[\mathbf{0}] \overrightarrow{(fn(M.P))} \\ \llbracket n[P] \rrbracket & \stackrel{\text{def}}{=} \llbracket \] \llbracket [P] \rrbracket (n) \\ \llbracket P \mid Q \rrbracket & \stackrel{\text{def}}{=} \llbracket P \rrbracket \mid \llbracket Q \rrbracket \\ \llbracket (\nu w)P \rrbracket & \stackrel{\text{def}}{=} (\nu w)\llbracket P \rrbracket \end{aligned}$$

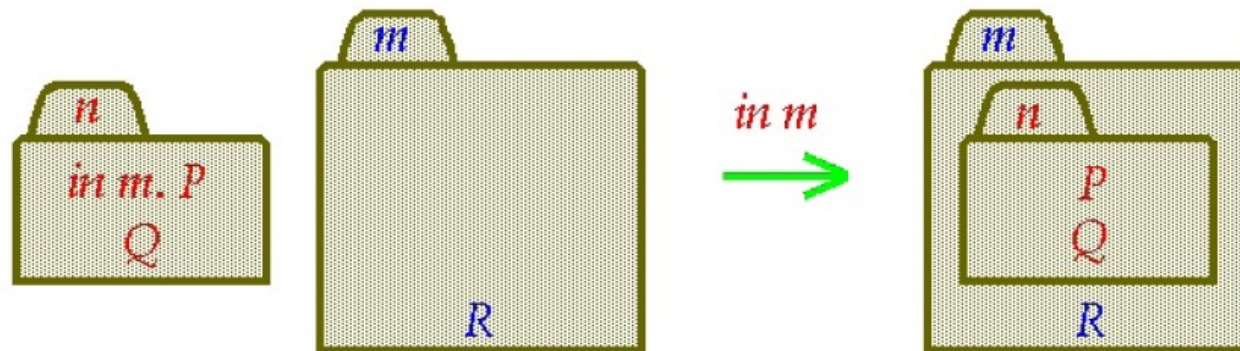
- We get automatically a representation of processes as NR-graphs

But what about the dynamics?

Reduction rules for the Ambient Calculus

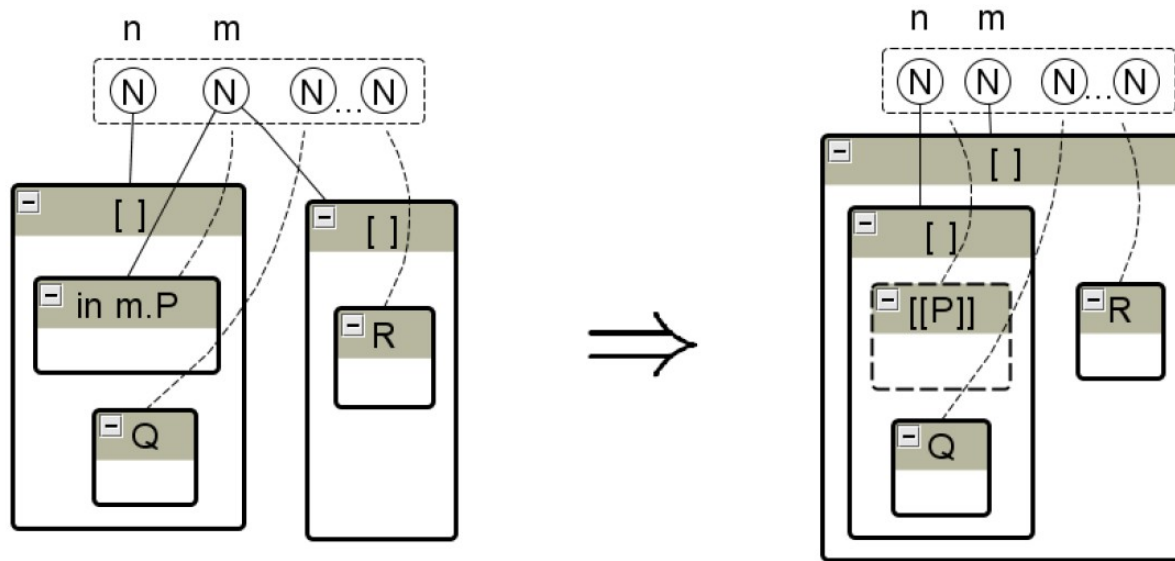
- (1) $n[\text{in } m.P \mid Q] \mid m[R] \Rightarrow m[n[P \mid Q] \mid R]$ (*Red In*)
- (2) $m[n[\text{out } m.P \mid Q] \mid R] \Rightarrow n[P \mid Q] \mid m[R]$ (*Red Out*)
- (3) $\text{open } n.P \mid n[Q] \Rightarrow P \mid Q$ (*Red Open*)

