## LR(1) Parsers

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## Building LR(1) Tables

How do we build the parse tables for an LR(1) grammar?

- Encode actions \& transitions into the ACTION \& GOTO tables
- If construction succeeds, the grammar is LR(1)
- "Succeeds" means defines each table entry uniquely

The Big Picture

- Model the state of the parser with "LR(1) items"
- The states will be set of $L R(1)$ items
- Use two functions goto( $s, X$ ) and closure(s)
- goto() tells which state you reach
- closure() adds information to round out a state
- Build up the states (sets of LR(1) items) and transitions
- Use this information to fill in the ACTION and GOTO tables

LR(1) Items
We represent a valid configuration of an LR(1) parser with a data structure called an LR(1) item

An $\operatorname{LR}(1)$ item is a pair $[P, \delta]$, where $P$ is a production $A \rightarrow \beta$ with a at some position in the rhs $\delta$ is a lookahead string of length $\leq 1$ (word or EOF )

The - in an item indicates which portion of the righthandside of the production we have seen on the top of the stack

## Meaning of an LR(1) Item

$[A \rightarrow \cdot \beta \gamma, \underline{a}]$ means that the input seen so far is consistent with the use of
$A \rightarrow \beta y$ immediately after the symbol on top of the stack
"possibility"
$[A \rightarrow \beta \cdot \gamma, \underline{a}]$ means that the input sees so far is consistent with the use of
$A \rightarrow \beta y$ at this point in the parse, and that the parser has already recognized $\beta$ (that is, $\beta$ is on top of the stack)
"partially complete"
$\left[A \rightarrow \beta \gamma^{\cdot}, \underline{a}\right]$ means that the parser has seen $\beta \gamma$, and that a lookahead symbol of $\underline{a}$ is consistent with reducing to $A$

## LR(1) Items

The production $A \rightarrow \beta$, where $\beta=B_{1} B_{2} B_{3}$ with lookahead $\underline{a}$, can give rise to 4 items

$$
\left[A \rightarrow \cdot B_{1} B_{2} B_{3}, q\right],\left[A \rightarrow B_{1} \cdot B_{2} B_{3}, \underline{q}\right],\left[A \rightarrow B_{1} B_{2} \cdot B_{3}, q\right], \&\left[A \rightarrow B_{1} B_{2} B_{3} \cdot, \underline{q}\right]
$$

The set of $L R(1)$ items for a grammar is finite

What's the point of all these lookahead symbols?

- Carry them along to help choose the correct reduction
- Lookahead are bookkeeping, unless item has - at right end
- Has no direct use in [ $A \rightarrow \beta \cdot \gamma, \underline{a}$ ]
- In $[A \rightarrow \beta \cdot, \underline{a}$, a lookahead of $\underline{a}$ implies a reduction by $A \rightarrow \beta$
- For a parser state modelled with items $\{[A \rightarrow \beta \cdot, \underline{a}],[B \rightarrow \gamma \cdot \delta, \underline{b}]\}$, lookahead of $\underline{a} \Rightarrow$ reduce to $A$; lookahead in FIRST $(\delta) \Rightarrow$ shif $\dagger$
$\Rightarrow$ Limited right context is enough to pick the actions


## LR(1) Table Construction

High-level overview
1 Build the canonical collection of sets of LR(1) Items
a Start with an appropriate initial sate $s_{0}$

- [S' $\rightarrow \cdot$ SEOF], along with any equivalent item
- Derive equivalent items as closure ( $s_{0}$ )
b Repeatedly compute, for each $s_{k}$, and each symbol $X$, goto $\left(s_{k}, X\right)$
- If the set is not already in the collection, add it
- Record all the transitions created by goto( )

This eventually reaches a fixed point

## Computing Closures

Closure(s) adds all the items implied by the items already in $s$

- Item $[A \rightarrow \beta \cdot C \delta, a]$ in s implies $[C \rightarrow \bullet \tau, x]$ for each production with $C$ on the Ihs, and each $x \in \operatorname{FIRST}(\delta a)$
- Since $\beta C \delta$ is a valid rewriting, any way to derive $\beta C \delta$ is a valid rewritting, too
The algorithm

```
Closure(s )
    while ( }s\mathrm{ is still changing )
```



```
    \forallproductions C }->\tau\in
    \forall\underline{x}\in\operatorname{FIRST}(\delta\underline{a}) // \deltamight be \varepsilon
        if [C->\cdot\tau,\underline{x}]\not\ins
        then }s\leftarrows\cup{[C->\cdot\tau,\underline{x}]
```

- Classic fixed-point method
- Halts because s $\subset$ Items
- Closure "fills out" a state


## Example From SheepNoise

| Goal | $\rightarrow$ | SheepNoise |
| :--- | :--- | :--- |
| SheepNoise | $\rightarrow$ | SheepNoise baa |
|  | 1 | $\underline{\text { baa }}$ |

