

On symbolic semantics for name-decorated contexts

(extended abstract)

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Contexts

Open systems: systems that are not fully specified at some point in time.

- components, processes, services
- autonomous, distributed, cross-domain
- dynamically reconfiguring

computation + interaction + dynamics

synchronisation may happen with “unkown” partners

Symbolic semantics

(Tractable) Abstractions of **unknown/infinite** behaviours.

Example:

the infinitely many messages an intruder can use to attack a security protocol.

$...?X....$ any (free to choose later on)
 $...?\{X\}_k...$ a message encrypted either
with k or with a different one

a kind of lazy/late evaluation/instantiation !

[Humia, Amadio, Boreale, ... early 00s]

Some (symbolic) approaches to open systems

1. bisimulation up to contexts, i.e. “determine the most general context [amongst the infinite ones] in which two process are bisimilar” [Larsen, et al. 90s];
2. from rewrite rules to bisimulation congruence, i.e. “extract the minimal context in which a reduction can happen as a precondition for SOS congruent transitions” [Sewell, Leifer-Milner, Sassone, Sobocinski,from late 90s];
3. minimal boolean conditions for value-passing semantics [Hennessy-Lin 95]
4. minimal (behavioural) requirements over (parallel) context for a transition to occur [Rensink 00],
5. saturated semantics [Bonchi-Montanari 06]
6. ... and others !

BBB approach

Define a semantics for open systems, i.e. contexts:

$$C[X]$$

BBB approach

Define a semantics for open systems, i.e. contexts:

$$C[X] = a.0|X$$

A term with X a process variable representing *any* ground process p (or even open context $D[Z]$).

BBB approach

Define a semantics for open systems, i.e. contexts:

$$C[X] = a.0|X \xrightarrow{X} a0|X$$

However, X either does nothing...

BBB approach

Define a semantics for open systems, i.e. contexts:

$$C[X] = a.0|X \xrightarrow{\diamond a Y} a.a.0|Y$$

... or it evolves alone ...

BBB approach

Define a semantics for open systems, i.e. contexts:

$$C[X] = a.0 | X \xrightarrow{\diamond \bar{a} Y} a Y$$

... or is able to synch.

as prescribed by the semantical rules (finite)!

BBB approach

Symbolic transition system:

$$C[X] \xrightarrow[\alpha]{\phi} D[Y]$$

1. abstracting from components not playing an active role in the transition;
2. specifying the active components as little as possible;
3. making assumptions both on the *structure* and on the *behaviour* of the active components (Spatial logics, [Cardelli, Gordon]).

BBB approach

Symbolic transition system:

$$C[X] \xrightarrow{\phi}_a D[Y]$$

The logic expresses the (minimal) capabilities required to plugged-in components so as to fire the next transition:

$$\phi ::= \dots \mid \diamond a.\phi' \mid \dots \mid f(\phi') \mid X$$

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and a satisfiability (with residuals) notion for ground processes, e.g.:

$$p \models \diamond a\phi' \text{ iff } \exists q. p \rightarrow_a q \wedge q \models \phi'$$

BBB approach

A notion of correspondence
(soundness and completeness) - informally:

$$C[X] \xrightarrow{\phi}_a D[Y]$$

\Uparrow

$$\forall p \models \phi[q/Y]$$

\Downarrow

$$C[p] \rightarrow_a D[q]$$

BBB approach

A constructive procedure based on unification:
Unify:

$$\frac{P \rightarrow_a P' \quad Q \rightarrow_{\bar{a}} Q'}{P|Q \rightarrow_{\tau} P'|Q'}$$

with

$$a.0|X$$

i.e.

$$a.0|X \xrightarrow{\diamond \bar{a} Y} Y$$

A reference *sound* and *complete* STS.

