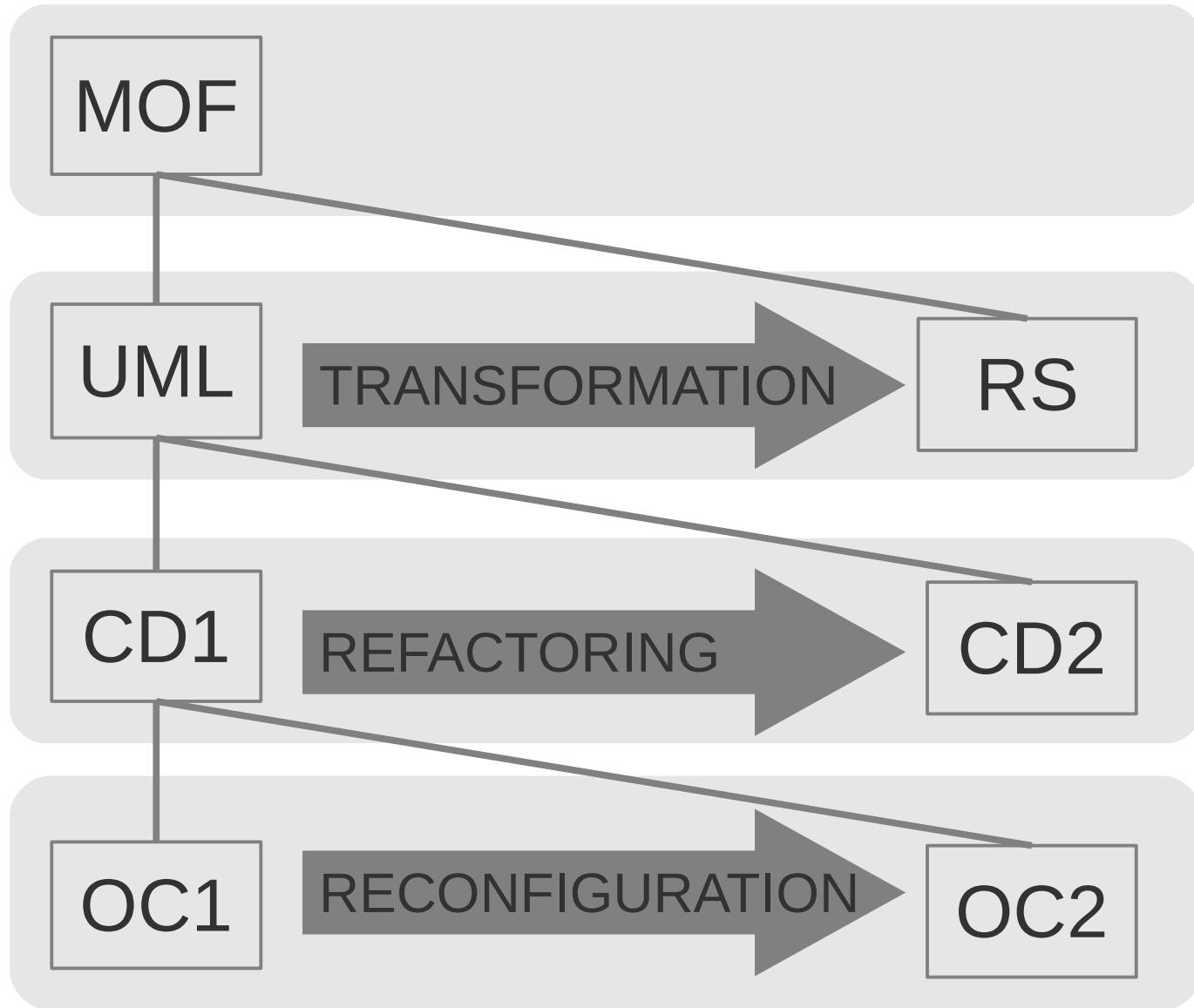


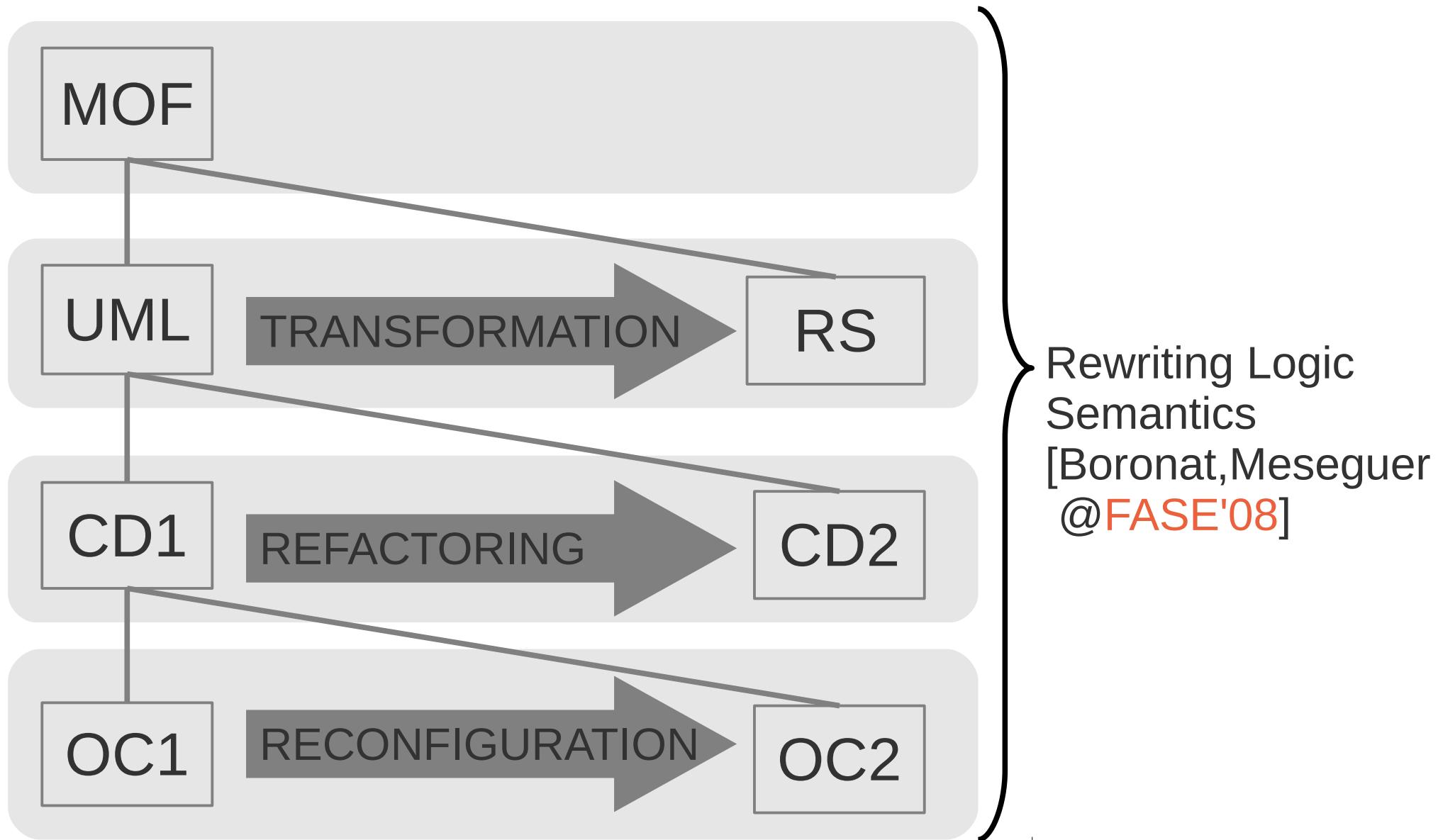
# Exploiting the hierarchical structure of rule-based specifications for decision planning

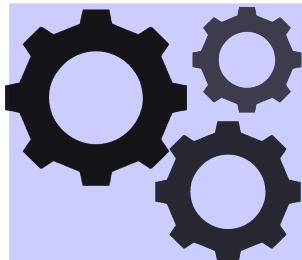
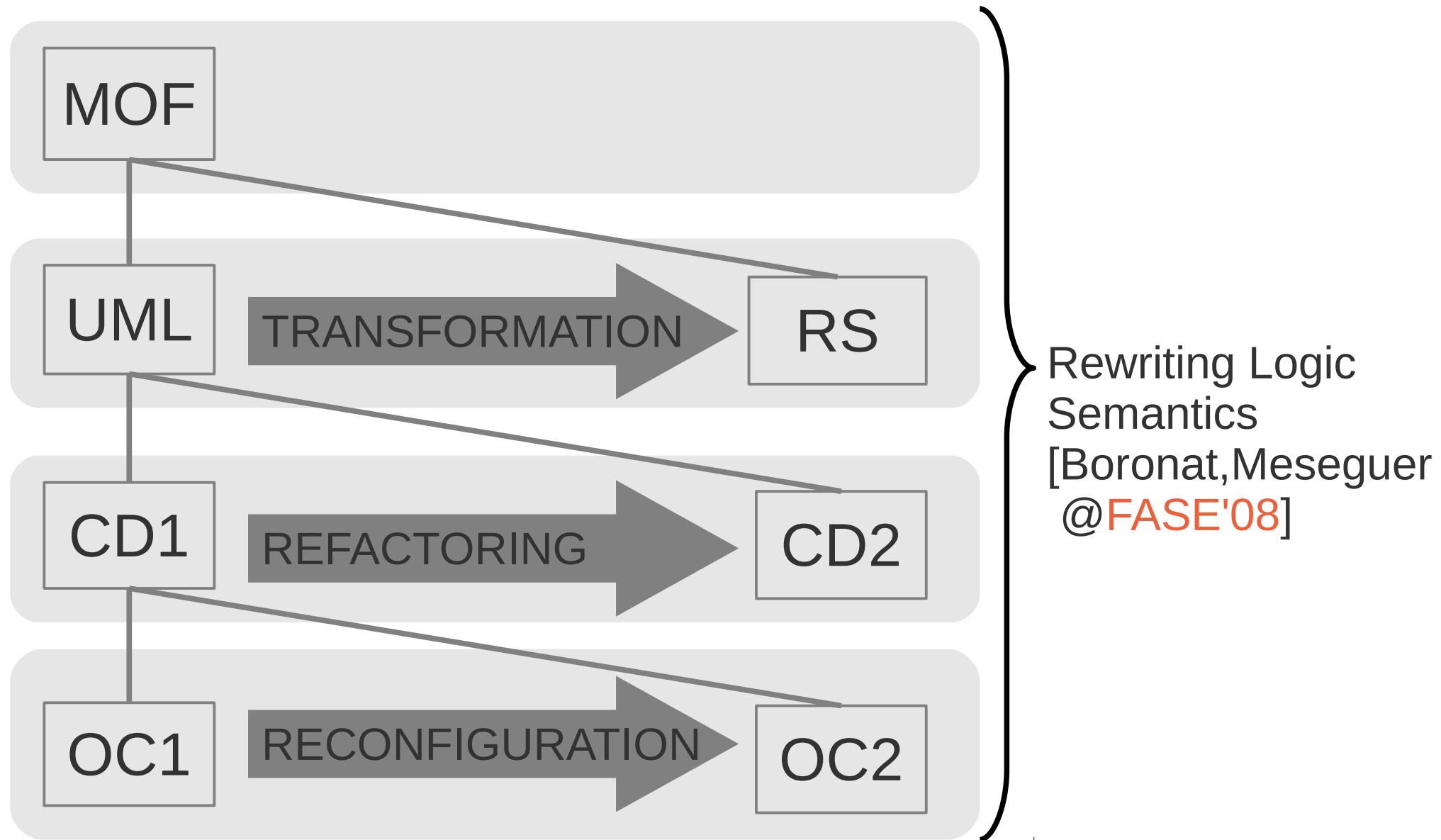


Alberto Lluch  
Artur Boronat  
Roberto Bruni  
Ugo Montanari  
Generoso Paolillo

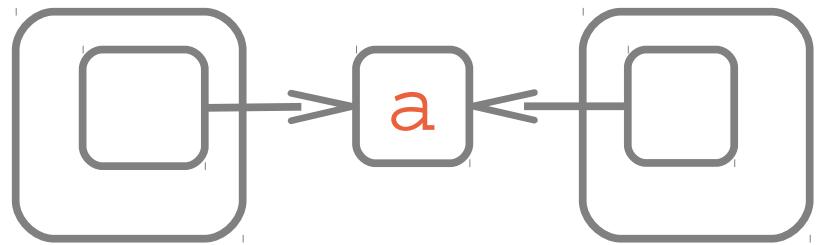
IFIP International Conference on Formal Techniques for Distributed Systems  
June 7 - 10, 2010, Amsterdam

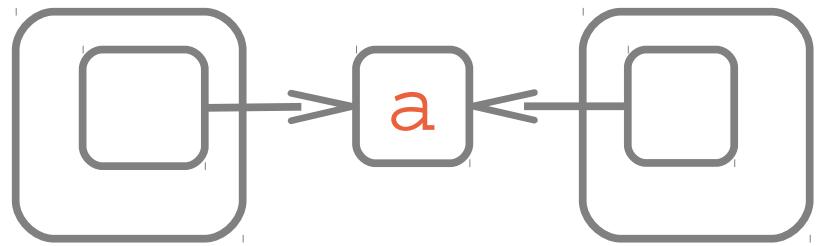




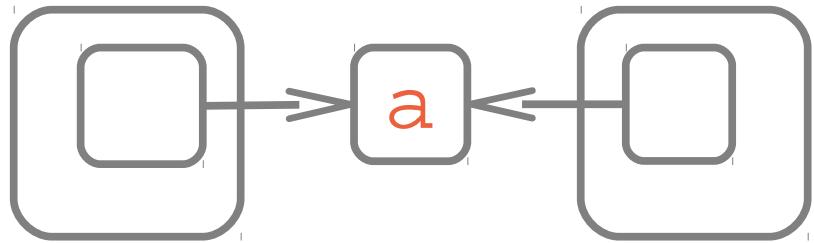


MOMENT2=ECLIPSE+MAUDE



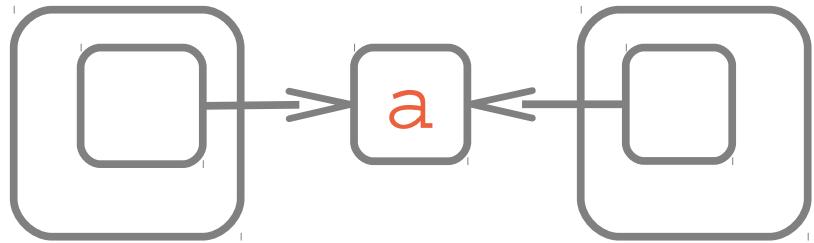


[ G( a ) ] | [ H( a ) ]



[ G( a ) ] | [ H( a ) ]

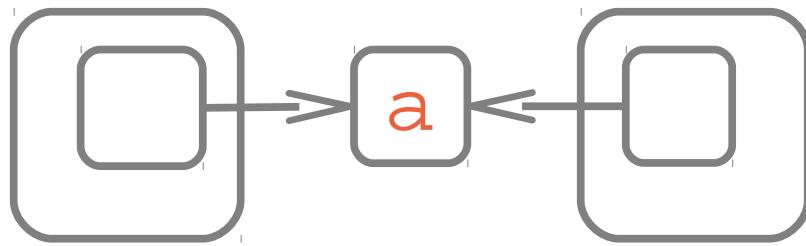
SOS-like rules →



[ G( a ) ] | [ H( a ) ]

SOS-like rules





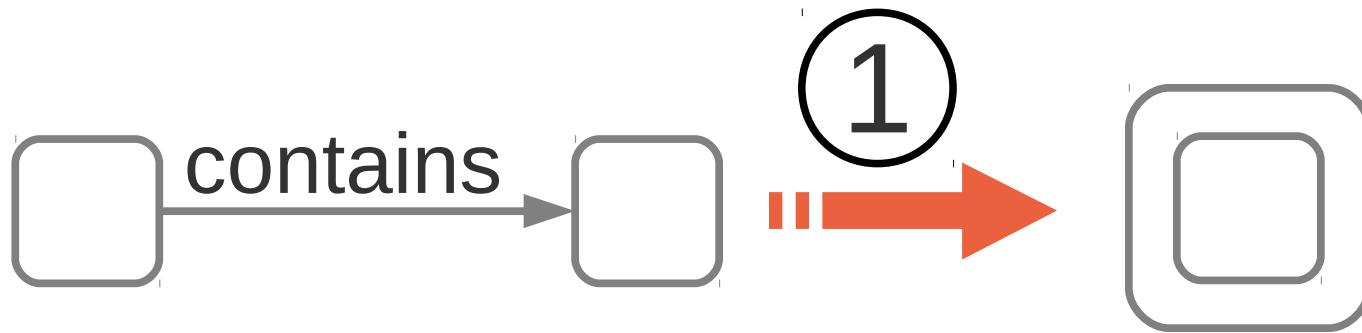
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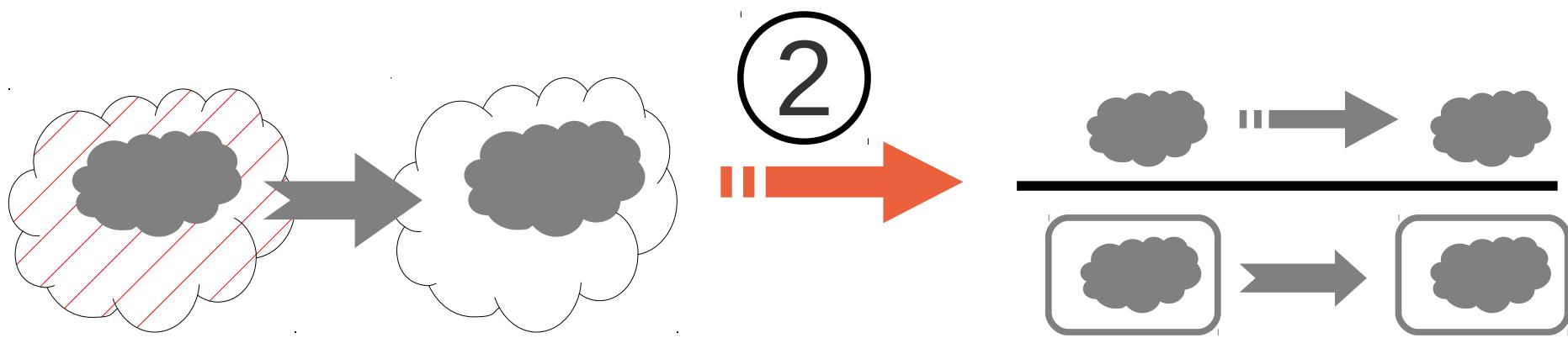
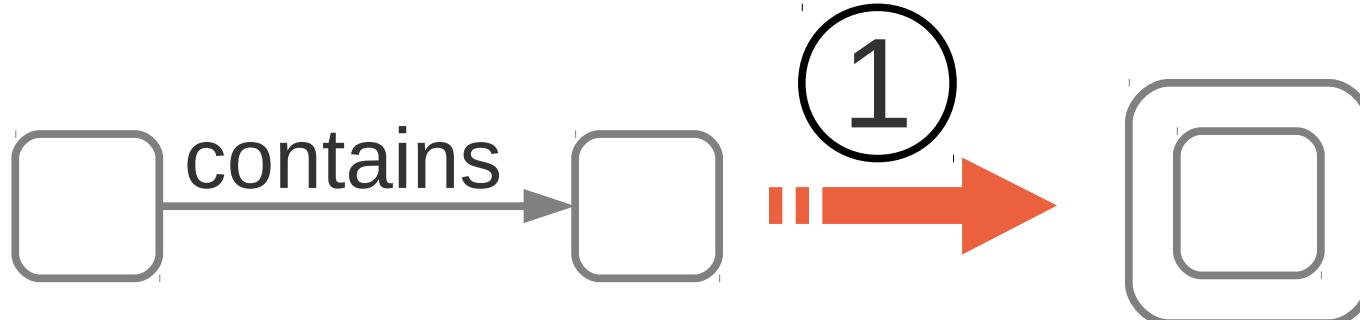
SOS-like rules