A graphical intuition:



The in-rule, seen as pair of NR-graphs

$$n[\text{in } m.P \mid Q] \mid m[R] \Rightarrow m[n[P \mid Q] \mid R] \quad (\text{Red In})$$



NR-graph rewriting needs to be formalized:

- role of R, Q and P
- meaning of $[[P]]$
- rule or *rule schema*?
- definition of matching?
- what is preserved?
- applicability?

Defining NR-graph rewriting: possible approaches

- Define from scratch rules, matches, rewriting (e.g. according to DPO approach), identify conditions for parallel/sequential independence, prove results about parallelism...
- Show that NR-graphs, equipped with suitable morphism, form an adhesive category (or a variation of it) and exploit general results.
- Embed NR-graphs into a known category of graphs, and work there, exploiting the existing results...
 - we embed NR-graphs into **Term Graphs**
 - many-sorted terms with sharing
 - acyclic hypergraphs (edges labeled by operators) with node indegree ≤ 1
 - it is a **quasi-adhesive** category, but the interesting results are not very interesting...

Encoding NR-graphs into Term Graphs

- Basic idea: add a new node sort for *locations*
 - every hyperedge and locally restricted node is attached to a location
 - every hyperedge *offers* a location (its interior)
 - locations form a tree
- We exploit an existing axiomatization of Term Graphs, as arrows of gs-monoidal theories.

$$\begin{array}{ccc} \mathbf{AGN}(S, B) / \equiv_{\mathcal{A}} & \longleftrightarrow & \text{NR-Graphs over } (S, B) \\ \text{Sec. 4} \downarrow & & \text{Sec. 5} \downarrow \\ \mathbf{GS}(\Sigma_B^\bullet) & \xleftarrow{[10]} & \text{Term Graphs over } \Sigma_B^\bullet \end{array}$$

GS-monoidal theory: an axiomatization of term graphs

$$\begin{array}{l}
 \text{(op)} \frac{f \in \Sigma_{u,s}}{f : u \rightarrow s} \quad \text{(id)} \frac{u \in S^*}{id_u : u \rightarrow u} \quad \text{(bang)} \frac{u \in S^*}{!_u : u \rightarrow \epsilon} \quad \text{(dup)} \frac{u \in S^*}{\nabla_u : u \rightarrow uu} \\
 \text{(sym)} \frac{u, v \in S^*}{\rho_{u,v} : uv \rightarrow vu} \quad \text{(seq)} \frac{t : u \rightarrow v \quad t' : v \rightarrow w}{t; t' : u \rightarrow w} \quad \text{(par)} \frac{t : u \rightarrow v \quad t' : u' \rightarrow v'}{t \otimes t' : uu' \rightarrow vv'}
 \end{array}$$

Definition 11 (gs-monoidal theory). Given a signature Σ over a set of sorts S , the associated gs-monoidal theory $\mathbf{GS}(\Sigma)$ is the category whose objects are the elements of S^* , and whose arrows are equivalence classes of gs-monoidal terms, i.e., terms generated by the inference rules in Fig. 6 subject to the following con – identities and sequential composition satisfy the axioms of categories:

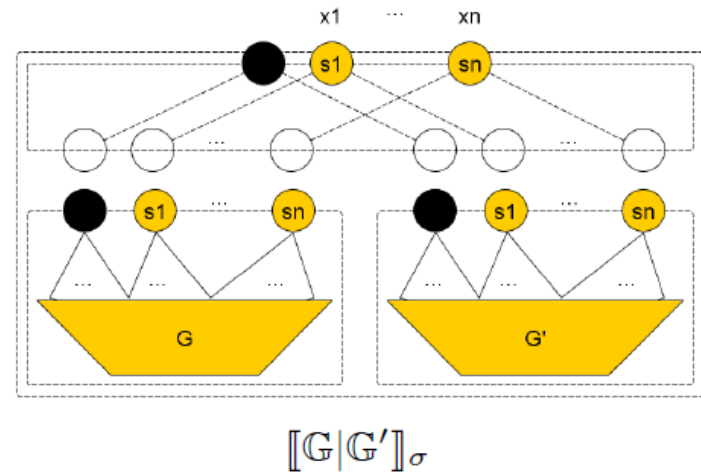
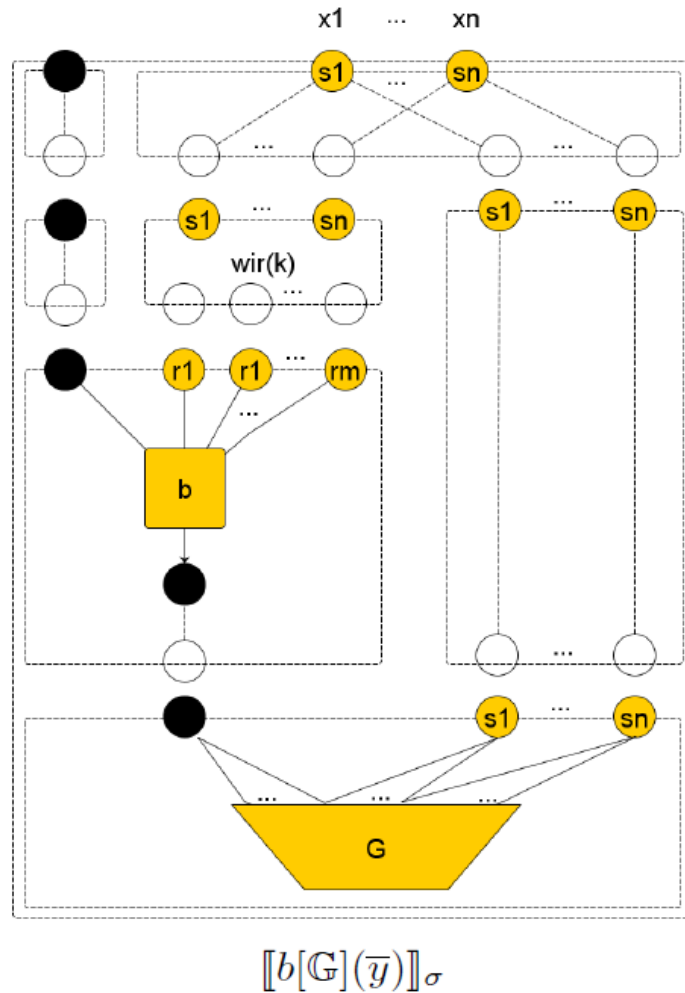
- [identity] $id_u ; t = t = t ; id_v$ for all $t : u \rightarrow v$;
- [associativity] $t_1 ; (t_2 ; t_3) = (t_1 ; t_2) ; t_3$ whenever any side is defined,
- \otimes is a monoidal functor with unit id_ϵ , i.e. it satisfies:
 - [functoriality] $id_{uv} = id_u \otimes id_v$, and
 - $(t_1 \otimes t_2) ; (t'_1 \otimes t'_2) = (t_1 ; t'_1) \otimes (t_2 ; t'_2)$ whenever both sides are defined,
 - [monoid] $t \otimes id_\epsilon = t = id_\epsilon \otimes t \quad t_1 \otimes (t_2 \otimes t_3) = (t_1 \otimes t_2) \otimes t_3$
- ρ is a natural transformation, i.e. it satisfies:
 - [naturality] $(t \otimes t') ; \rho_{v,v'} = \rho_{u,u'} ; (t' \otimes t)$ for all $t : u \rightarrow v$ and $t' : u' \rightarrow v'$ and furthermore it satisfies:
 - [symmetry] $(id_u \otimes \rho_{v,w}) ; (\rho_{u,w} \otimes id_v) = \rho_{u \otimes v, w} \quad \rho_{u,v} ; \rho_{v,u} = id_{u \otimes v}$
 - $\rho_{\epsilon,u} = \rho_{u,\epsilon} = id_u$
- ∇ and $!$ satisfy the following axioms:
 - [unit] $!_\epsilon = \nabla_\epsilon = id_\epsilon$
 - [duplication] $\nabla_u ; (id_u \otimes \nabla_u) = \nabla_u ; (\nabla_u \otimes id_u) \quad \nabla_u ; (id_u \otimes !_u) = id_u$
 - $\nabla_u ; \rho_{v,u} = \nabla_u$
 - [monoidality] $\nabla_{uv} ; (id_u \otimes \rho_{v,u} \otimes id_v) = \nabla_u \otimes \nabla_v \quad !_uv = !_u \otimes !_v$