BBB approach

Natural definition of *strict symbolic bisimulation*:

$$\begin{array}{ccc} C[X] & \xrightarrow[\phi]{a} & C'[Y] \\ \sim_s & & \sim_s \\ D[X] & \xrightarrow[\phi]{a} & D'[Y] \end{array}$$

same (syntactic equality) formula!

BBB approach

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same (syntactic equality) formula!

Relaxation: *loose symbolic bisimulation*

$$\begin{array}{ccc} C[X] & \xrightarrow[\phi]{}_a & C'[Y] \\ \dot{\sim}_1 & & \dot{\sim}_1 \\ D[X] & \xrightarrow[\psi]{}_a & D'[Z] \text{ and } D'[\psi'] \end{array}$$

and $\exists \psi'$ spatial such that $\phi = \psi; \psi'$

BBB approach

$$C[X] \xrightarrow{\phi_1; \dots; \phi_h} \ell D[Y] \text{ if } C[X] \xrightarrow{\phi_1} \tau \cdots \xrightarrow{\phi_{k-1}} \tau \xrightarrow{\phi_k} \ell \xrightarrow{\phi_{k+1}} \tau \cdots \xrightarrow{\phi_h} \tau D[Y]$$

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strict *weak* symbolic bisimulation (symmetric!): \approx_s

$$\begin{array}{ccc} C[X] & \xrightarrow{\phi} \ell & C'[Y] \\ \approx_s & & \approx_s \\ D[X] & \xrightarrow{\phi} \ell & D'[Y] \end{array}$$

loose *weak* symbolic bisimulation (symmetric!): \approx_1

$$\begin{array}{ccc} C[X] & \xrightarrow{\phi} \ell & C'[Y] \\ \approx_1 & & \approx_1 \\ D[X] & \xrightarrow{\psi} \ell & D'[Y] \text{ and } D'[\psi'] \end{array}$$

and $\exists \psi'$ spatial such that $\phi = \psi; \psi'$

BBB approach

All the symbolic bisimilarities imply (are correct approximations of) universal bisimilarity:

$$\left. \begin{array}{l} \sim_s \Rightarrow \dot{\sim}_1 \\ \sim_s \Rightarrow \approx_s \\ \dot{\sim}_1 \Rightarrow \approx_1 \end{array} \right\} \Rightarrow \sim_u (\approx_u) \quad \forall p C[p] \sim D[p]$$

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Instantiation time matters !

$$C[X] = a.0 + a.b.0 + a.one_b(X)$$

$$D[X] = a.0 + a.b.0 + a.stop(X).$$

BBB approach

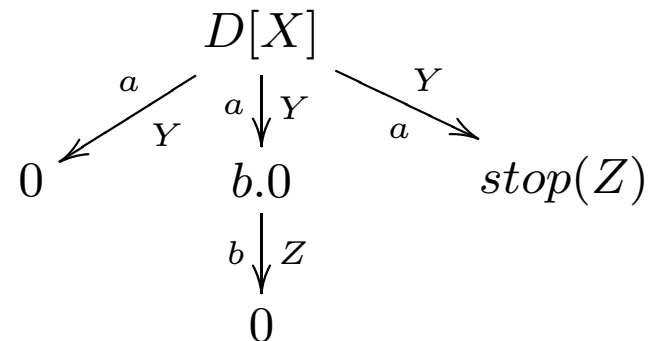
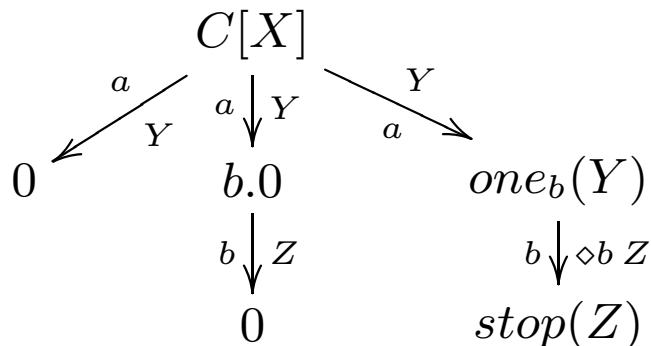
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Towards Names ...