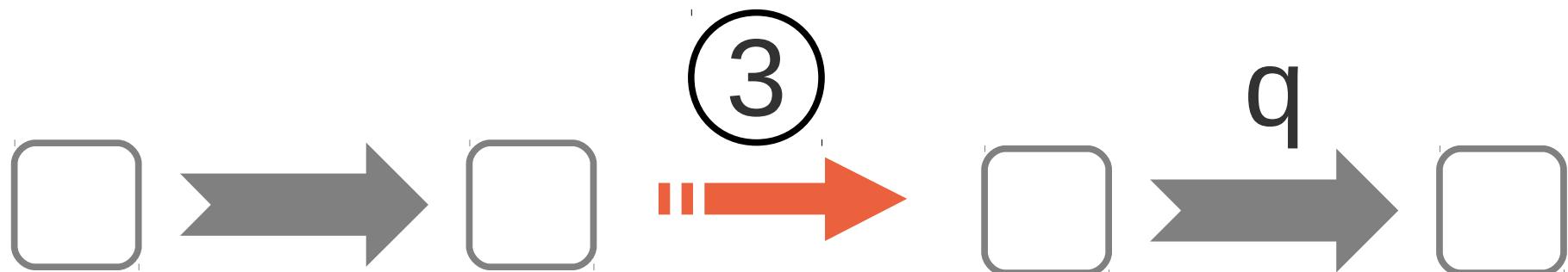
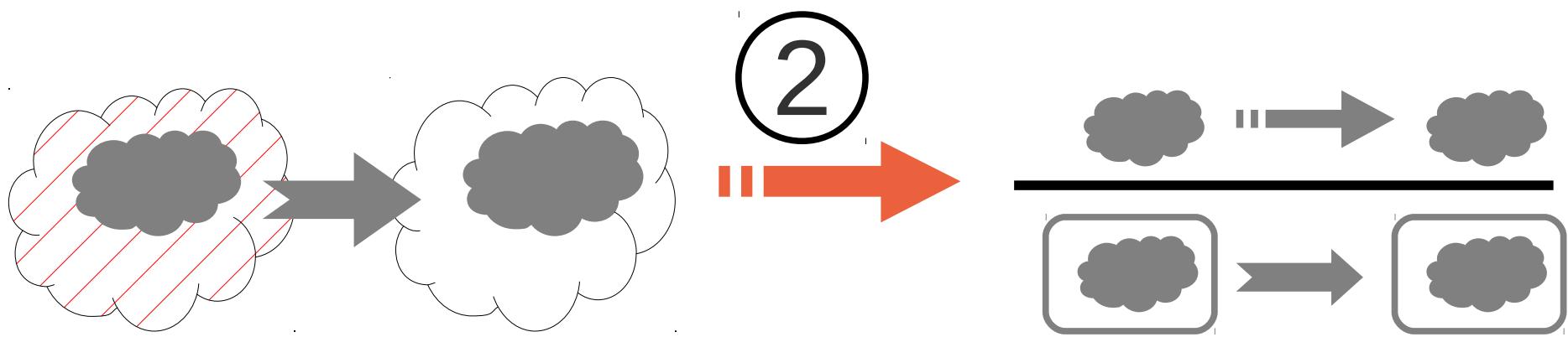
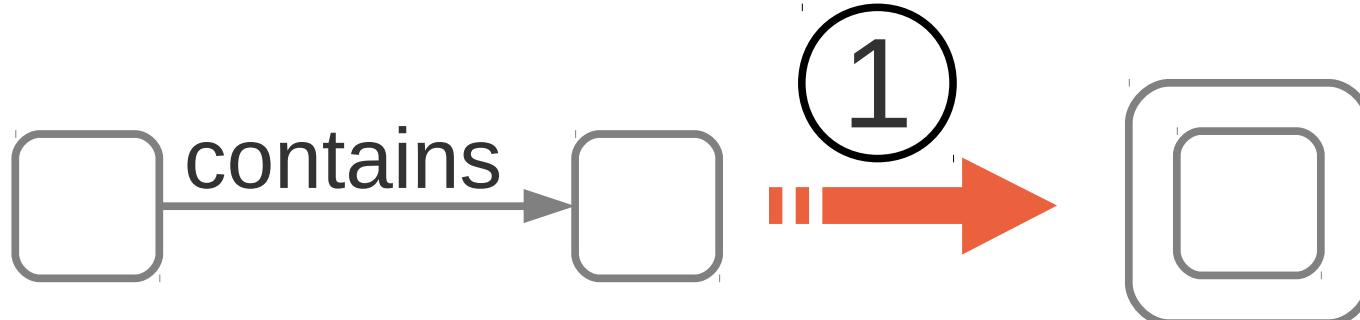


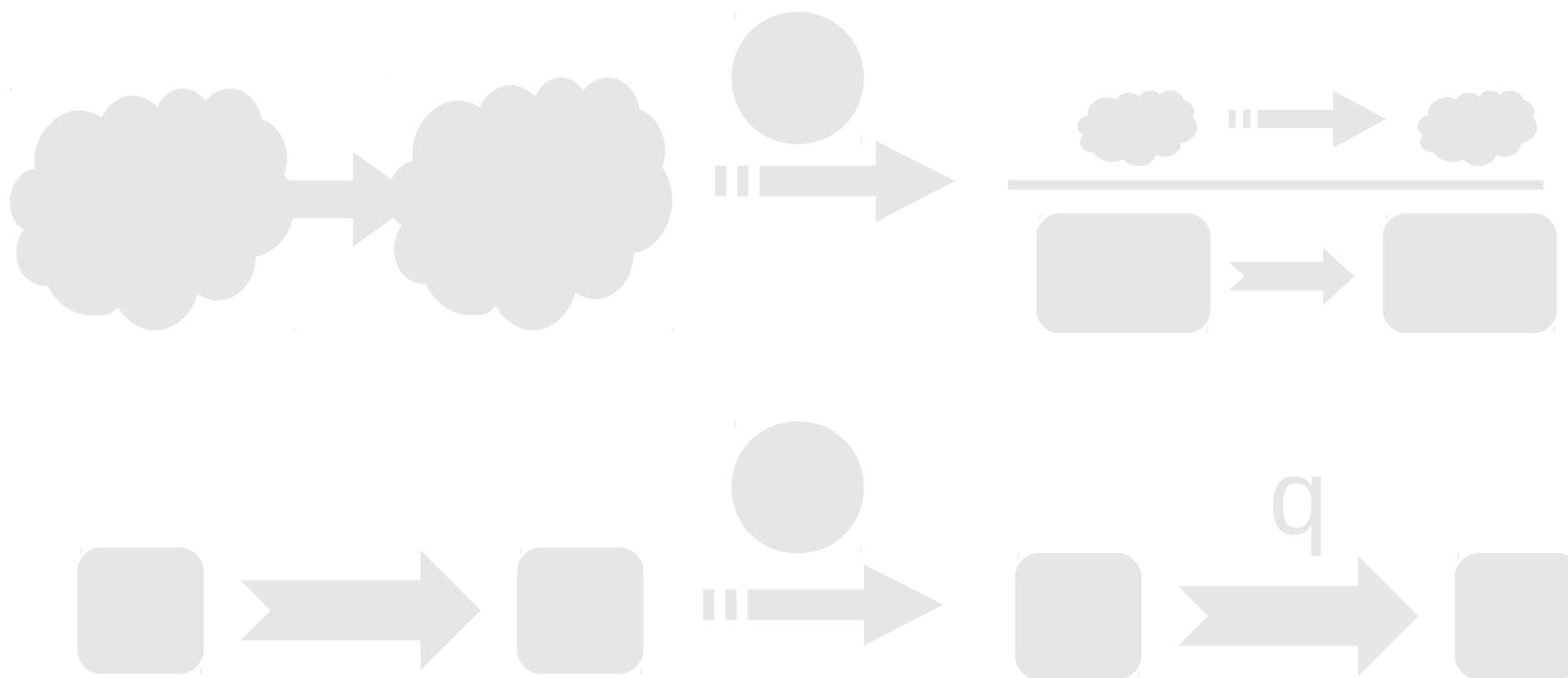
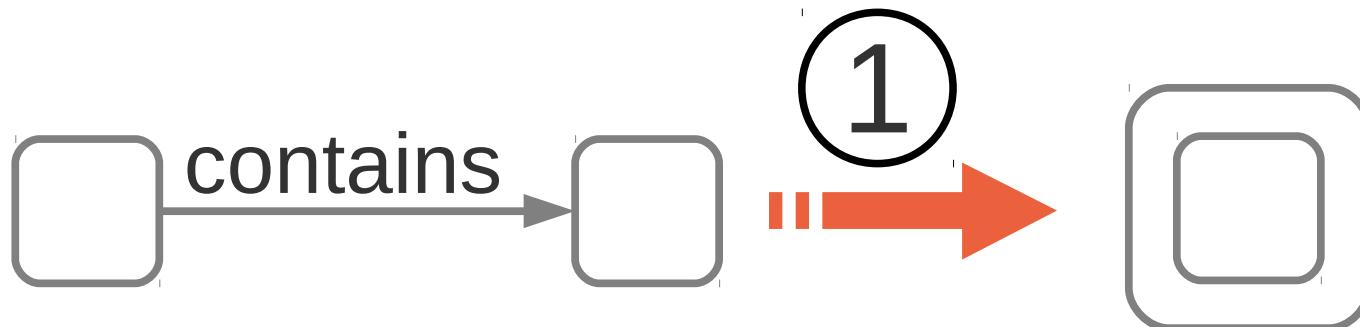
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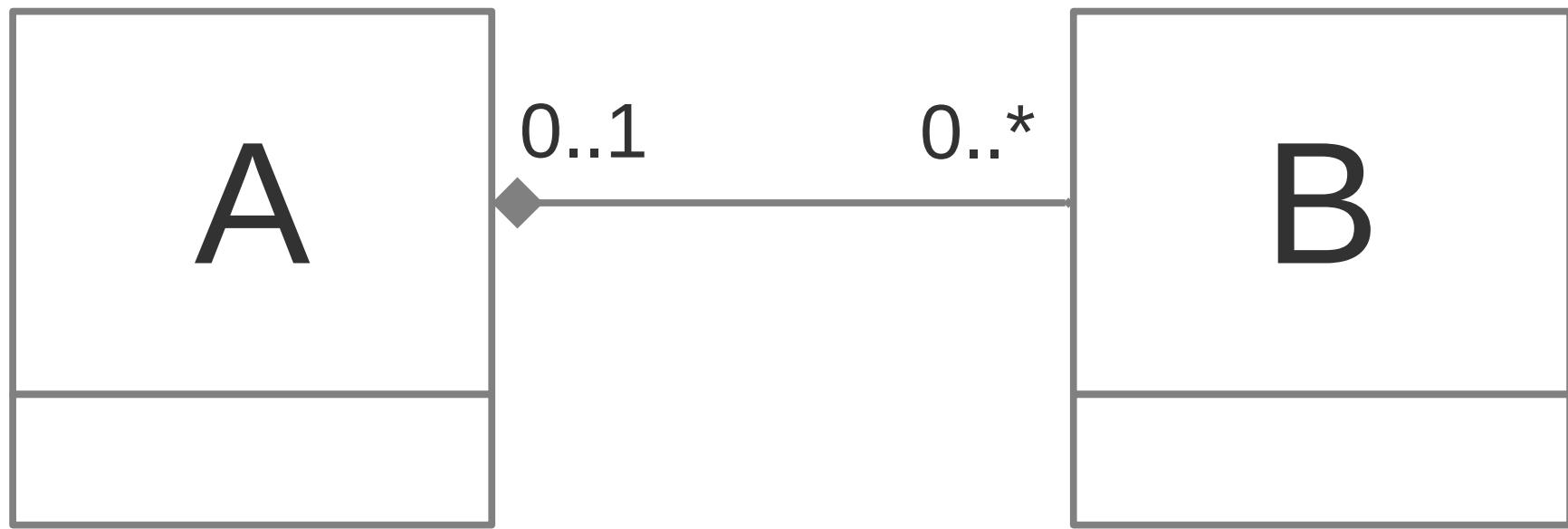
ADR  
[Montanari, Bruni, Lluch,  
Gadducci, Tuosto, etc.  
@TGC'10]

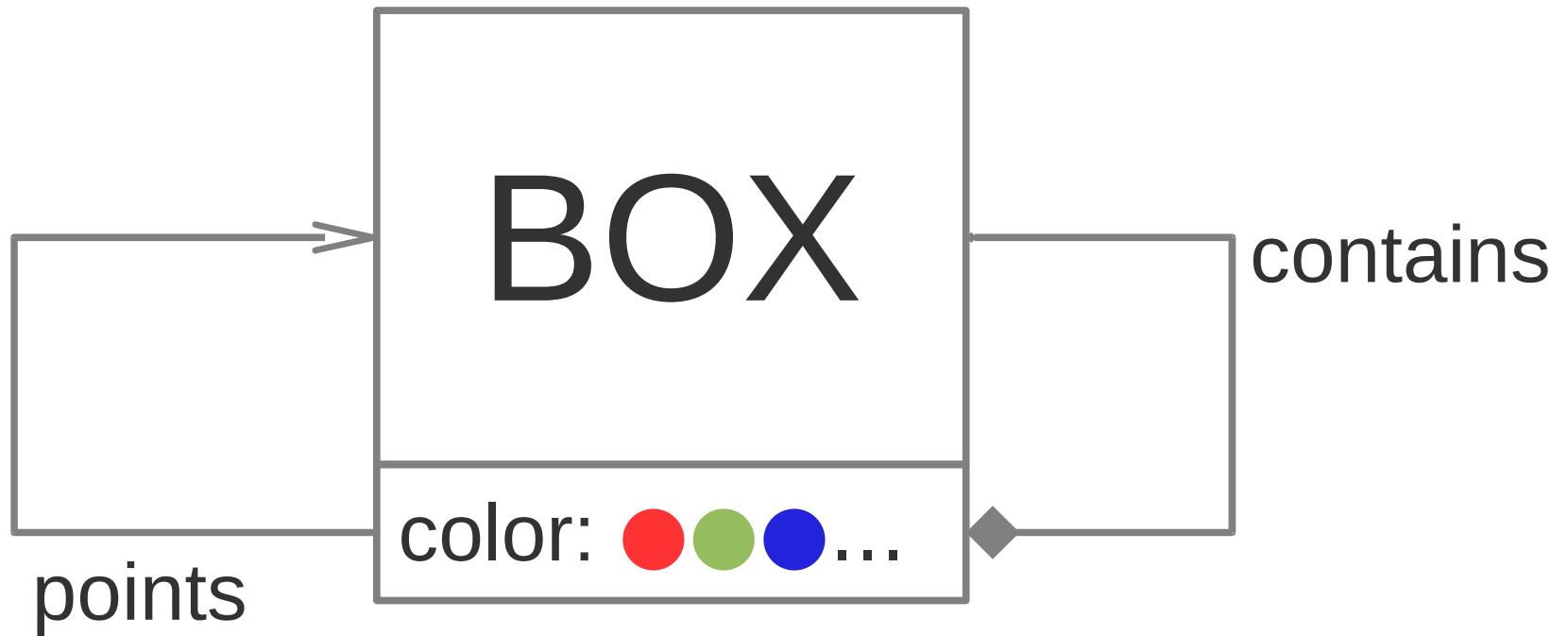


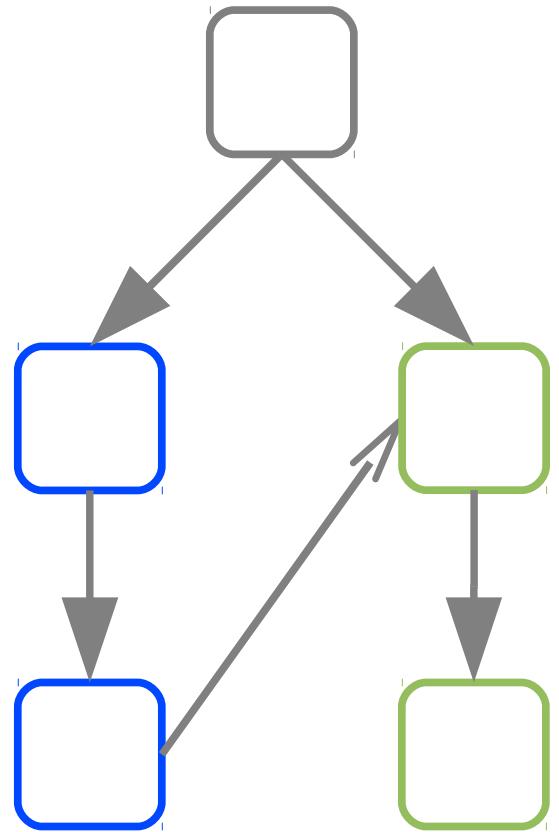


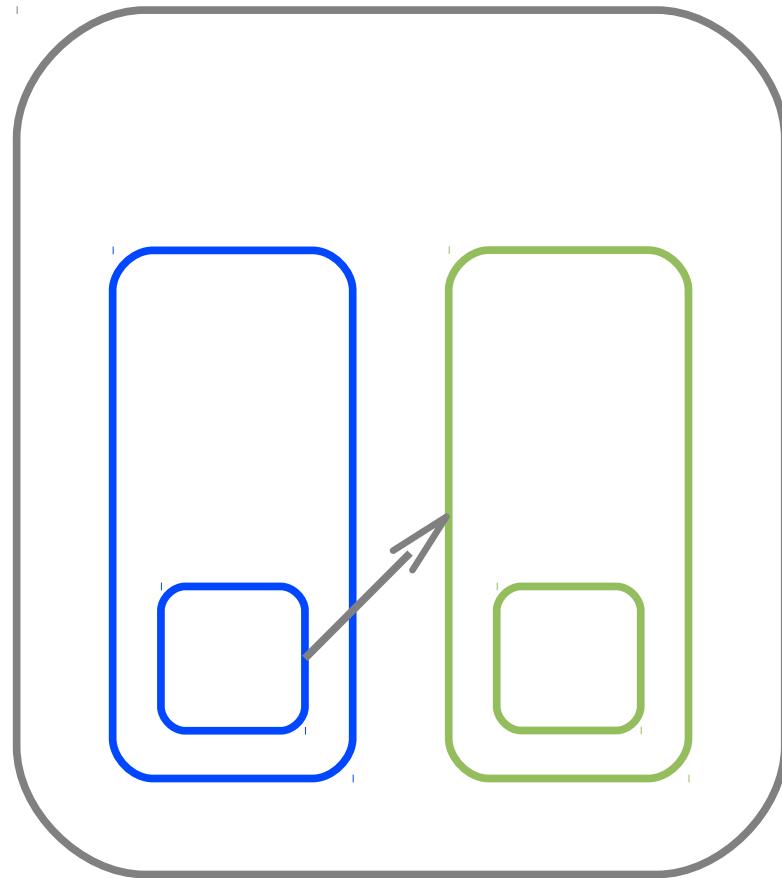
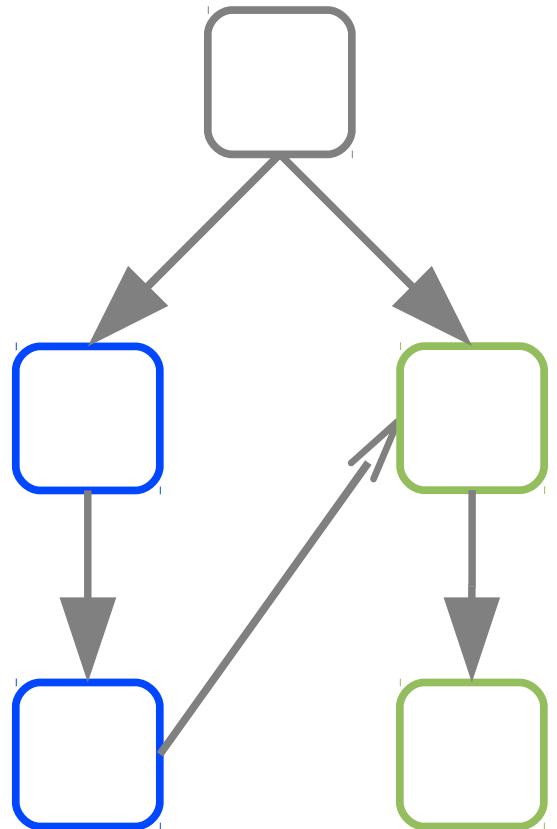