Encoding AGN into Term Graphs

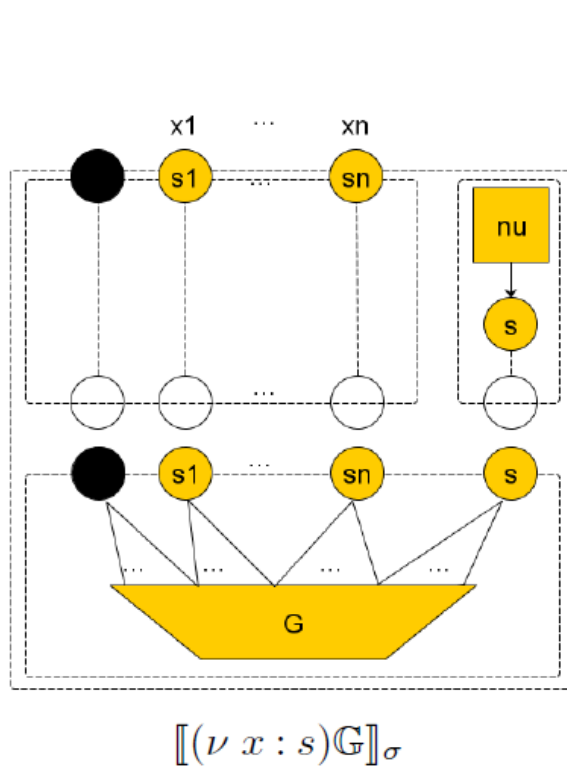
Inductive encoding from AGN terms to gs-monoidal terms

- $[[\mathbf{0}]]_\sigma = [!_{\bullet, \tau(\sigma)}] : \bullet, \tau(\sigma) \rightarrow \epsilon$
- $[[x : s]]_\sigma = [!_{\bullet, \tau(\sigma)}] : \bullet, \tau(\sigma) \rightarrow \epsilon$
- $[[\mathbb{G}|\mathbb{G}']]_\sigma = [\nabla_{\bullet, \tau(\sigma)}] ; [[\mathbb{G}]]_\sigma \otimes [[\mathbb{G}']]_\sigma : \bullet, \tau(\sigma) \rightarrow \epsilon$
- $[[\nu x : s]\mathbb{G}]]_\sigma = [id_{\bullet, \tau(\sigma)} \otimes \nu_s] ; [[\mathbb{G}\{y:s/x:s\}]]_{\sigma, y:s} : \bullet, \tau(\sigma) \rightarrow \epsilon$
where $y : s = \text{fresh}_{\mathbb{G}}(x : s, \sigma)$
- $[[\mu x : s]\mathbb{G}]]_\sigma = [(\nabla_{\bullet} ; id_{\bullet} \otimes \mu_s) \otimes id_{\tau(\sigma)}] ; [[\mathbb{G}\{y:s/x:s\}]]_{y:s, \sigma} : \bullet, \tau(\sigma) \rightarrow \epsilon$
where $y : s = \text{fresh}_{\mathbb{G}}(x : s, \sigma)$