Full name discipline in open processes is difficult.

E.g.

$$(\nu a)(a|X)$$

Is the a of any X the a of the restriction? (design choice)

Does α conversion commute with instantiation? (semantic choice)

...

Scenario: Web Crawlers

A simplistic proof-of-concept scenario.

$$s ::= \mathbf{0} \mid c \mid \text{link}(x, y) \mid s|s$$
$$c ::= \text{rash}(a, x, \tilde{y}) \mid \text{cautious}(a, x, \tilde{y}) \mid \text{scrupulous}(a, x, \tilde{y})$$

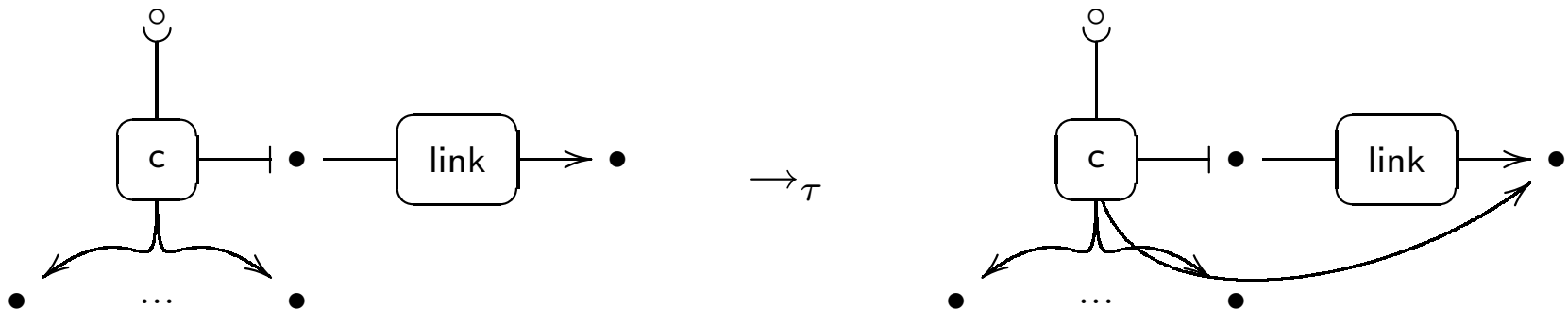
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$$c(a, x, \tilde{y}) \mid \text{link}(x, z) \mid s \xrightarrow{\tau} c(a, x, \tilde{y} + z) \mid \text{link}(x, z) \mid s$$



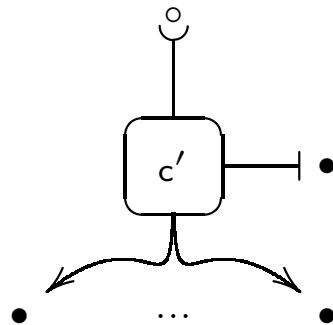
LEARN

Scenario: Web Crawlers

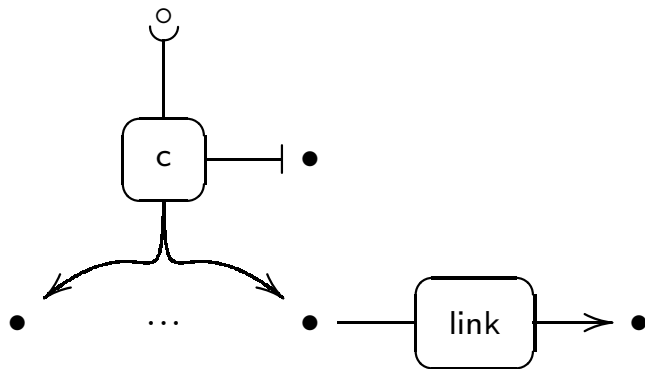
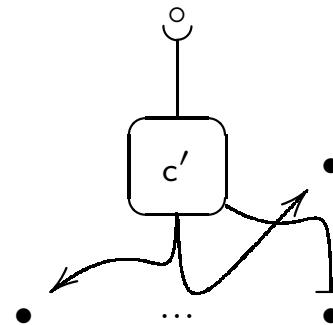
$\text{rash}(a, x, \tilde{y} + z) \mid s$
 $c(a, x, \tilde{y} + z) \mid \text{link}(z, w) \mid s$