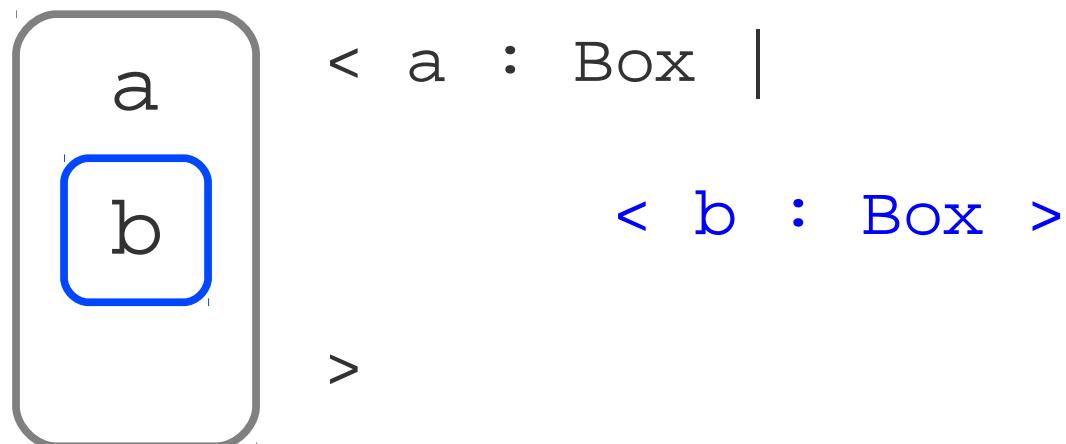


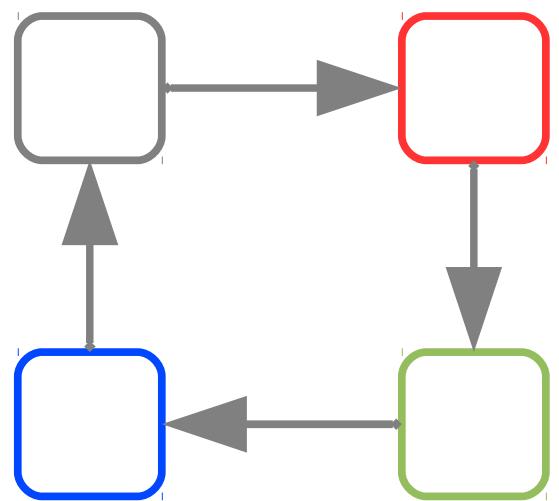


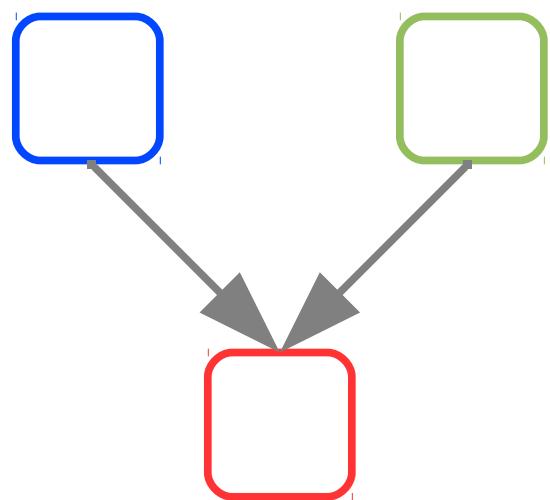
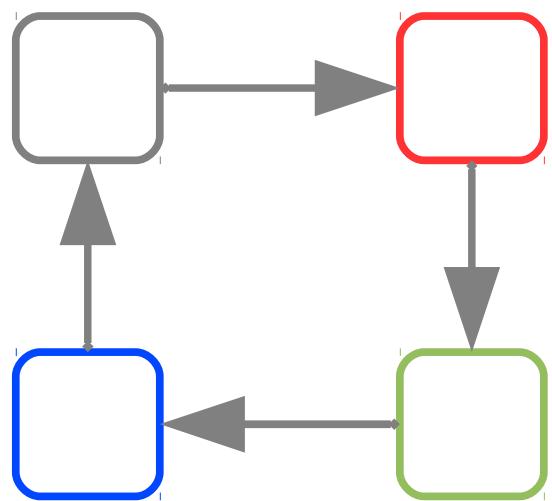
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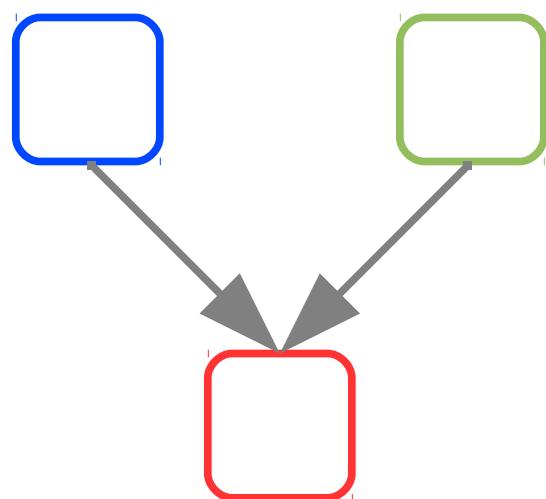
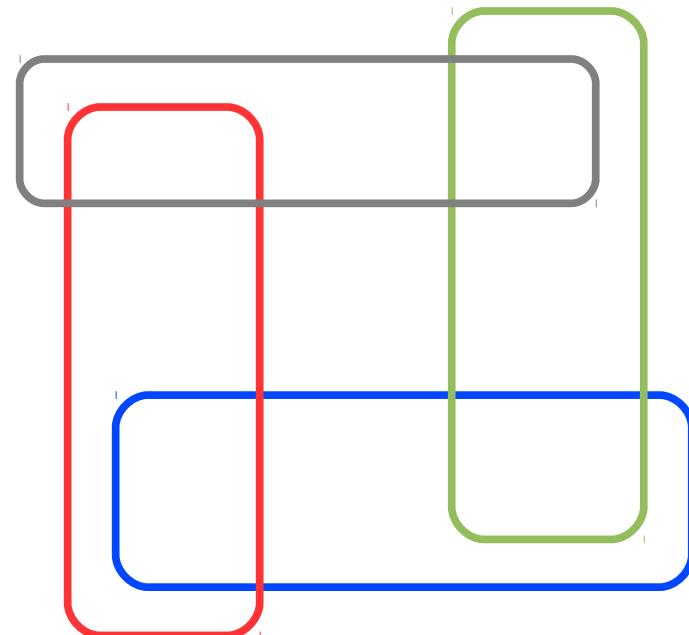
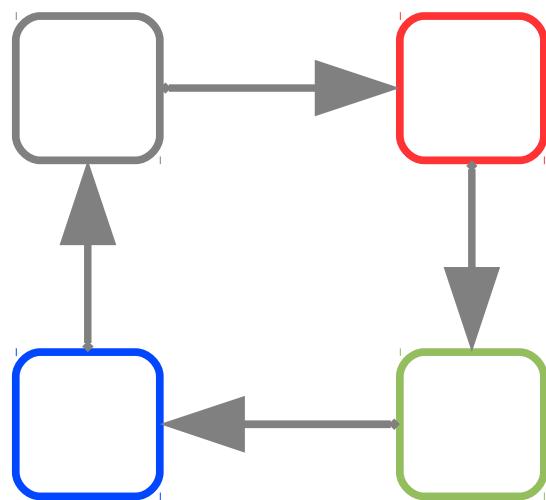


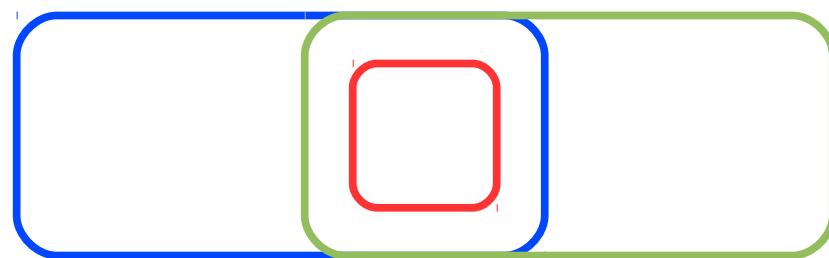
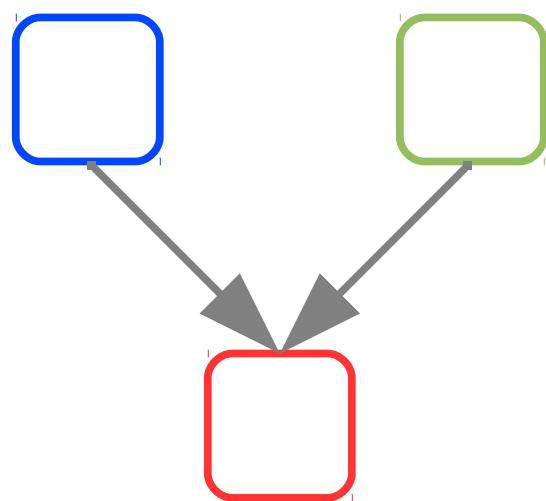
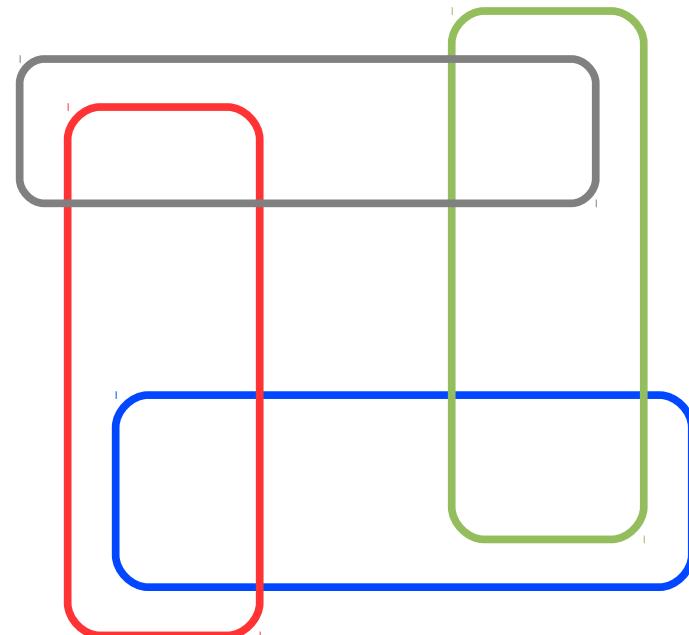
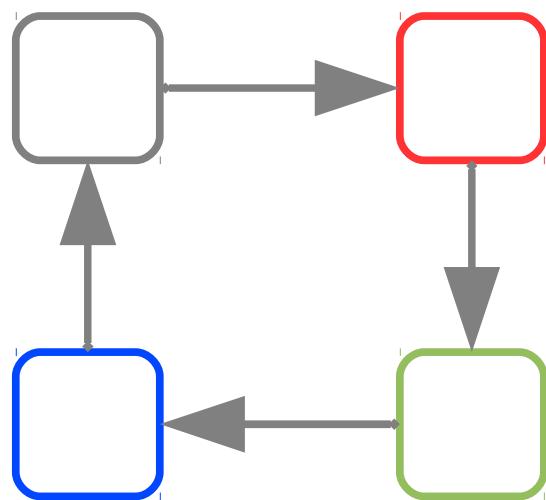
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# Object Collections (flat graphs)

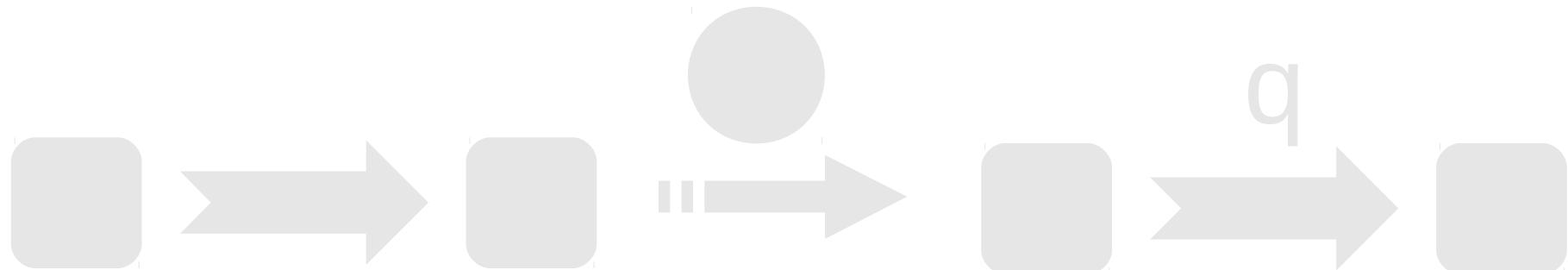
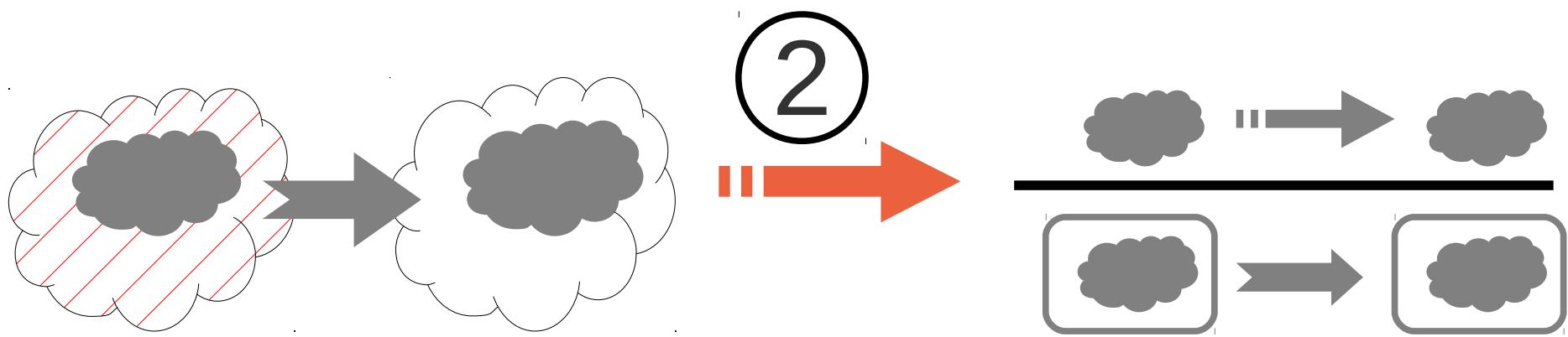
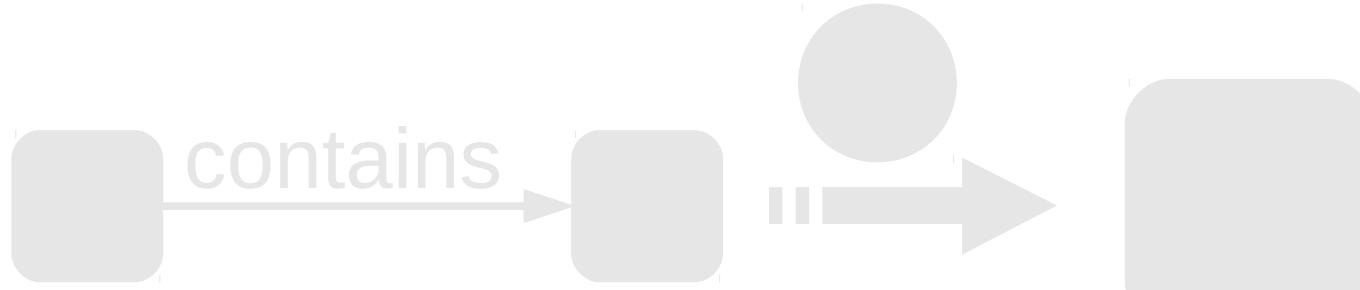
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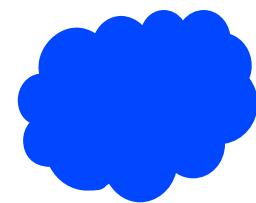
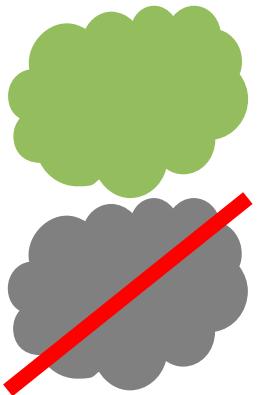
## Object Collections (flat graphs)