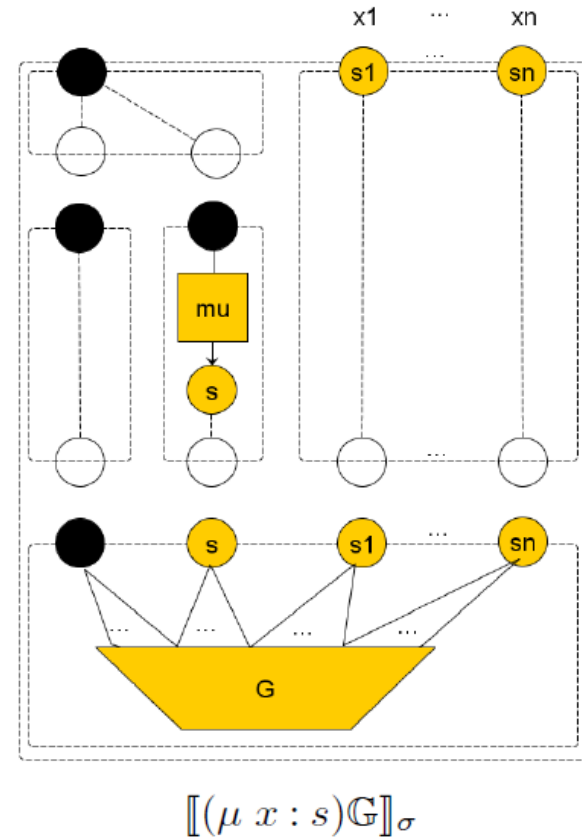
Encoding AGN into Term Graphs, graphically



Encoding AGN into Term Graphs, graphically



$[(\nu x : s)G]_\sigma$



$[(\mu x : s)G]_\sigma$

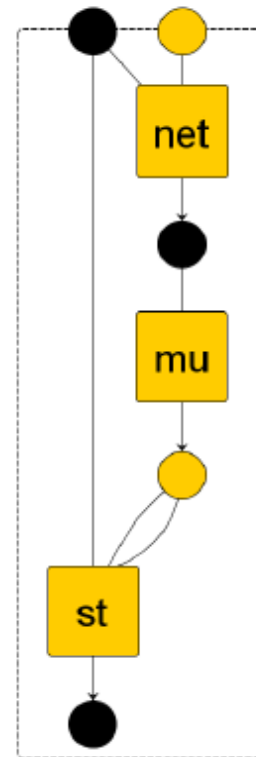
Properties of the encoding

Correct

Complete

Surjective onto **well-scoped** term graphs

A badly scoped term graph:
edge **st** accesses a node locally
restricted in a sibling edge **net**