\rightarrow_{τ}
 \rightarrow_{τ}

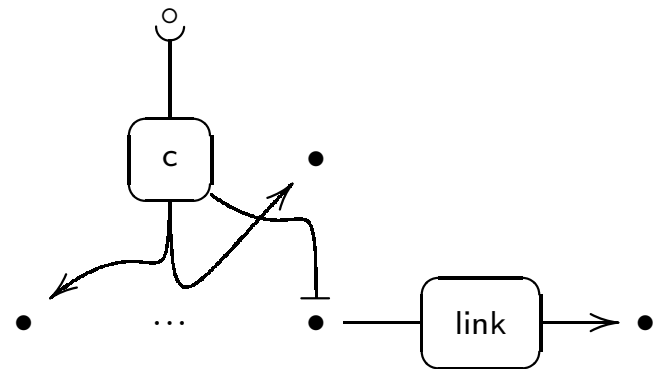
$\text{rash}(a, z, \tilde{y} + x) \mid s$
 $c(a, z, \tilde{y} + x) \mid \text{link}(z, w) \mid s$



\rightarrow_{τ}



\rightarrow_{τ}

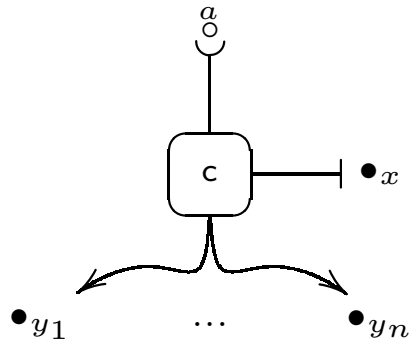


MOVE

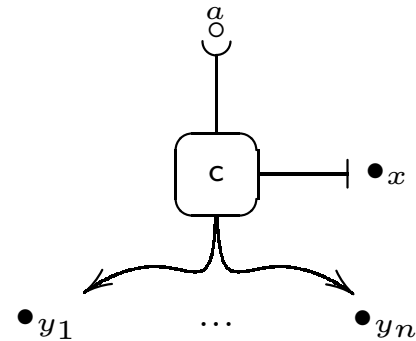
Scenario: Web Crawlers

$c(a, x, \tilde{y}) \mid s \rightarrow_{az}$
 $\text{scrupulous}(a, x, \tilde{y}) \mid s \rightarrow_{ax}$

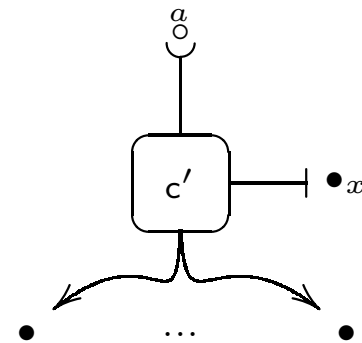
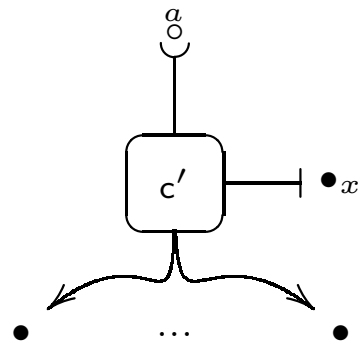
$c(a, x, \tilde{y}) \mid s$ with $z \in \tilde{y} + x$
 $\text{scrupulous}(a, x, \tilde{y}) \mid s$