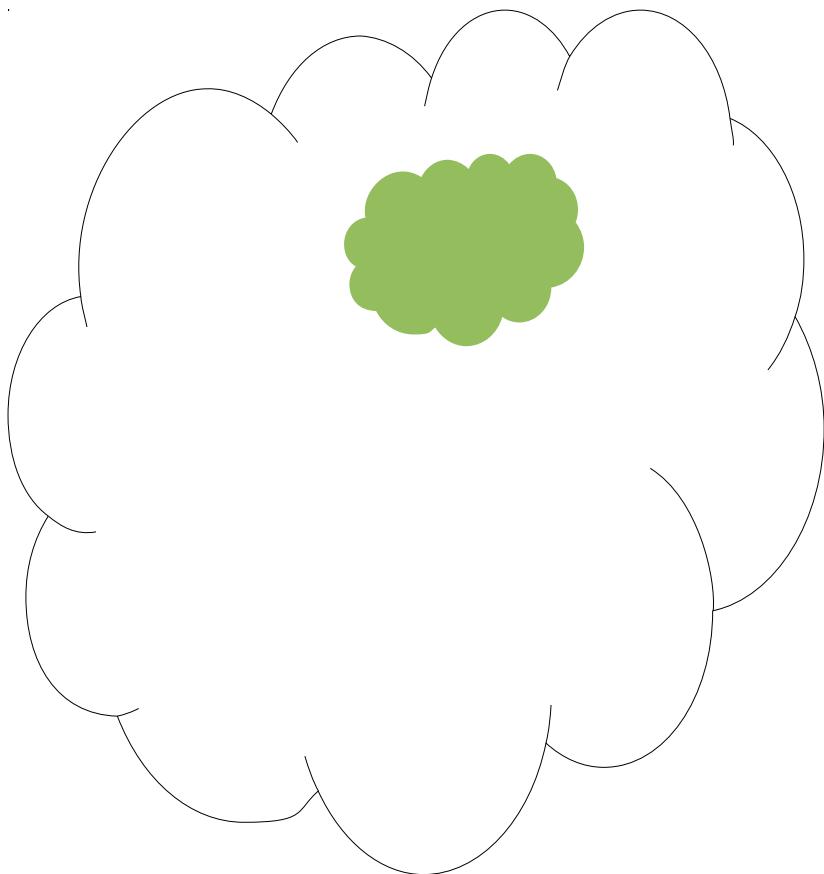
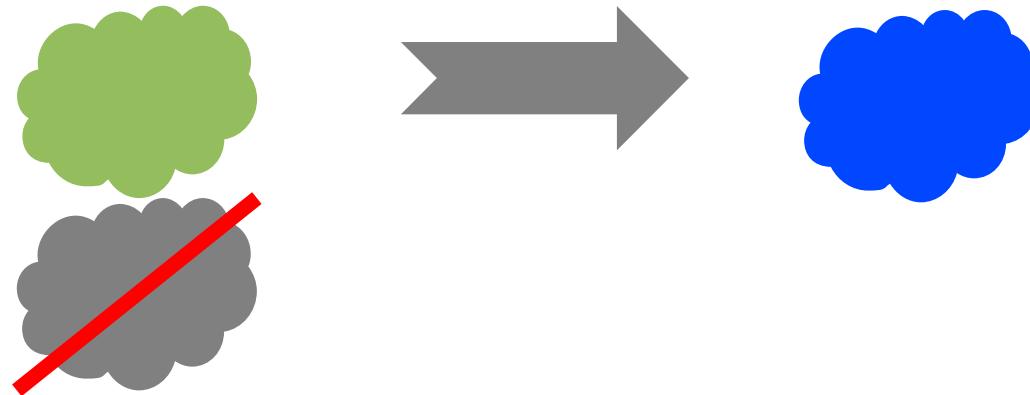
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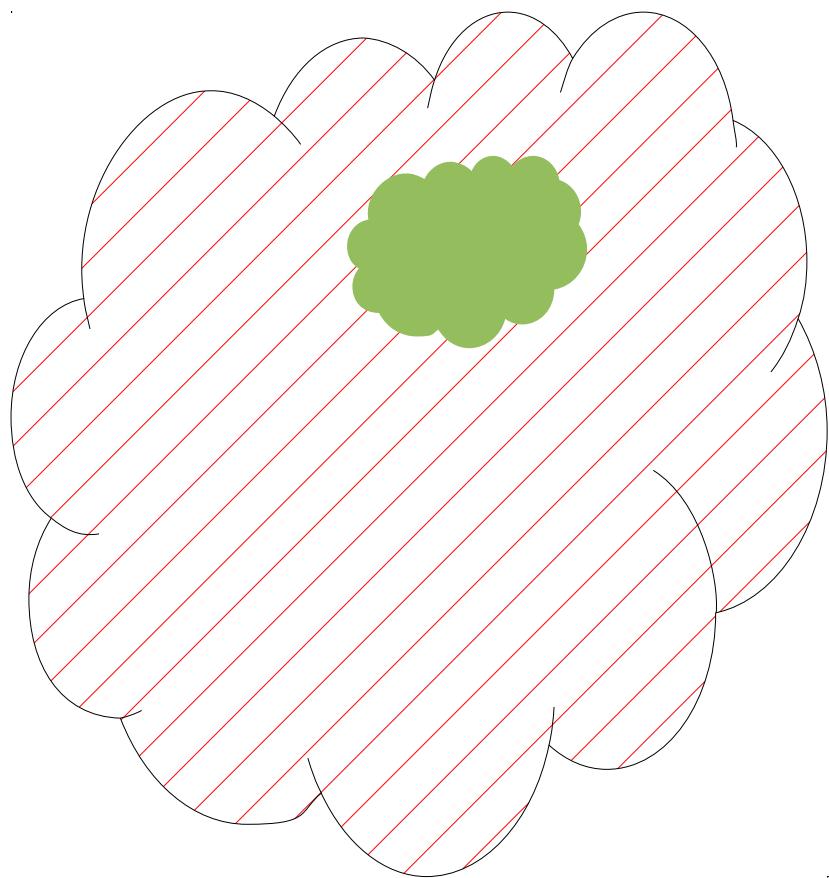
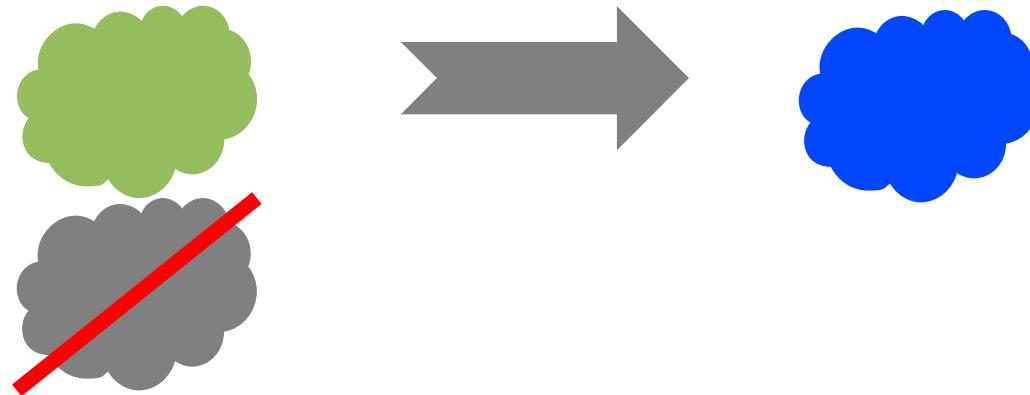
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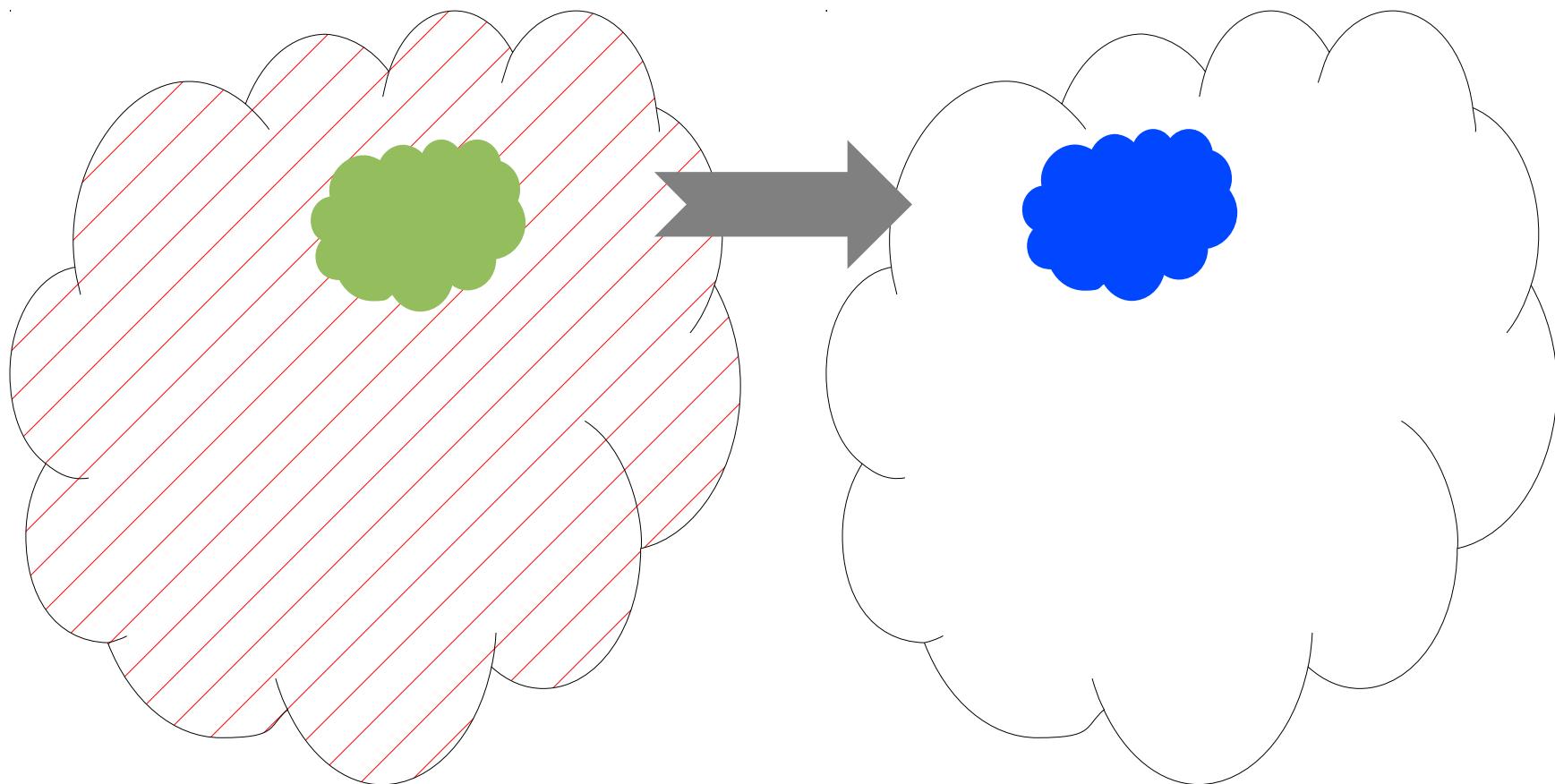
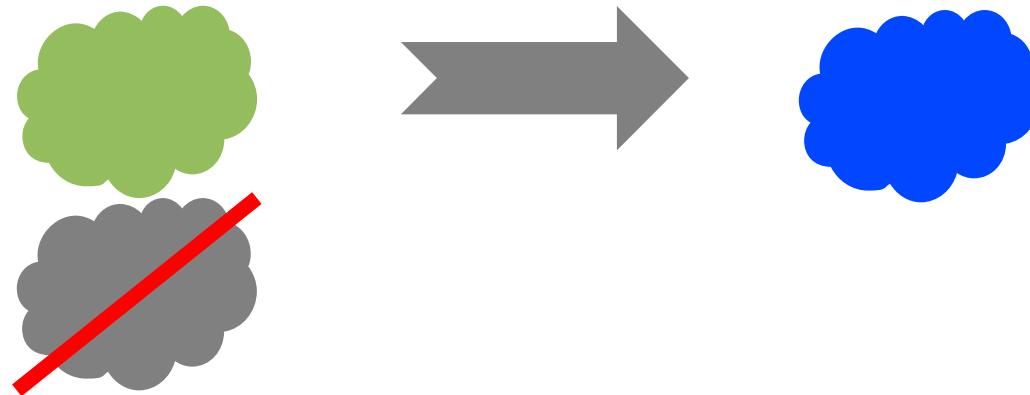
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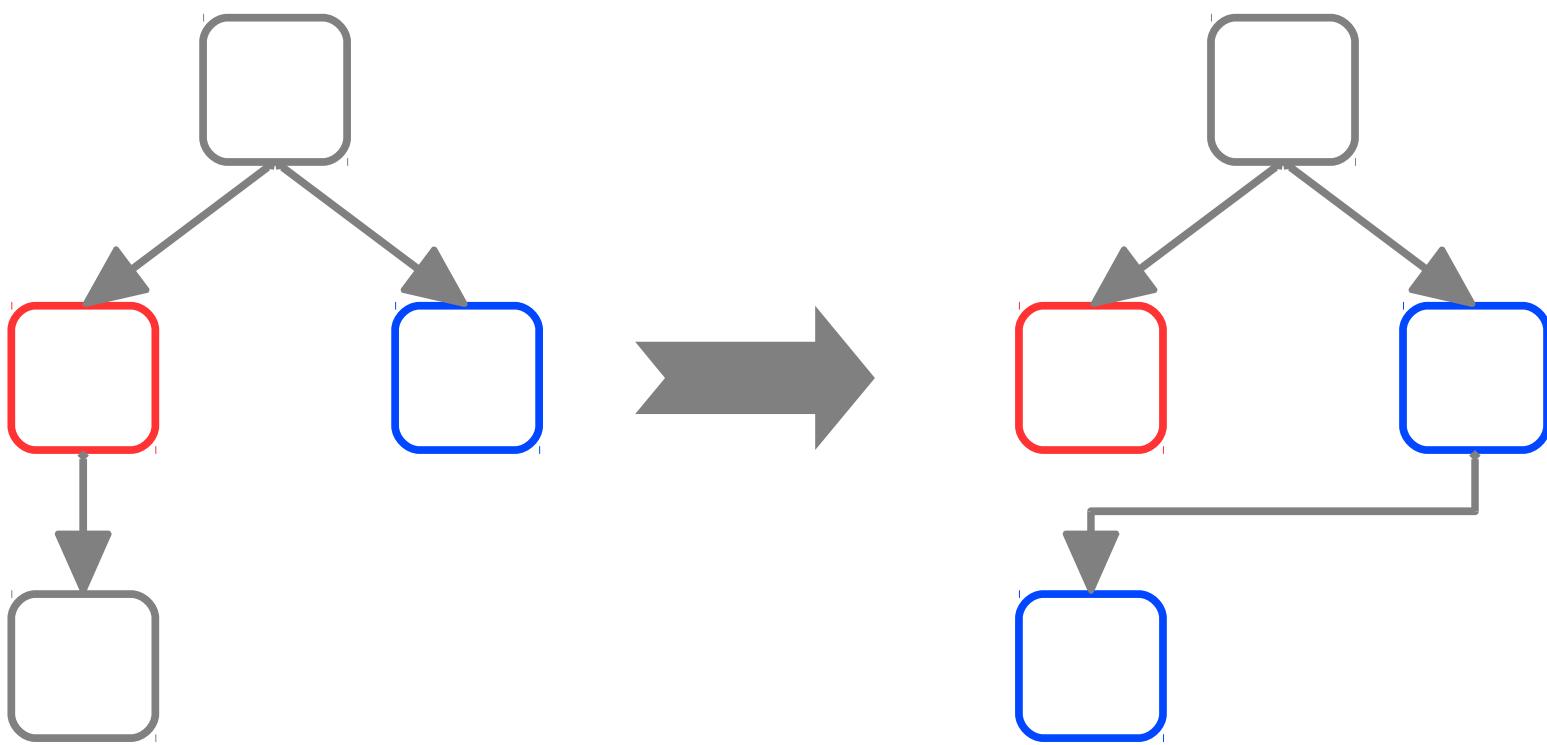


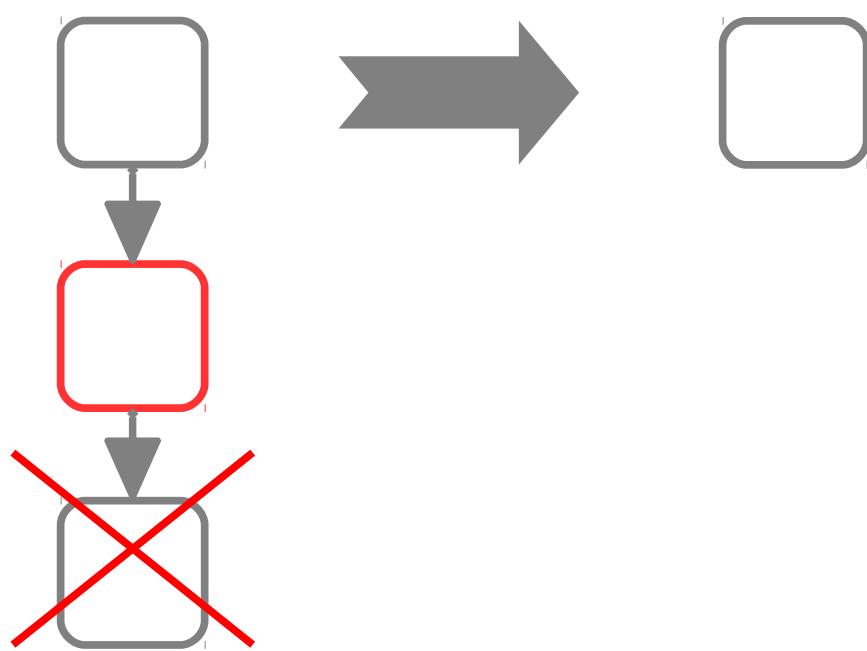


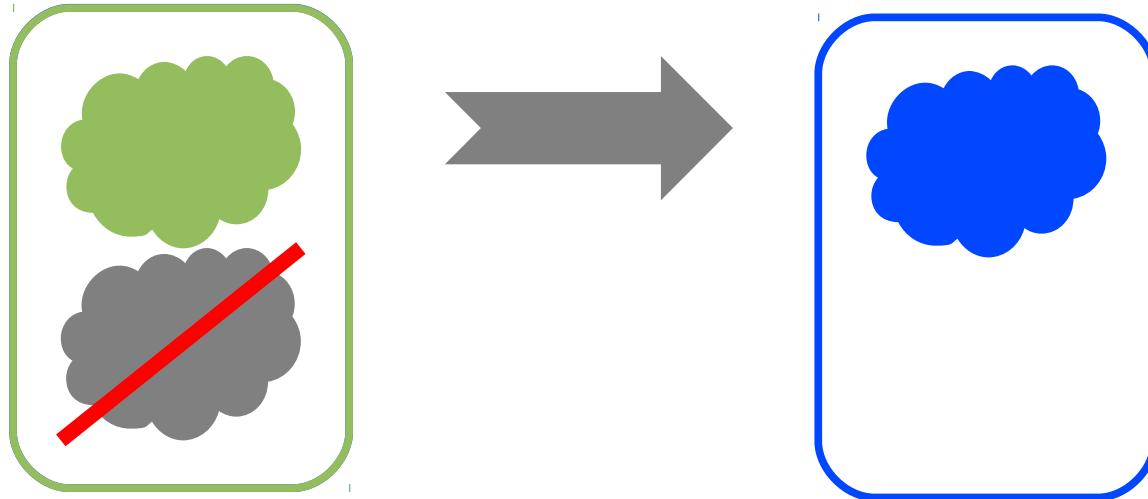


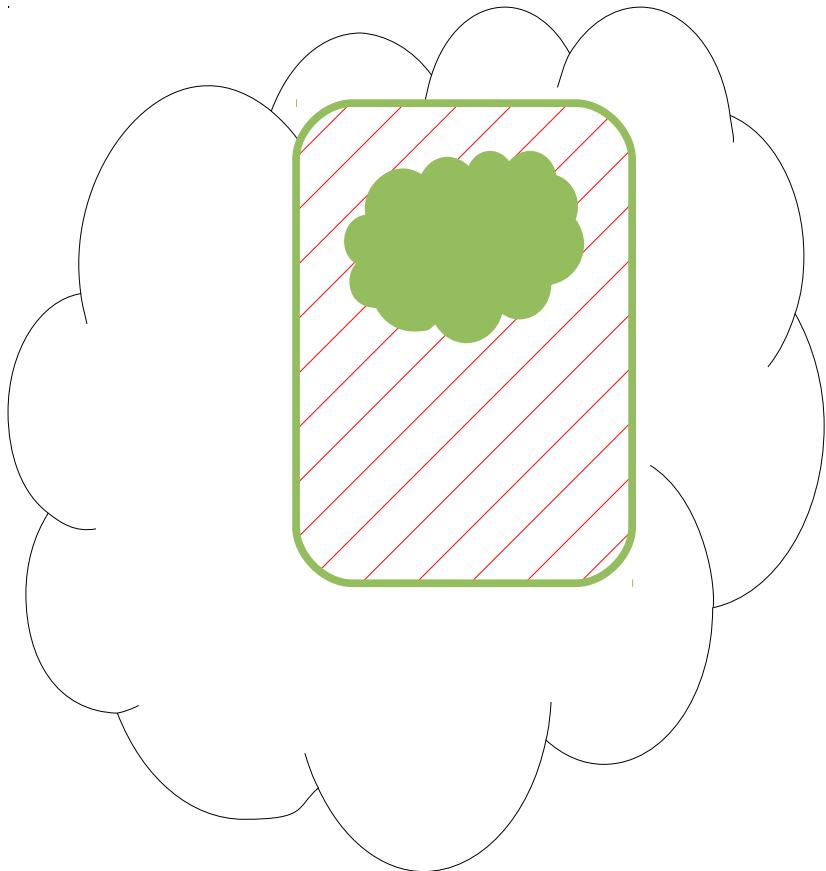
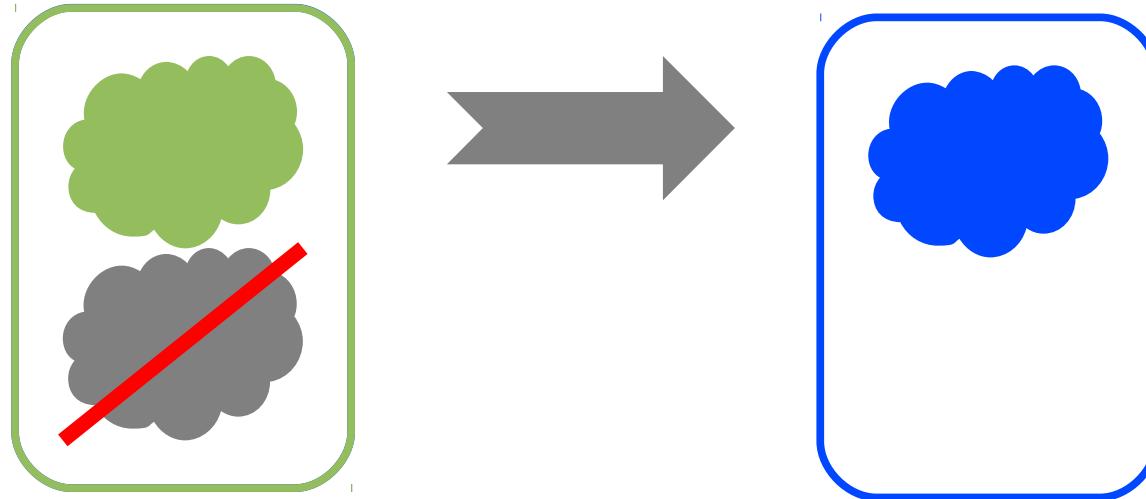