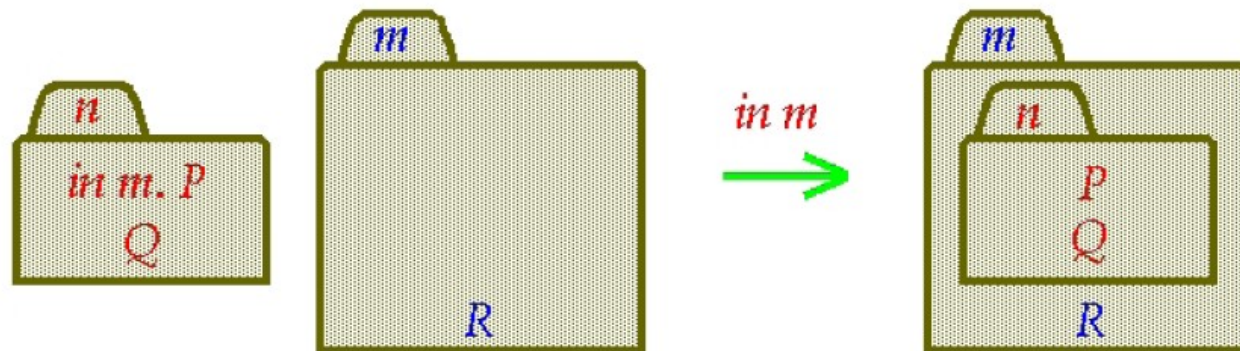


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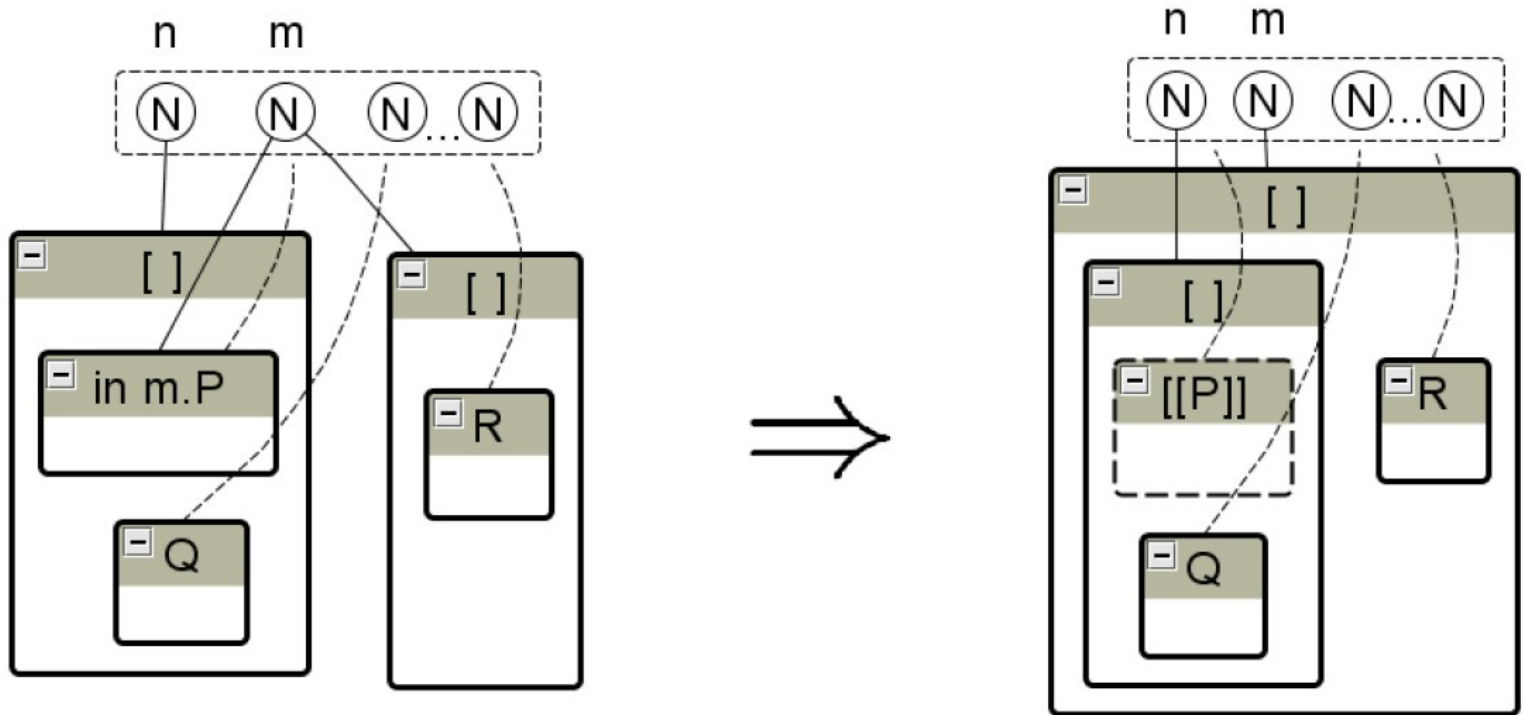
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A graphical intuition:



Back to the Ambient Calculus in-rule

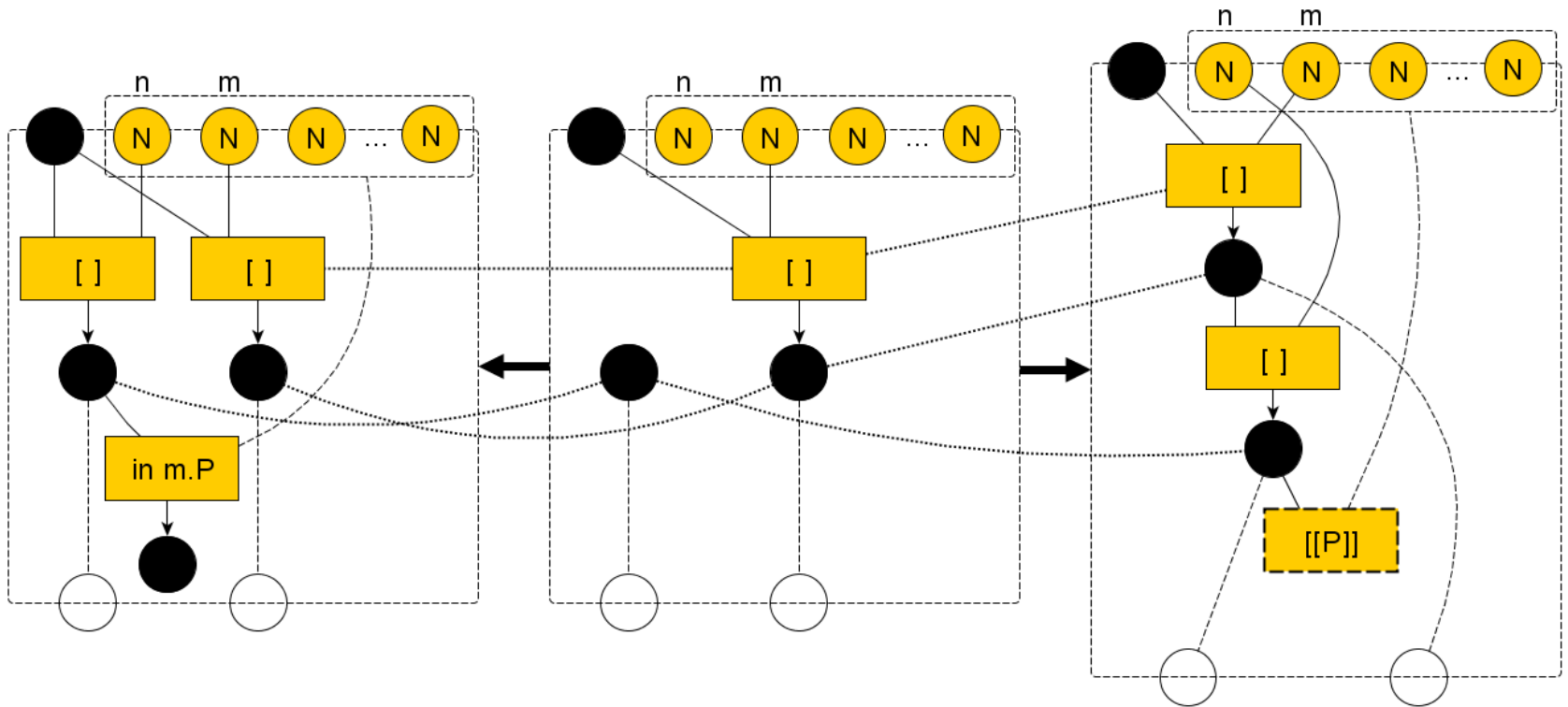
$$n[\text{in } m.P \mid Q] \mid m[R] \Rightarrow m[n[P \mid Q] \mid R] \quad (\text{Red In})$$



Let us translate it into term graphs

The in-rule, seen as Term Graph rule

$$n[\text{in } m.P \mid Q] \mid m[R] \Rightarrow m[n[P \mid Q] \mid R] \quad (\text{Red In})$$



The more formalized framework allows to

- identify the parts of the state that are preserved
- give a precise meaning to R and Q

Ongoing work

- Prove that the encoding of Ambient Calculus rules is correct
 - well-scopedness is preserved
 - rewrite steps are one-to-one with reductions
- Identify conditions on rules/matches that allow for the parallel application of rules, and thus for unfolding...
 - known results are too weak
 - Term Graphs are quasi-adhesive, but regular monos
 - are monos which preserve “variables”
 - you cannot even model rule $\mathbf{a} \Rightarrow \mathbf{b}$
 - look for weaker conditions of applicability of Church-Rosser theorem
 - characterization of Van Kampen squares in Term Graphs

Conclusions

- A methodological approach for the graphical representation of process calculi and other computational formalisms
- **Static part:** *Using graph algebras as intermediate language*
 - Correct and complete axiomatization of class of graphs with nesting and restriction
 - Encoding of process terms into the graph algebra
 - Applied to π -calculus, Sagas, CaSPiS,...
- **Dynamics:** *Encode NR-graphs into Term Graphs*
 - Characterize conditions for parallel application of rules [existing ones are too weak]
 - Exploit concurrent semantics of graph rewriting
 - unfolding techniques
 - analysis and verification