\rightarrow_{az}



\rightarrow_{ax}



OBSERVE

Scenario: Web Crawlers

$$R[X] \stackrel{\text{def}}{=} \text{rash}(a, x, \tilde{y}) \mid X$$

$$K[X] \stackrel{\text{def}}{=} \text{cautious}(a, x, \tilde{y}) \mid X$$

$$S[X] \stackrel{\text{def}}{=} \text{scrupulous}(a, x, \tilde{y}) \mid X$$

$R[X]$	$\xrightarrow{\text{link}(x,z) \mid Y} \tau$	$\text{rash}(a, x, \tilde{y} + z) \mid \text{link}(x, z) \mid Y$	(for any z)
$R[X]$	$\xrightarrow{Y} \tau$	$\text{rash}(a, y_i, \tilde{y} + x - y_i) \mid Y$	
$R[X]$	$\xrightarrow{Y} ax$	$R[Y]$	
$R[X]$	$\xrightarrow{Y} ay_i$	$R[Y]$	
$K[X]$	$\xrightarrow{\text{link}(x,z) \mid Y} \tau$	$\text{cautious}(a, x, \tilde{y} + z) \mid \text{link}(x, z) \mid Y$	(for any z)
$K[X]$	$\xrightarrow{\text{link}(y_i,z) \mid Y} \tau$	$\text{cautious}(a, y_i, \tilde{y} + x - y_i) \mid \text{link}(y_i, z) \mid Y$	(for any z)
$K[X]$	$\xrightarrow{Y} ax$	$K[Y]$	
$K[X]$	$\xrightarrow{Y} ay_i$	$K[Y]$	
$S[X]$	$\xrightarrow{\text{link}(x,z) \mid Y} \tau$	$\text{scrupulous}(a, x, \tilde{y} + z) \mid \text{link}(x, z) \mid Y$	(for any z)
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$S[X]$	$\xrightarrow{Y} ax$	$S[Y]$	

Scenario: Web Crawlers

Universally:

$$\text{rash}(a, x, \tilde{y})|s \approx_u \text{cautious}(a, x, \tilde{y})|s$$

(they communicate all the addresses they gather – valid or not)

$$\text{rash}(a, x, \emptyset)|\text{link}(x, y) \not\approx_w \text{scrupulous}(a, x, \emptyset)|\text{link}(x, y)$$

$$\text{R}[X] \not\approx_u \text{S}[X] \not\approx_u \text{K}[X] \approx_u \text{R}[X]$$

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$$\text{R}[X] \not\approx_u \text{S}[X] \not\approx_u \text{K}[X] \approx_u \text{R}[X]$$

Symbolically:

$$\begin{array}{l} \text{R}[X] \\ \text{K}[X] \end{array} \xrightarrow[\text{link}(y_i, z)|Y]{Y} \tau \quad \begin{array}{l} \text{rash}(a, y_i, \tilde{y} + x - y_i) | Y \\ \text{cautious}(a, y_i, \tilde{y} + x - y_i) | \text{link}(y_i, z) | Y \end{array} \quad (\text{for any } z)$$

$$\text{R}[X] \not\approx_s \text{K}[X]$$

$$\text{R}[X] \approx_1 \text{K}[X]$$

Scenario: Web Crawlers

$$K[X] \not\approx_1 S[X]$$

$S[X]$ observes only valid sites y_i :

$$S[X] \xrightarrow{\text{link}(y_i, z) | Y} \tau \text{ scrupulous}(a, y_i, \tilde{y} + x - y_i) \mid \text{link}(y_i, z) \mid Y \xrightarrow{Y} a y_i \dots$$

while $K[X]$ observes known sites:

$$K[X] \xrightarrow{Y} a y_i K[Y]$$

cautious \approx_1 scrupulous on a “valid” (no broken link) network!