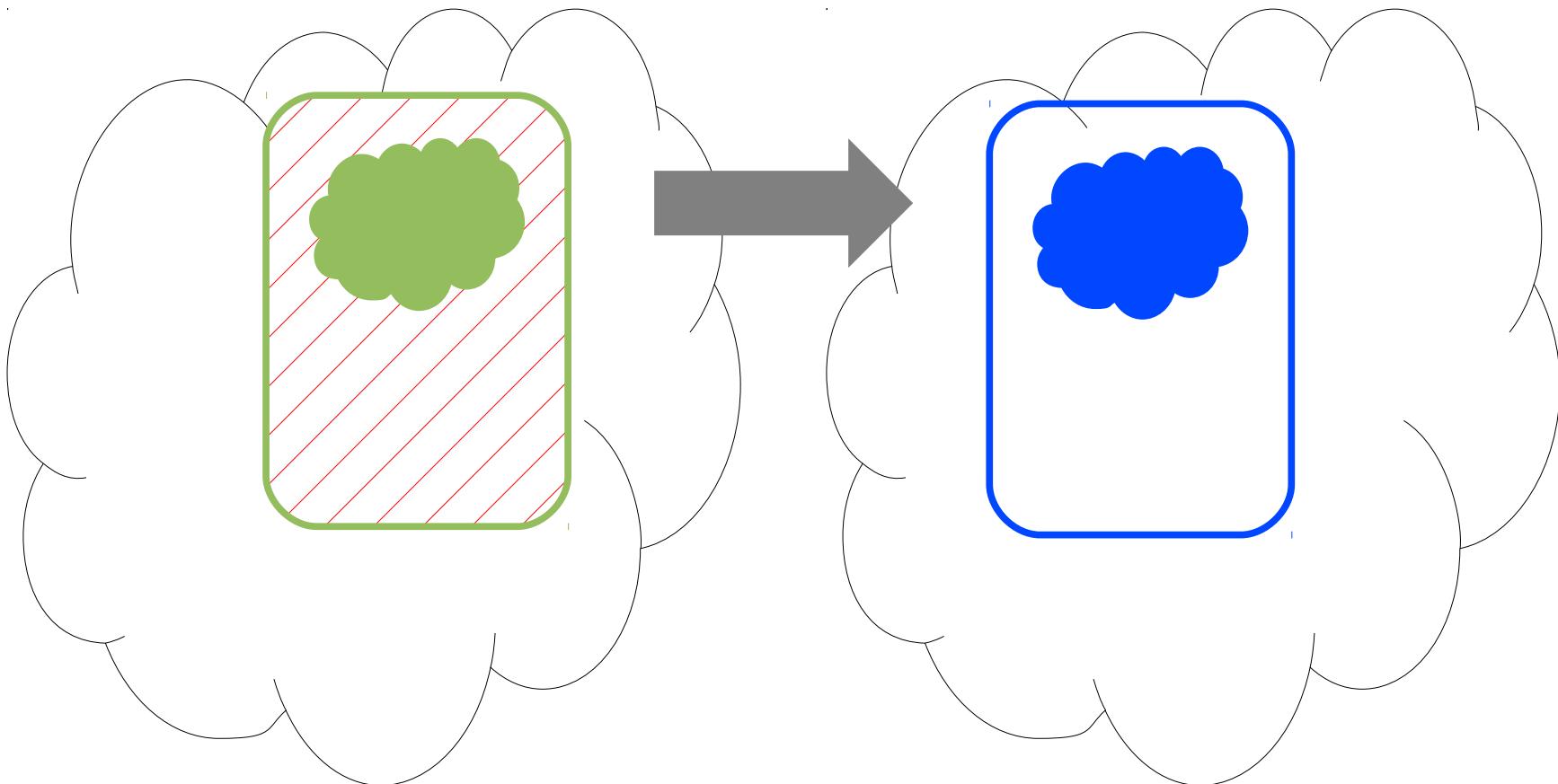
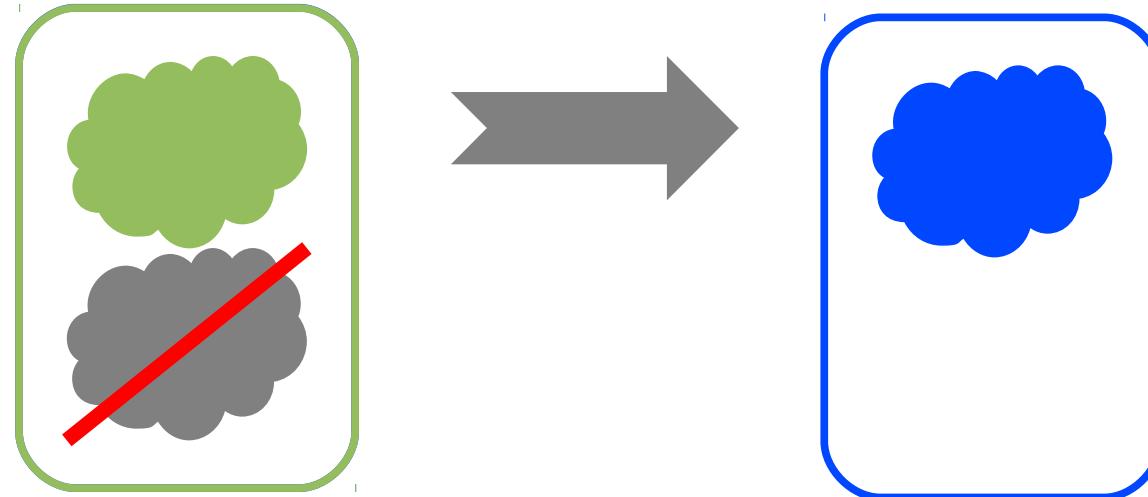


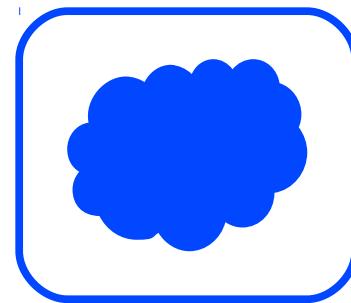


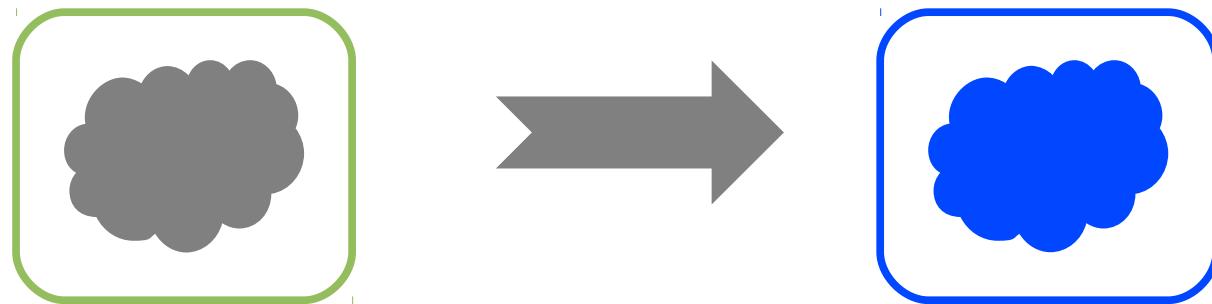
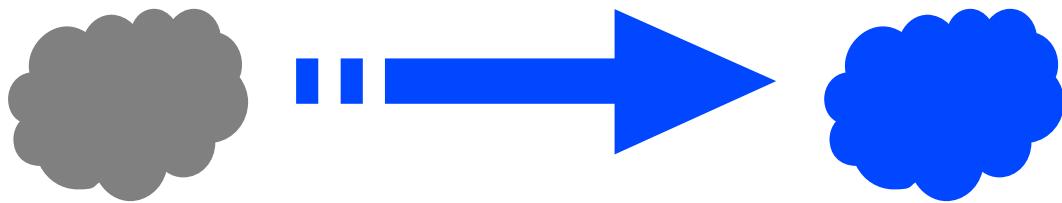




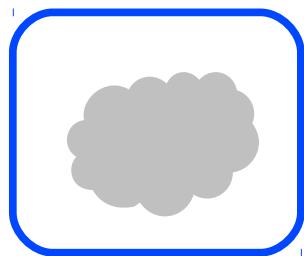
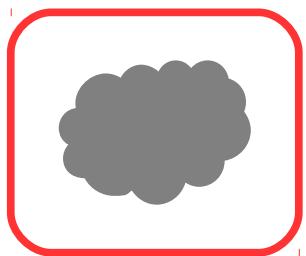


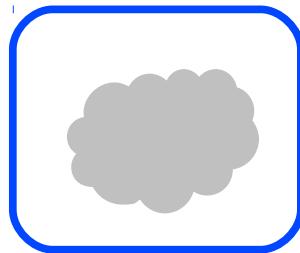
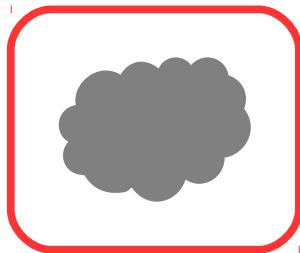
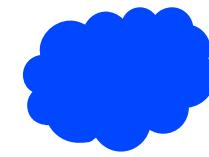




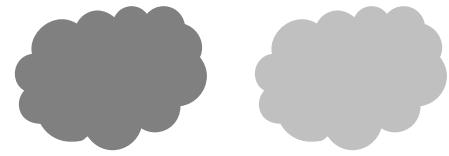


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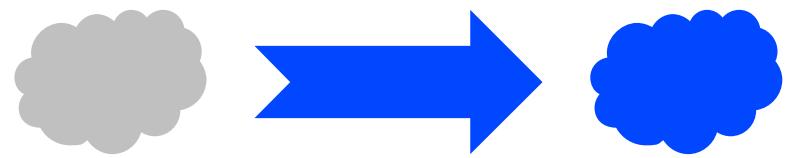




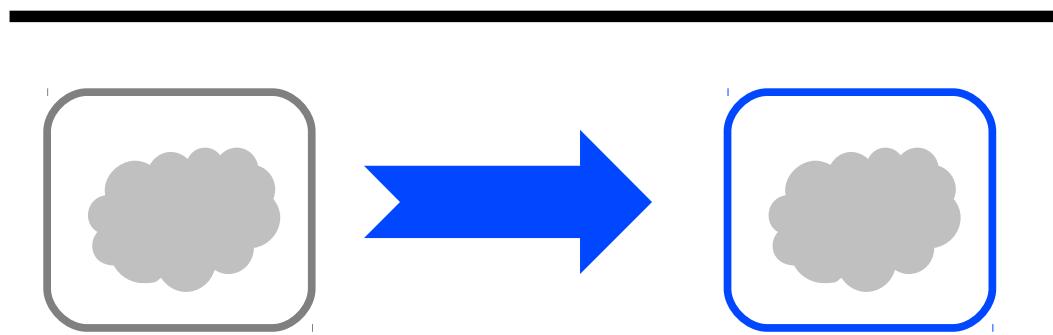


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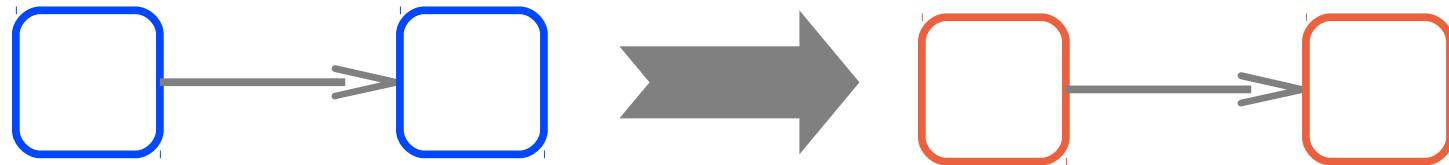


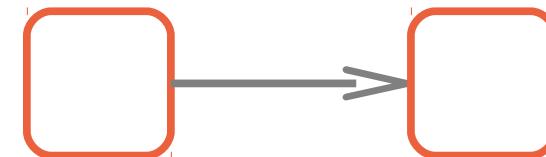




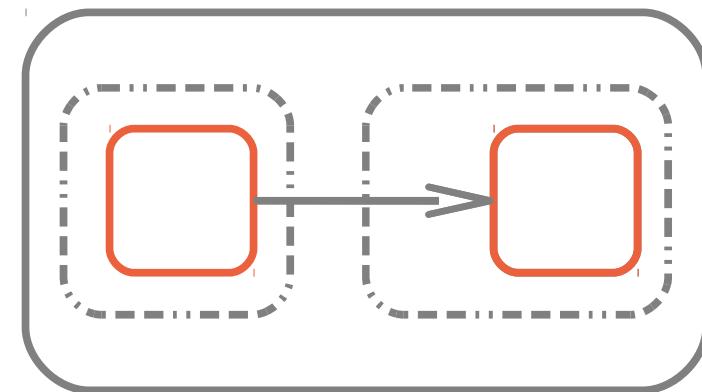
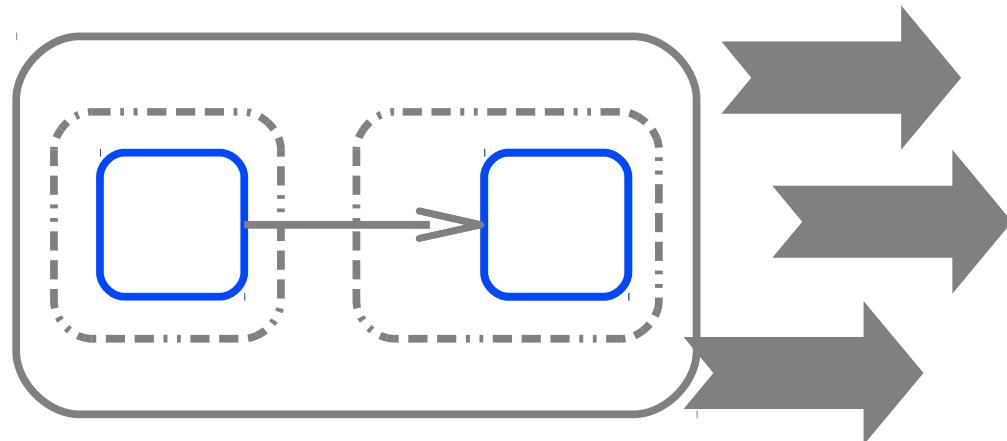


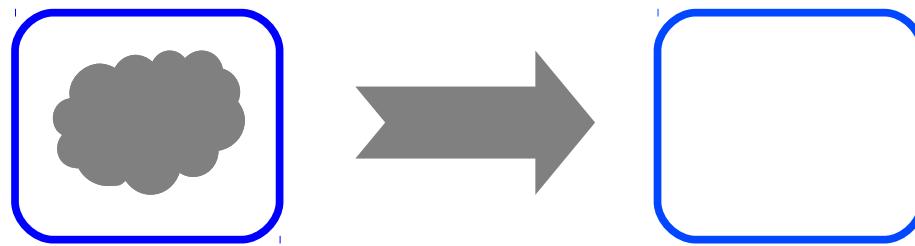
WHICH STYLE  
IS BEST?

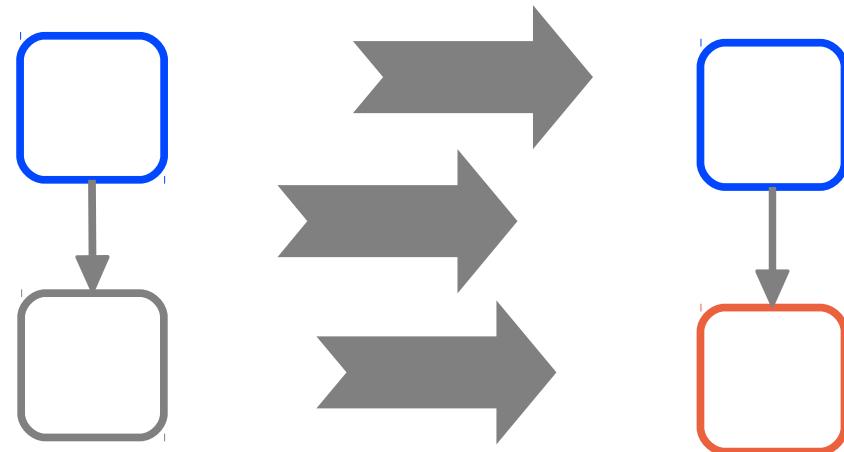




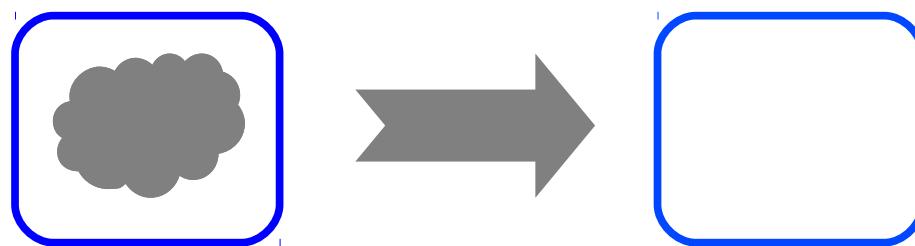
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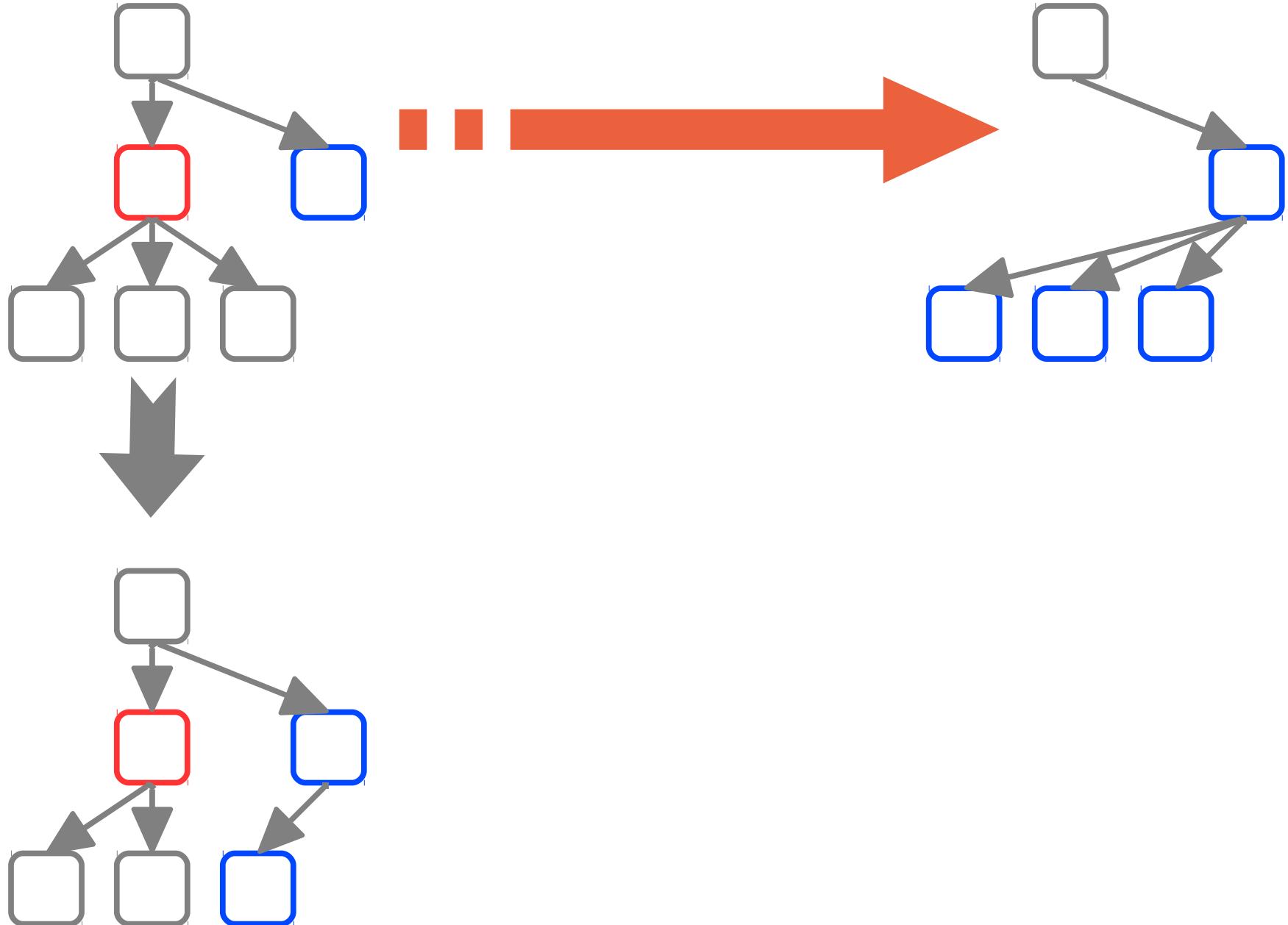


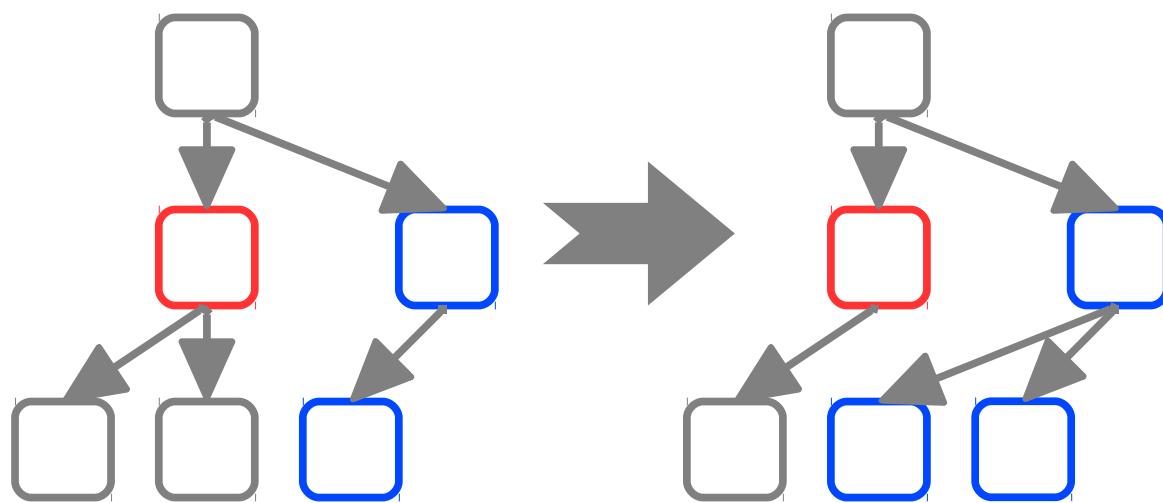
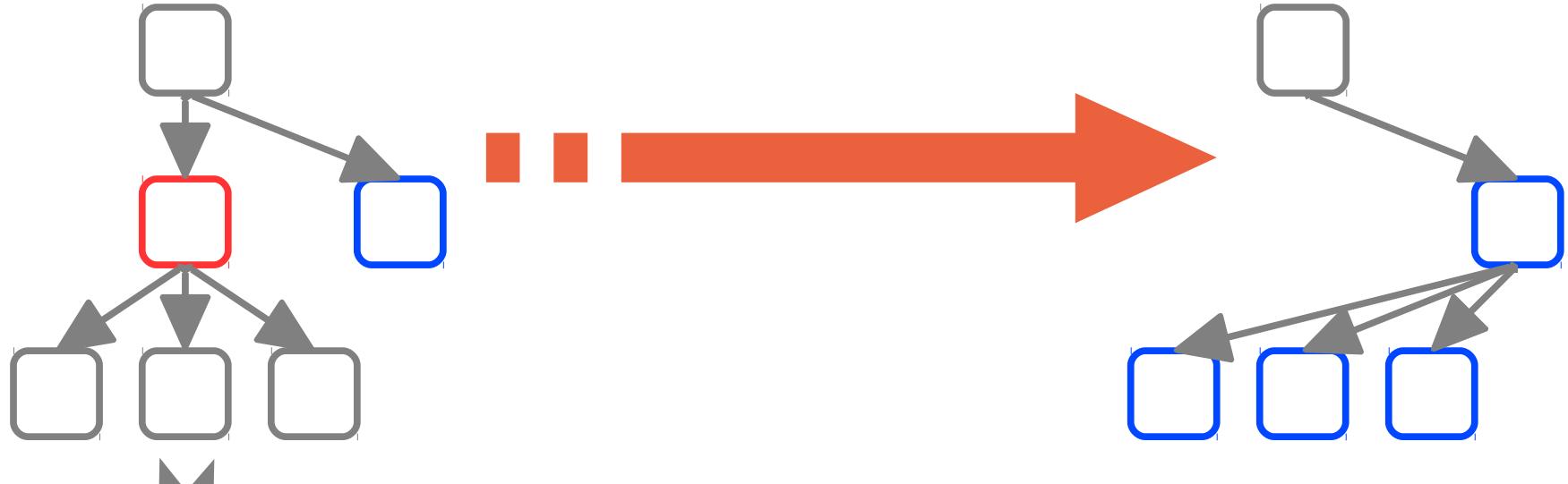


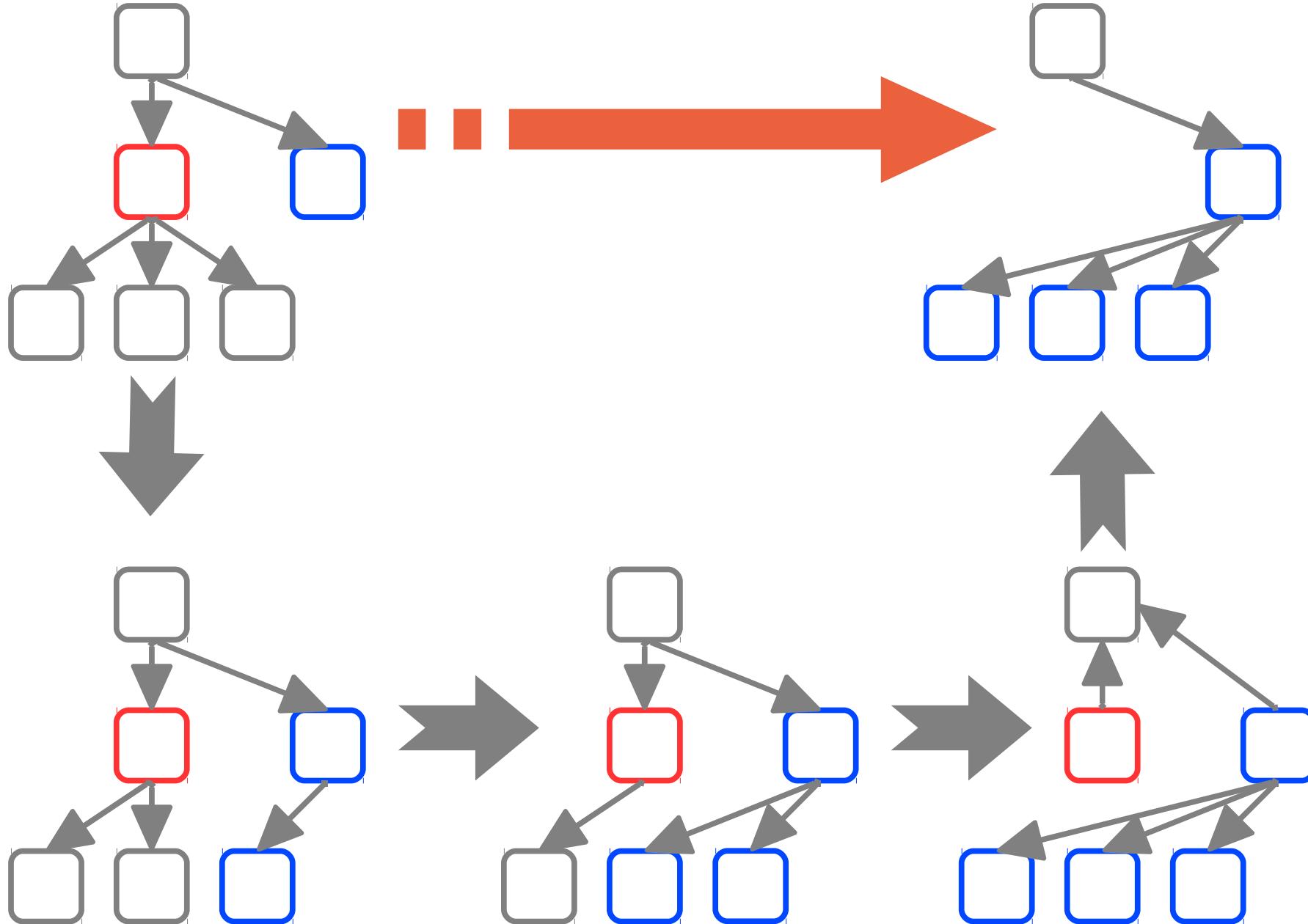
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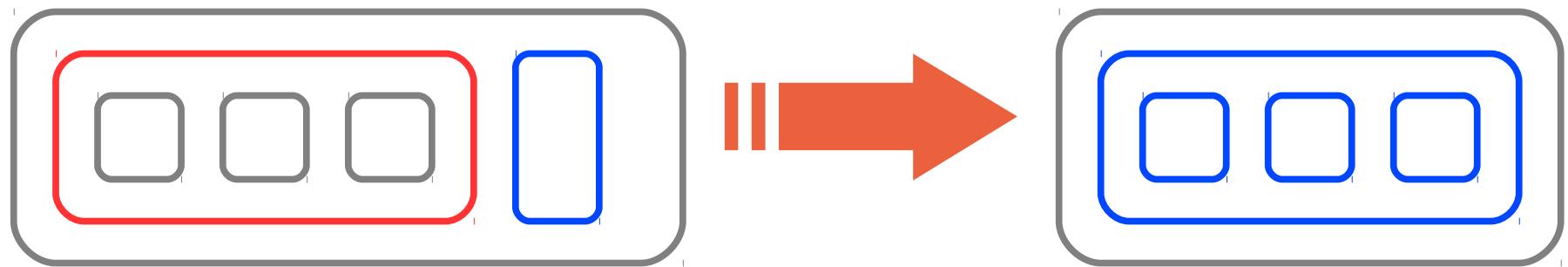


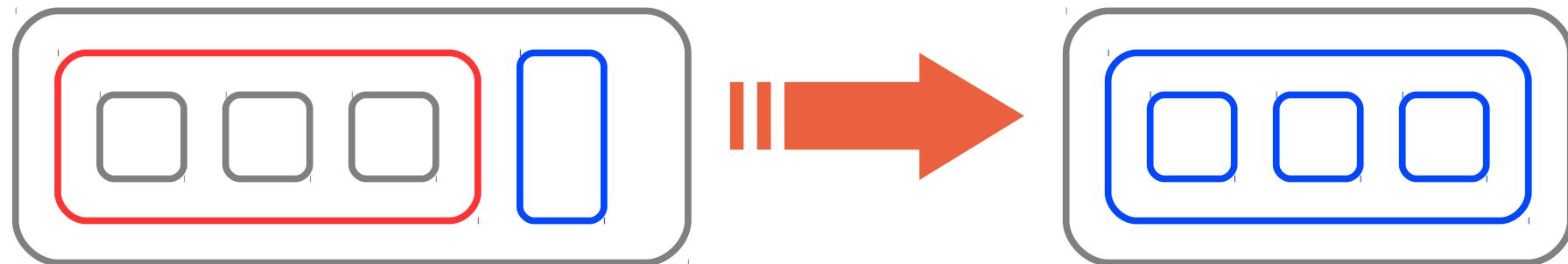


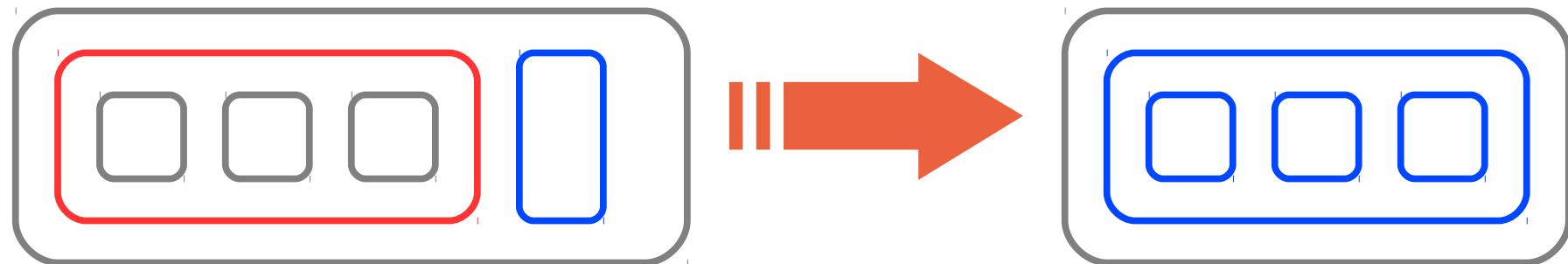
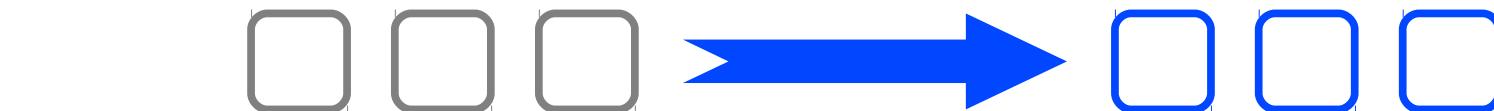


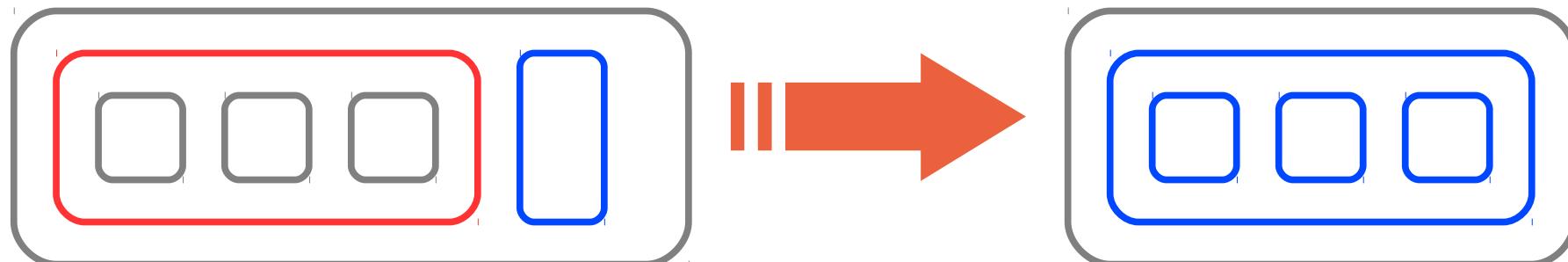












time

SPO

PURE  
SOS

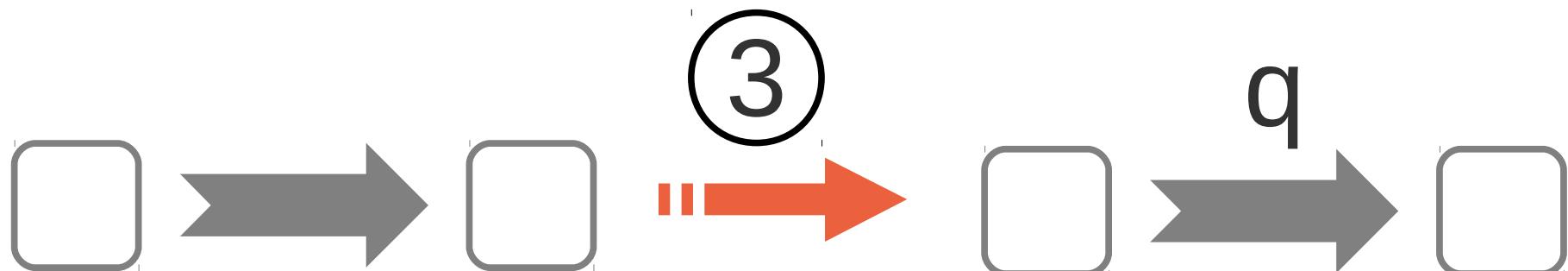
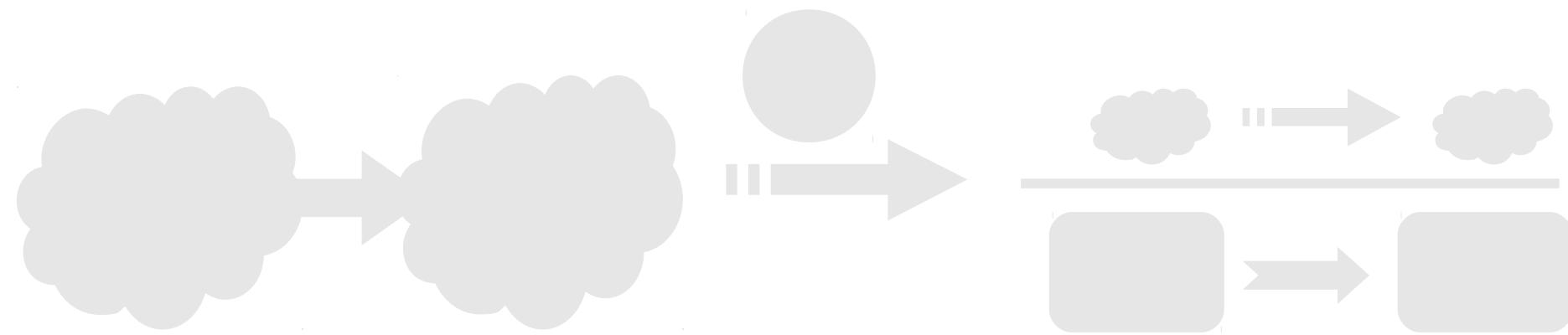
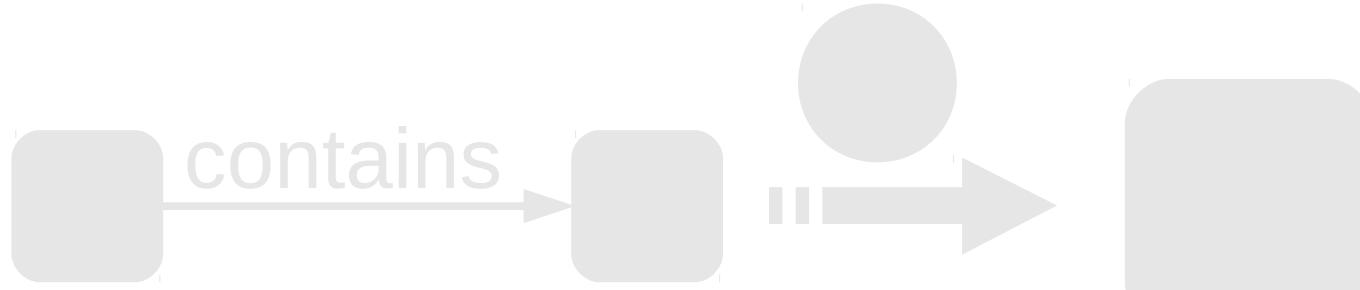
LOCAL  
SOS

$2^4$

$2^5$

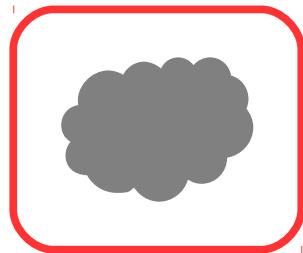
$2^6$

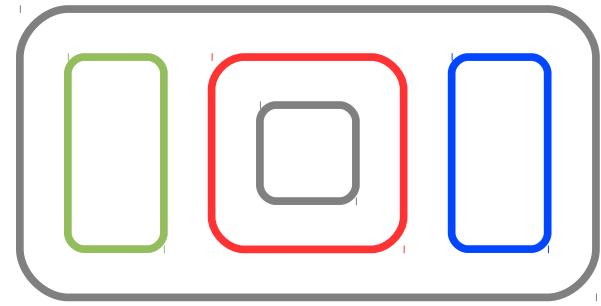


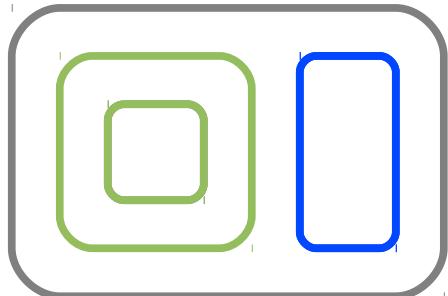
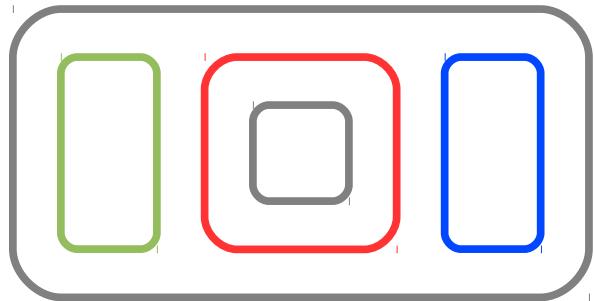




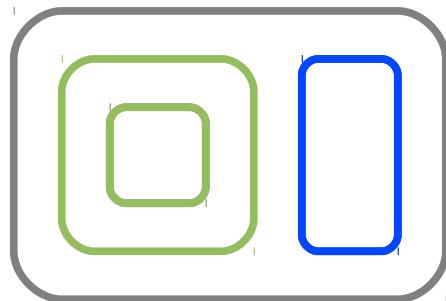
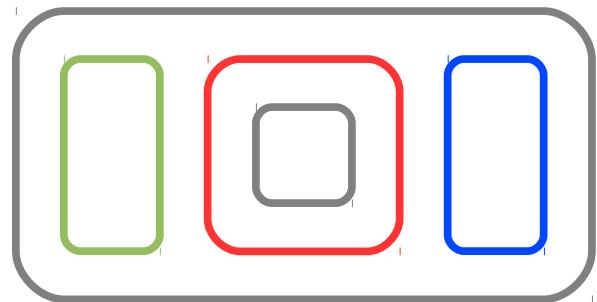
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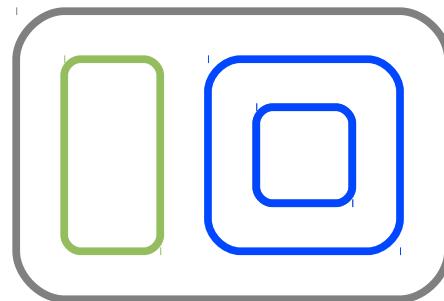