Typed symbolic semantics

Types as contracts!

(Software Architectures: Type as Interfaces; Service-Oriented Computing: Types as Service (level) Contract; ...).

Types discipline a (naive - e.g. no restriction) form of names:

$$s : T_{\tilde{d}, \tilde{p}} \text{ iff}$$

- for any $x \in \tilde{d}$ there exists y such that s contains $\text{link}(x, y)$;
- for any link $\text{link}(x, y)$ in s such that $y \notin \tilde{p}$ then it must be the case that $\text{link}(y, z)$ is in s for some z .

$$s \text{ valid if } s : T_{-, \emptyset}$$

- every s has a type;
- subject-reduction;

$$C[X : T_{\tilde{d}, \tilde{p}}] \approx_u D[X : T_{\tilde{d}, \tilde{p}}] \text{ if for any } s : T_{\tilde{d}, \tilde{p}} \quad C[s] \approx D[s]$$

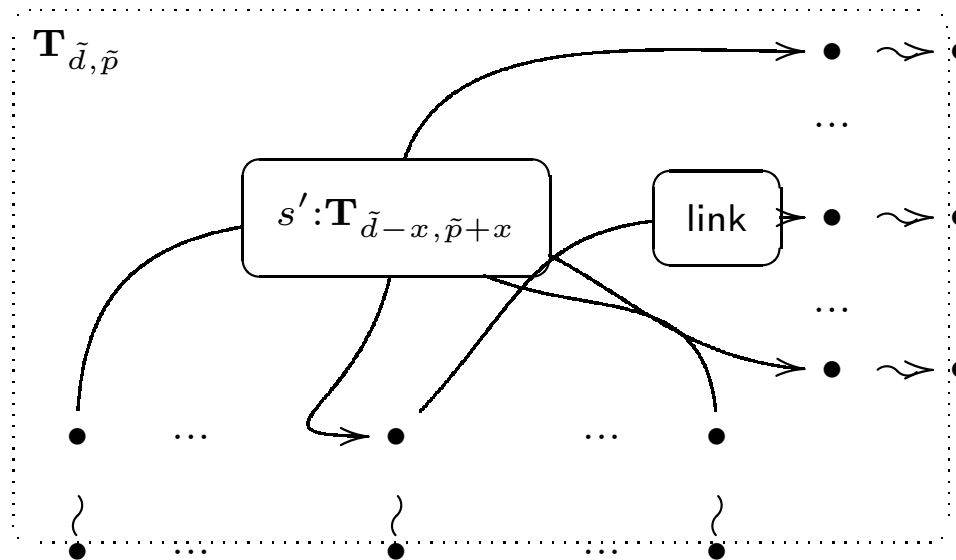
Typing context variables

1) Decomposing types (type structural equivalence \equiv_T):

$$s : T_{\tilde{d}, \tilde{p}} \text{ iff}$$

- $s \equiv_T \text{link}(x, y) | s'$ and $s' : T_{\tilde{d}-x, \tilde{p}+x}$, or
- $s \equiv_T \text{link}(x, z) | s'$ and $s' : T_{\tilde{d}-x+z, \tilde{p}+z+x}$.