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or



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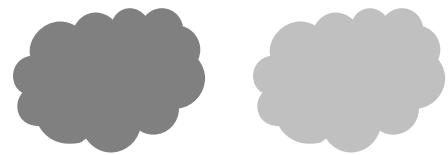
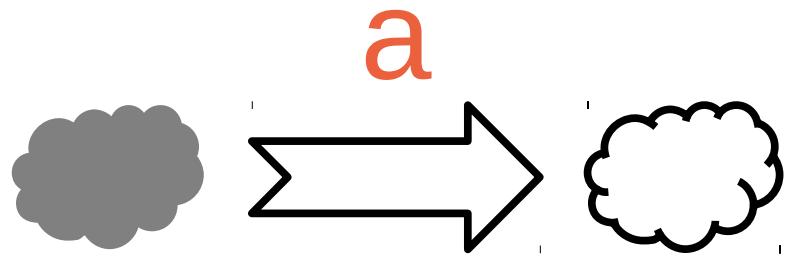
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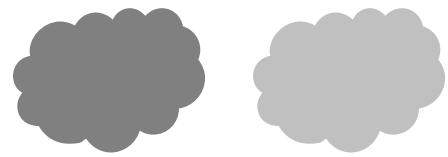
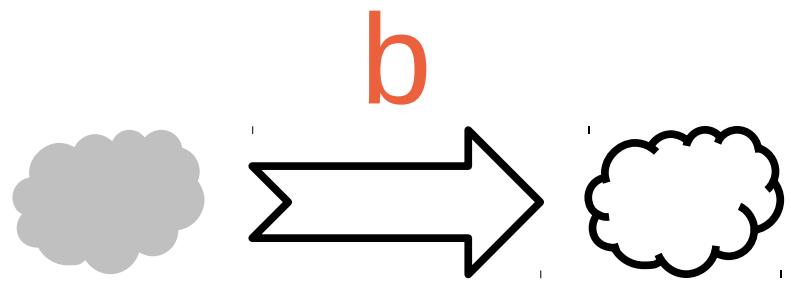
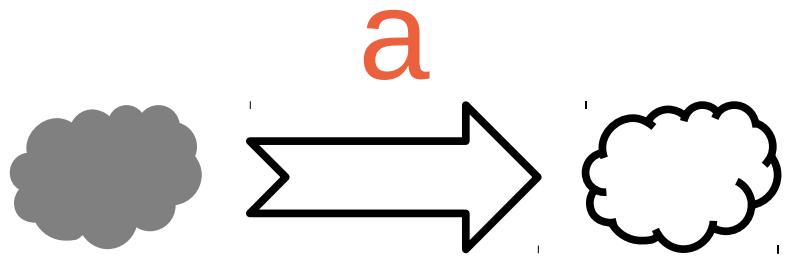


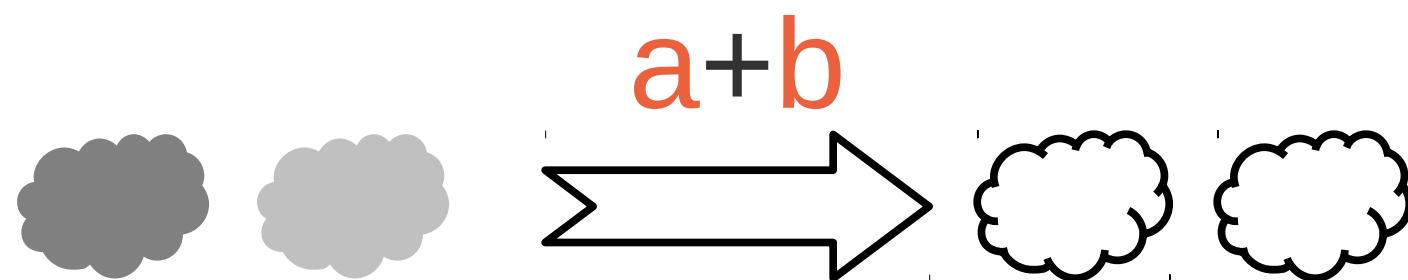
2







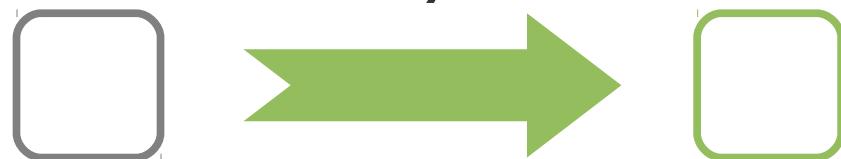




1\$,2h



2\$,1h





< A , + , x , 0 , 1 >

< Domain , choose , combine , worst , best >

< A , + , x , 0 , 1 >

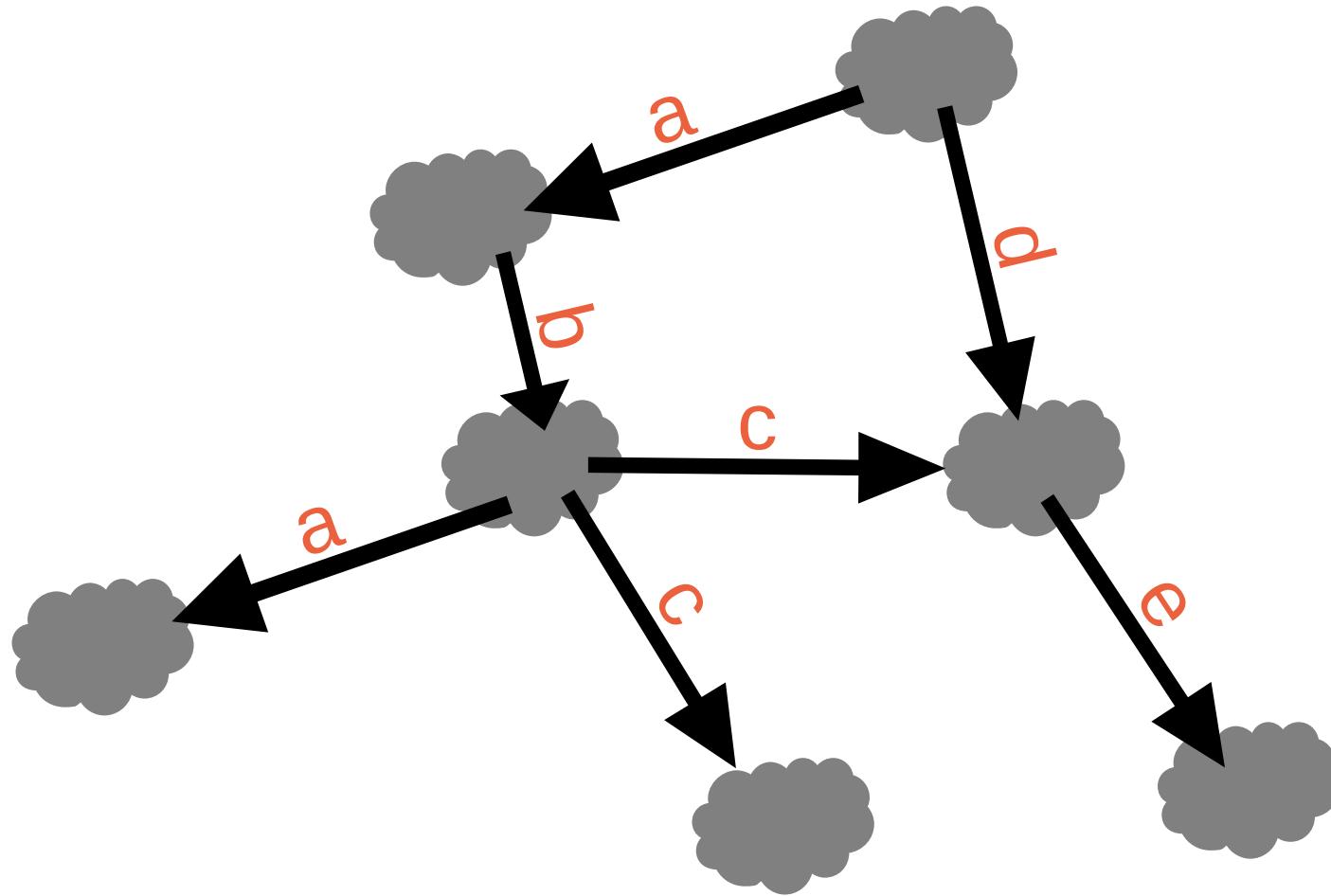
< Domain , choose , combine , worst , best >

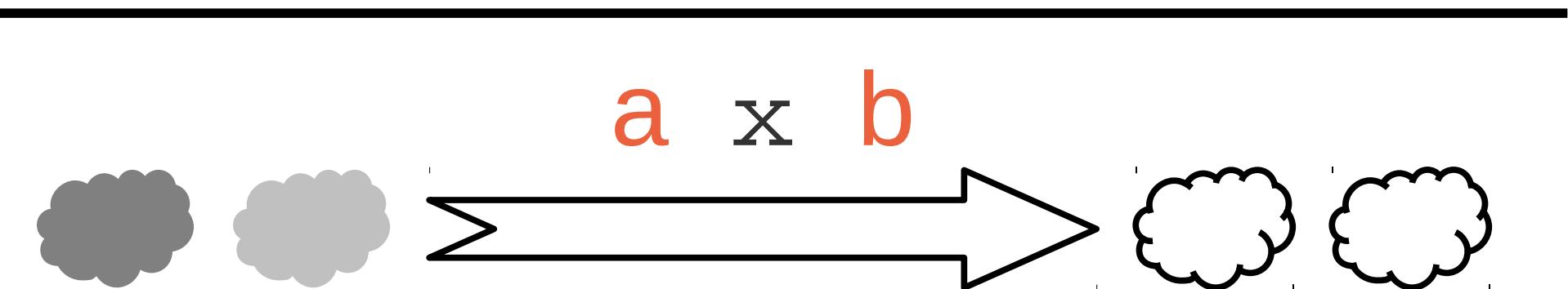
< Nat<sup>∞</sup> , min , + , ∞ , 0 >

< [0,1] , min , max , 0 , 1 >

< Bool , or , and , false , true >

$\langle \mathbf{A}, +, \mathbf{x}, 0, 1 \rangle \quad \times \quad \langle \mathbf{B}, +, \mathbf{x}, 0, 1 \rangle$  $=$  $\langle \mathbf{Ax} \mathbf{B}, (+, +), (\mathbf{x}, \mathbf{x}), (0, 0), (1, 1) \rangle$





# IMPLEMENTATION NOTES

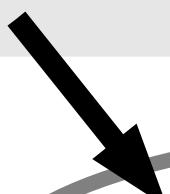
Object Configuration Module



Nested Object Configuration Module



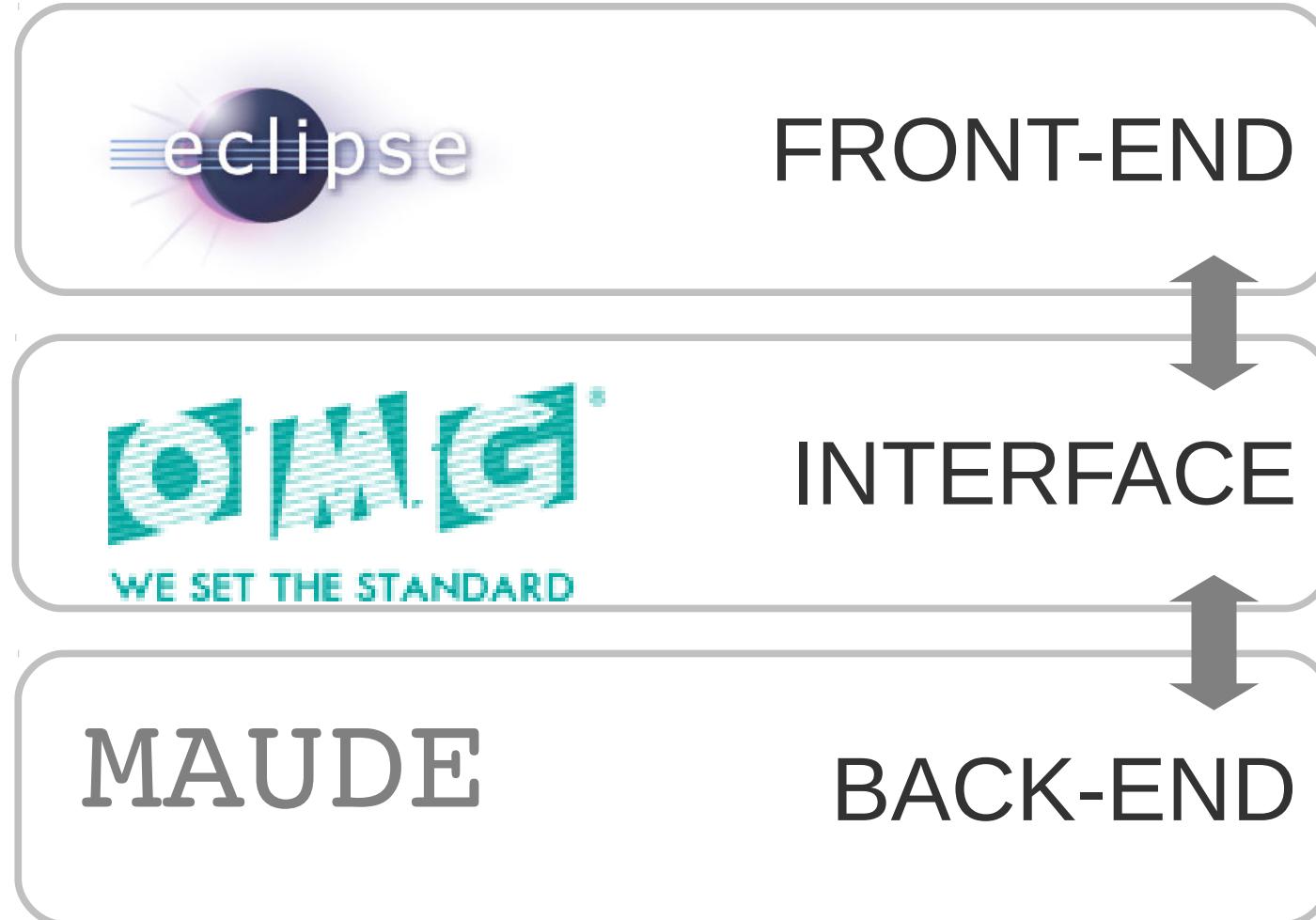
Rewrite rules



STATE SPACE

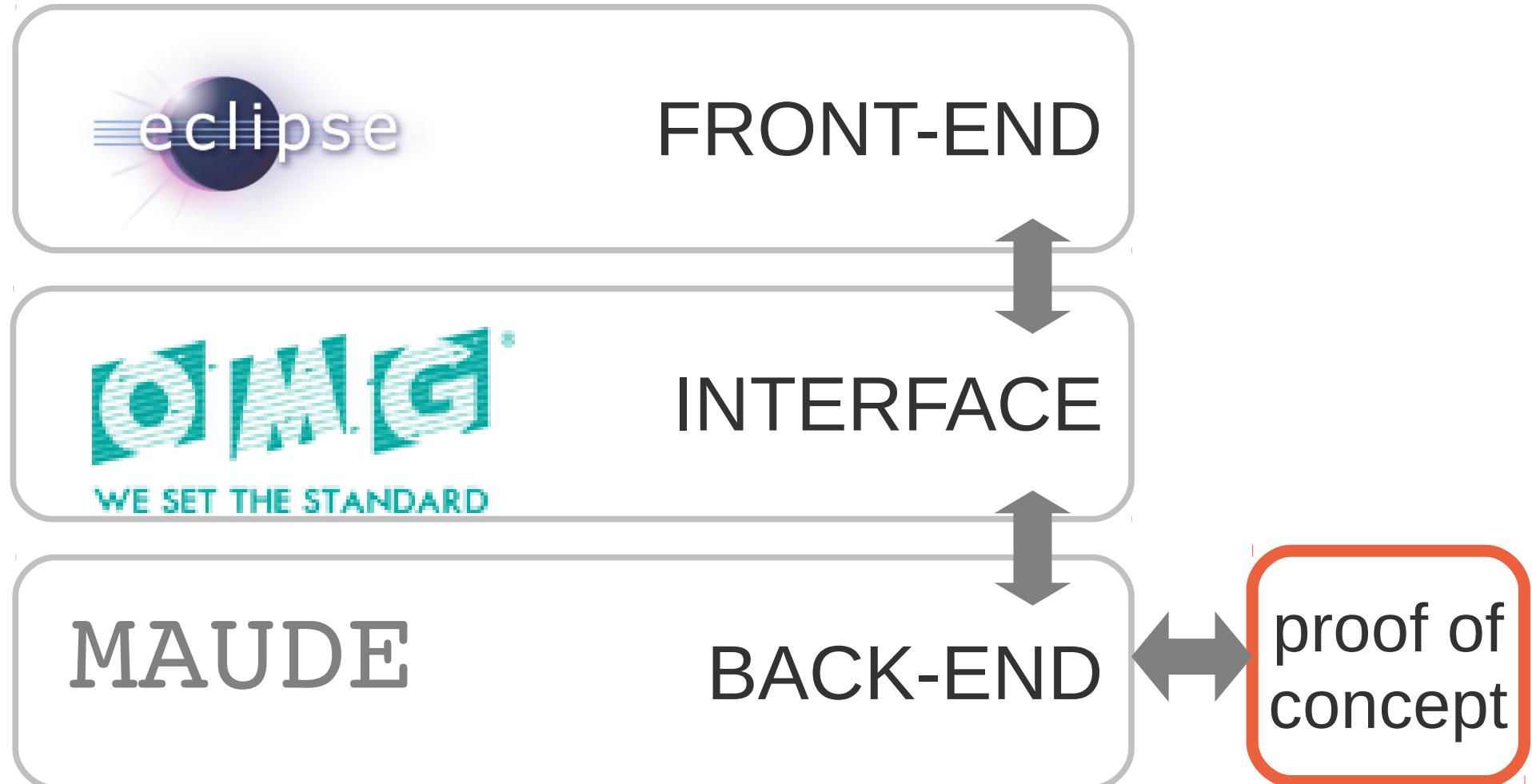
# MOMENT2

<http://www.cs.le.ac.uk/people/aboronat/tools/moment2-gt/>



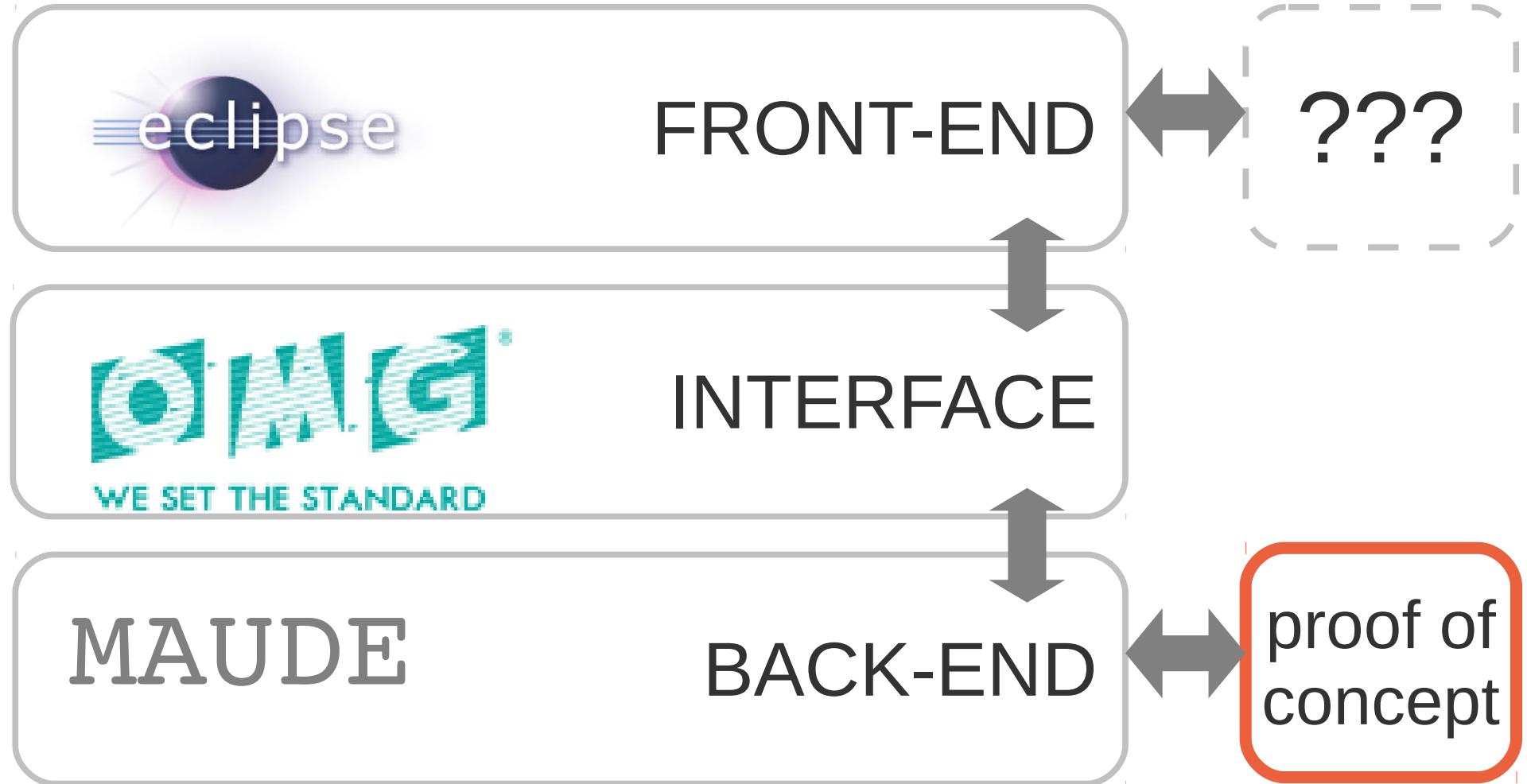
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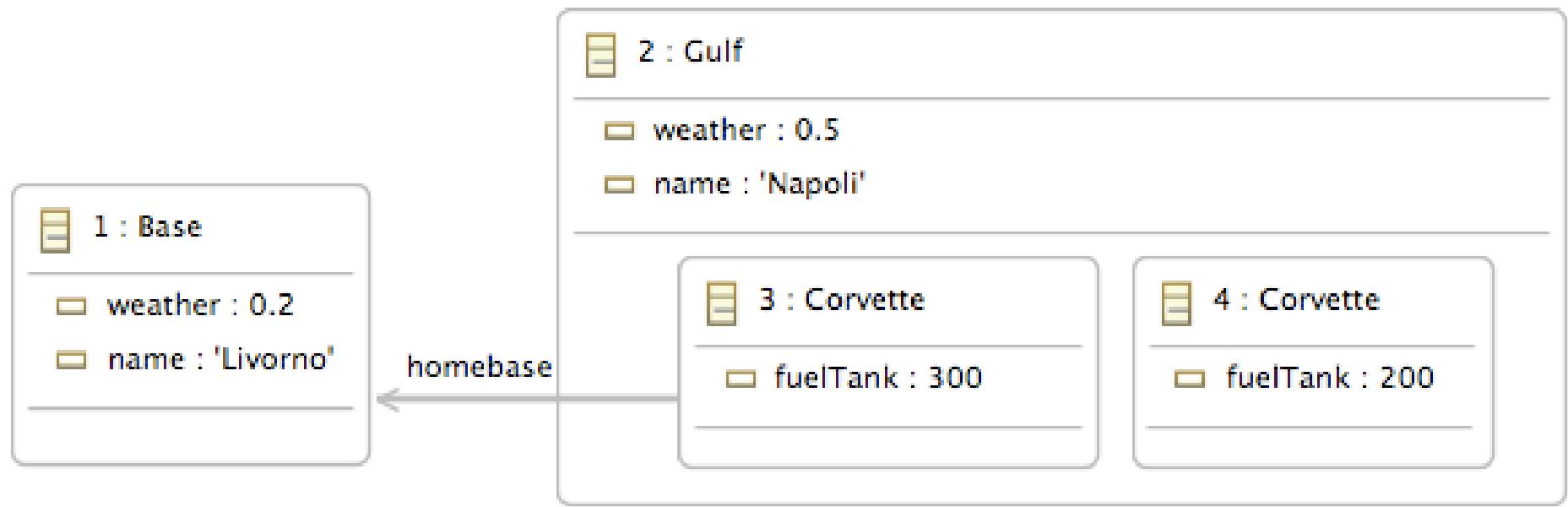
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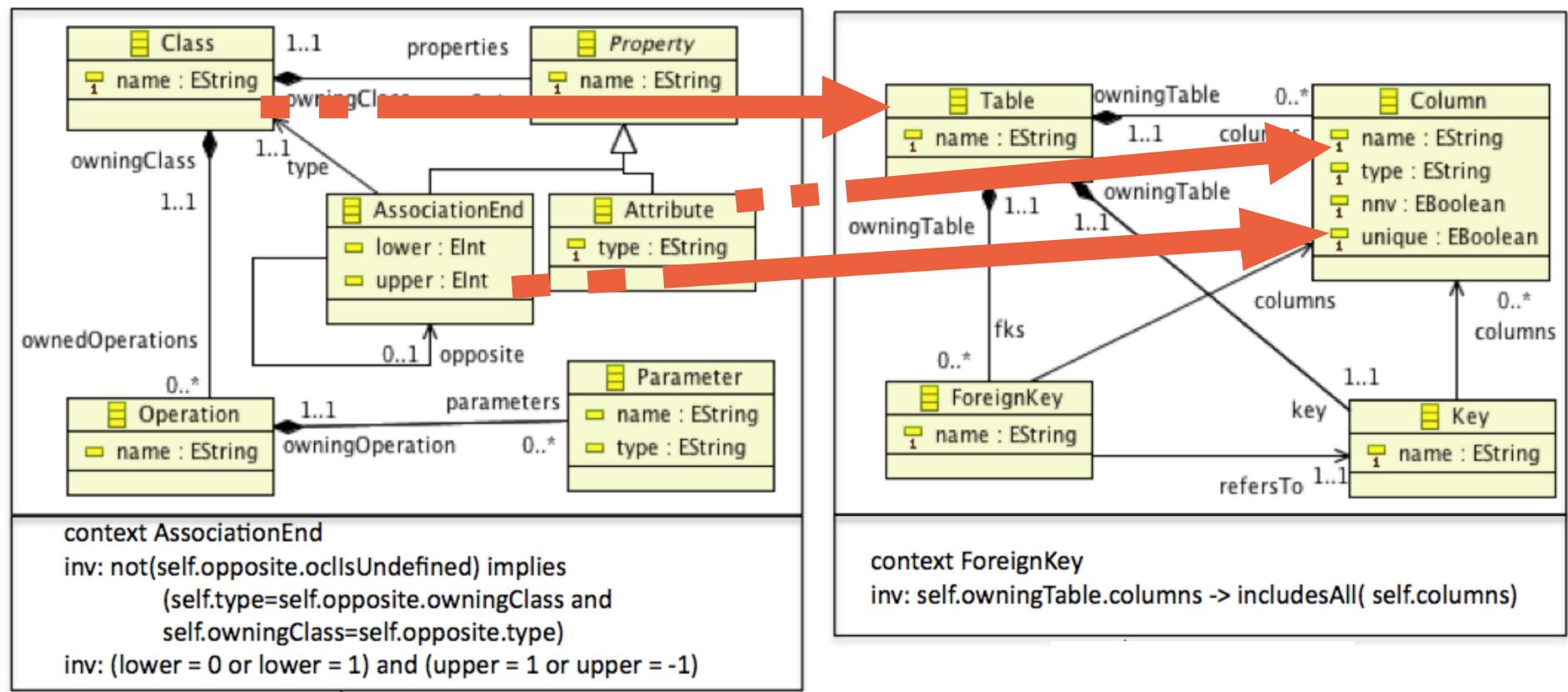
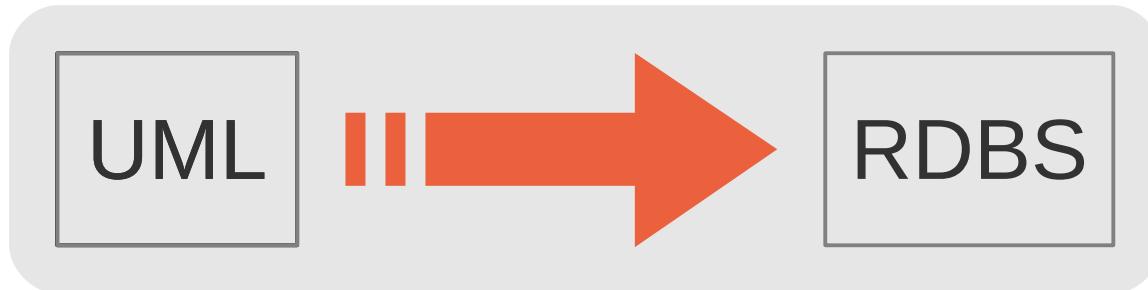


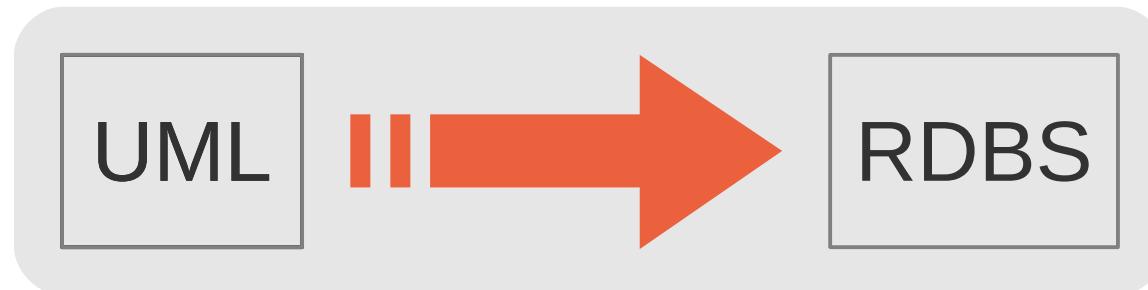
# MOMENT2

<http://www.cs.le.ac.uk/people/aboronat/tools/moment2-gt/>









A graph with two curves plotted against an implied vertical axis. The upper curve is a thick, dark gray line labeled "SPO" in black text, oriented diagonally upwards from left to right. The lower curve is a thick, orange-red line labeled "SOS" in black text, also oriented diagonally upwards but positioned below the SPO curve.

# CONCLUSION

FLAT



HIERARCHICAL

FLAT



HIERARCHICAL

SPO/REDUCTION



CRL/SOS

FLAT    

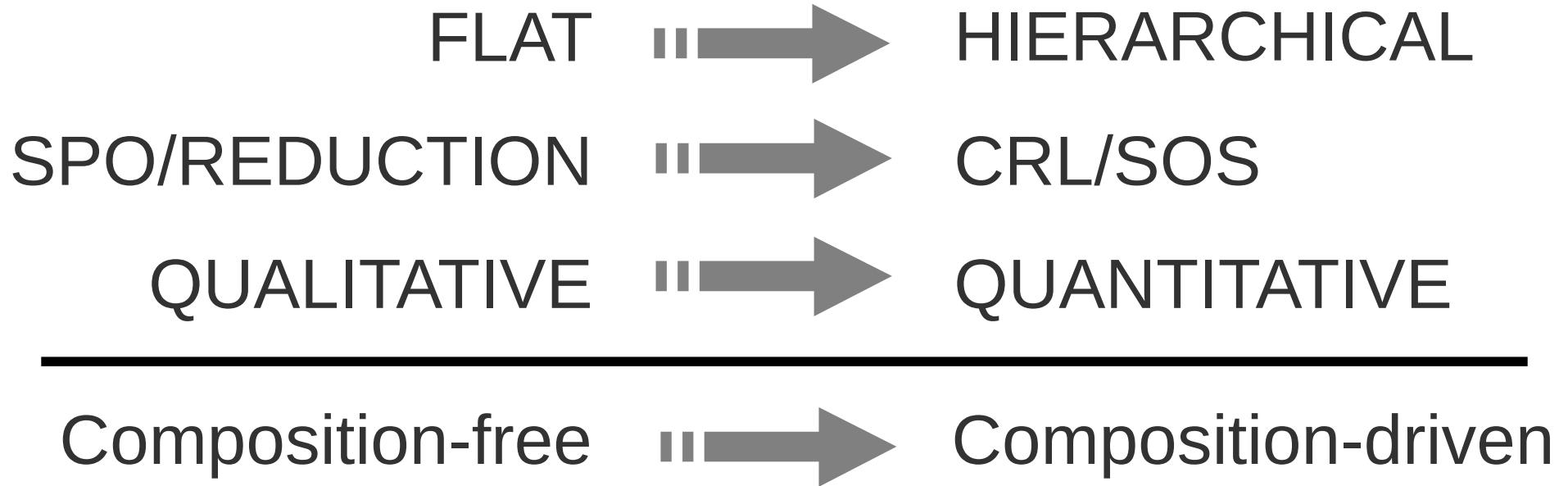
SPO/REDUCTION    

QUALITATIVE    

HIERARCHICAL

CRL/SOS

QUANTITATIVE



FLAT    

HIERARCHICAL

SPO/REDUCTION    

CRL/SOS

QUALITATIVE    

QUANTITATIVE

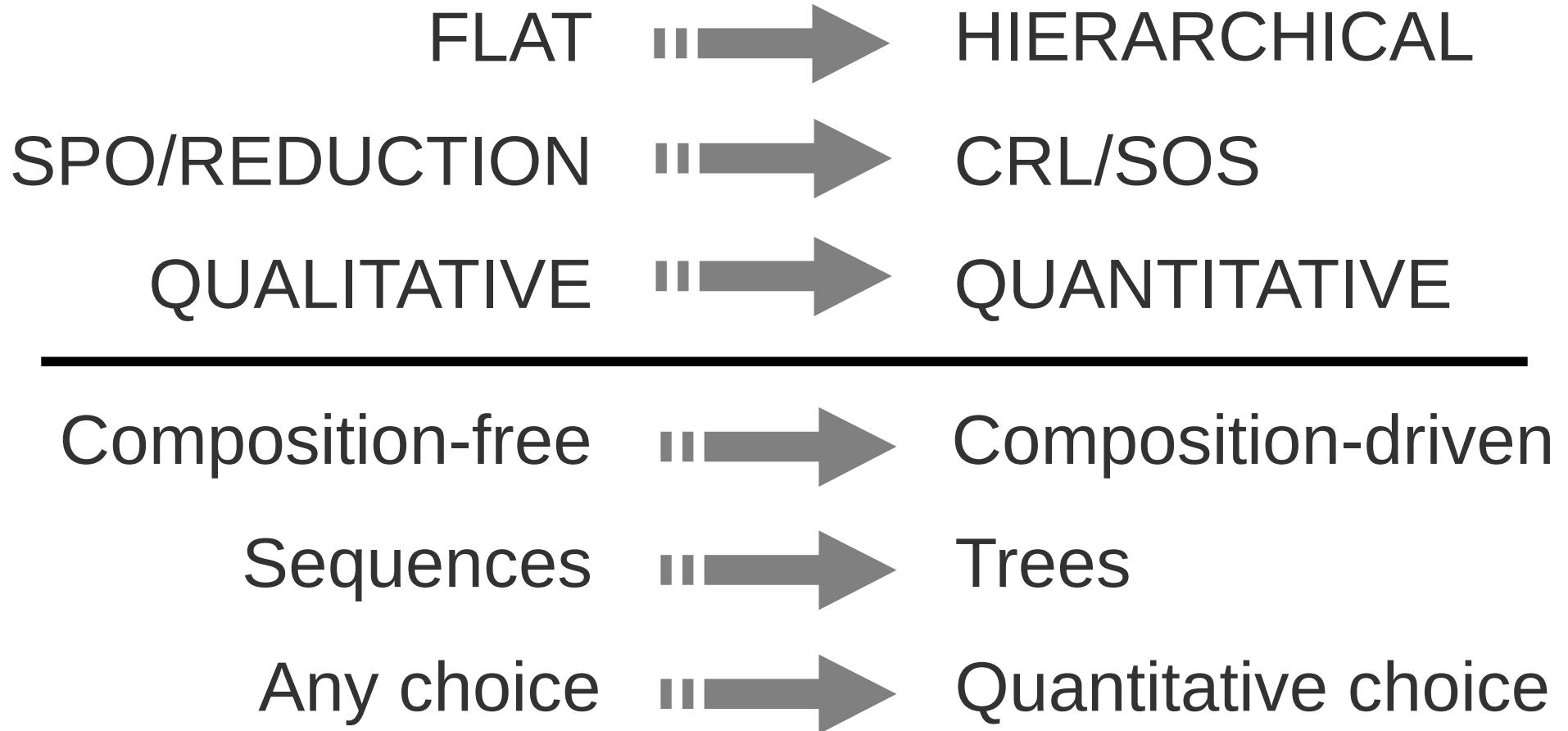
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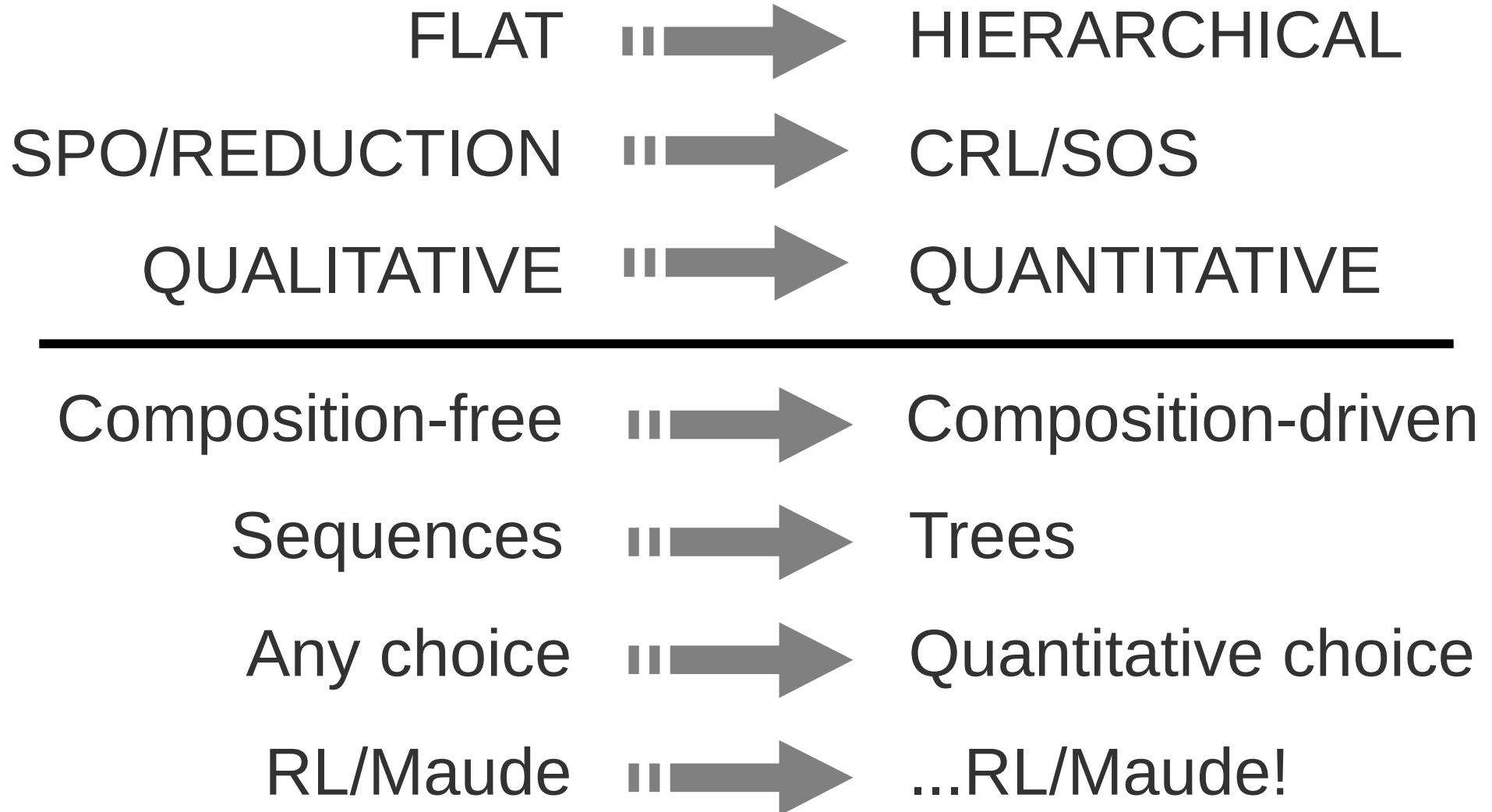
Composition-free    

Composition-driven

Sequences    

Trees





**THANKS!**



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