with $x \in \tilde{d}$, $y \in \tilde{p}$, $z \notin \tilde{p}$



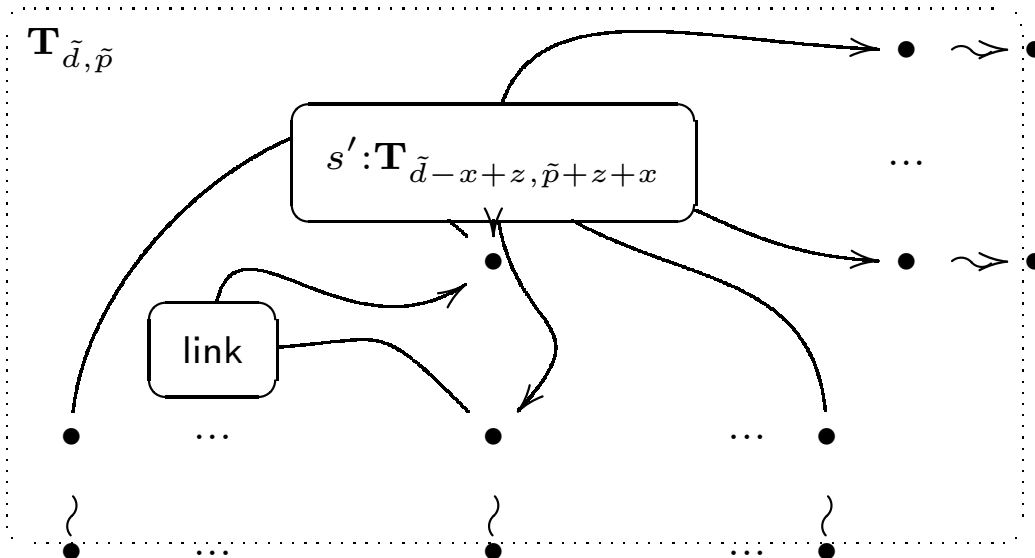
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with $x \in \tilde{d}$, $y \in \tilde{p}$, $z \notin \tilde{p}$



Typing context variables

2) Decorating symbolic transitions, e.g.:

$$C[X : T_{\tilde{d}, \tilde{p}}] \equiv_T C[\text{link}(x, y) \mid Y : T_{\tilde{d}-x, \tilde{p}+x}] \xrightarrow{Y} \alpha D[\tilde{d}-x, \tilde{p}+x] \text{ if } y \in \tilde{p}$$

$$C[X : T_{\tilde{d}, \tilde{p}}] \equiv_T C[\text{link}(x, y) \mid Y : T_{\tilde{d}-x+y, \tilde{p}+y+x}] \xrightarrow{Y} \alpha D[Y : T_{\tilde{d}-x+y, \tilde{p}+y+x}] \text{ if } y \notin \tilde{p}$$

3) Considering **decorated** weak loose symbolic bisimulation in the decorated symbolic transition system up to \equiv_T (\approx_d).

Typed symbolic semantics

Finally,

$$S[X : T_{\tilde{y}+x, \emptyset}] \approx_d K[X : T_{\tilde{y}+x, \emptyset}]$$

Indeed

$$K[X : T_{\tilde{y}+x, \emptyset}] \xrightarrow{Y}_{ay_i} K[Y : T_{\tilde{y}+x, \emptyset}]$$

can be weakly simulated by the symbolic moves

$$S[X : T_{\tilde{y}+x, \emptyset}] \equiv_T S[\text{link}(y_i, z) | Y : T_{\tilde{y}+x-y_i, y_i}] \xrightarrow{Y}_{ay_i} \\ \text{scrupulous}(a, y_i, \tilde{y} + x - y_i) | \text{link}(y_i, z) | Y : T_{\tilde{y}+x-y_i, y_i} \quad (z \in \tilde{y} + x)$$

and

$$S[X : T_{\tilde{y}+x, \emptyset}] \equiv_T S[\text{link}(y_i, z) | Y : T_{\tilde{y}+x-y_i+z, y_i+z}] \xrightarrow{Y}_{ay_i} \\ \text{scrupulous}(a, y_i, \tilde{y} + x - y_i) | \text{link}(y_i, z) | Y : T_{\tilde{y}+x-y_i+z, y_i+z} \quad (z \notin \tilde{y} + x)$$

(whose target states are again bisimilar)

Summing up

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- a more complete scenario to be addressed (restriction)

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- a toy implementation to play with
`www.di.unipi.it/ lafuenta/ice08`