Initial step builds the item [Goal $\rightarrow$ •SheepNoise,EOF] and takes its closure( )

Closure $([$ Goal $\rightarrow$ •SheepNoise,EOF] )

| \# | Item | Derived from ... |
| :---: | :---: | :---: |
| 1 | [Goal $\rightarrow$ • SheepNoise,EOF] | Original item |
| 2 | [SheepNoise $\rightarrow$ • SheepNoise baa, EOF] | $1, \delta \underline{a}$ is EOF |
| 3 | [SheepNoise $\rightarrow$ - baa, EOF] | $1, \delta \underline{a}$ is EOF |
| 4 | [SheepNoise $\rightarrow$ • SheepNoise baa, baa] | $2, \delta \underline{\text { is baa }}$ |
| 5 | [SheepNoise $\rightarrow$ • baa, baa] | $2, \delta \underline{\text { is baa }}$ |
|  | stop! | $4 \delta \alpha$ is baa b |

$\mathrm{S}_{0}$ (the first state) is
$\{[$ Goal $\rightarrow$ • SheepNoise, EOF ], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF ],
[SheepNoise $\rightarrow \cdot$ baa, EOF], [SheepNoise $\rightarrow \cdot$ SheepNoise baa,baa],
[SheepNoise $\rightarrow$ • baa, baa] \}

## Computing Gotos

Goto( $s, x$ ) computes the state that the parser would reach if it recognized an $x$ while in state $s$

- Goto( $\{[A \rightarrow \beta \bullet X \delta, \underline{a}]\}, X)$ produces $[A \rightarrow \beta X \bullet \delta, \underline{a}] \quad$ (obviously)
- It finds all such items \& uses closure() to fill out the state

The algorithm

```
Goto(s,X)
    new <\varnothing
    \forall items [A->\beta\cdotX\delta,q] Gs
        new }\leftarrow\mathrm{ new }\cup{[A->\betaX\cdot\delta,q]
    return closure(new)
```

- Not a fixed-point method!
- Straightforward computation
- Uses closure( )


## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| 2 | SheepNoise baa |  |
| 2 | baa |  |

$S_{0}$ is $\{[G o a l \rightarrow \cdot$ SheepNoise, EOF ], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF], [SheepNoise $\rightarrow$ •baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa], [SheepNoise $\rightarrow$ •baa,baa] \}

Goto( $S_{0}$, baa )

- Loop produces

| Item | Source |
| :--- | :--- |
| [SheepNoise $\rightarrow \underline{\text { baa }} \bullet$, EOF $]$ | Item 3 in $s_{0}$ |
| [SheepNoise $\rightarrow$ baa $\bullet$, baa] | Item 5 in $s_{0}$ |

- Closure adds nothing since - is at end of rhs in each item


## Building the Canonical Collection: The algorithm

```
so}\leftarrowclosure ([S'->.cS,EOF]
S}\leftarrow{\mp@subsup{s}{0}{}
k}\leftarrow
while ( }S\mathrm{ is still changing)
    \forall\mp@subsup{s}{j}{}\inS and }\forallx\in(T\cupNT
        t}\leftarrow\mathrm{ goto(s (s,x)
        if t }\not\inS\mathrm{ then
        name clousure(t) as sk
        S\leftarrowS \cup{ Sk
        record sj }->\mp@subsup{s}{k}{}\mathrm{ on x
        k}\leftarrow\textrm{k}+
        else
        t is }\mp@subsup{s}{m}{}\in
        record sj }->\mp@subsup{S}{m}{}\mathrm{ on x
```

Start from $s_{0}=$ closure $\left(\left[S^{\prime} \rightarrow \cdot S, E O F\right]\right)$
Repeatedly construct new states, until all are found

- Fixed-point computation
- Loop adds to S
- $S \subseteq 2$ ITEMS, so $S$ is finite


## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| SheepNoise $\underline{\text { baa }}$ |  |  |
| 2 |  | $\underline{\text { baa }}$ |

Starts with $\mathrm{S}_{0}$
$S_{0}:\{[$ Goal $\rightarrow$ • SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF],
[SheepNoise $\rightarrow$ •baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa],
[SheepNoise $\rightarrow$ • baa, baa] \}
Iteration 1 computes
$\mathrm{S}_{1}=\operatorname{Goto}\left(\mathrm{S}_{0}\right.$, SheepNoise $)=$
$\{$ [Goal $\rightarrow$ SheepNoise • , EOF], [SheepNoise $\rightarrow$ SheepNoise • baa, EOF],
[SheepNoise $\rightarrow$ SheepNoise - baa, baa] $\} \quad$ No more for closure!
$S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow \underline{\text { baa } \cdot} \cdot \underline{\text { EOF }}]$,
[SheepNoise $\rightarrow$ baa $\cdot$, baa] $\}$
Iteration 2 computes

$$
\begin{aligned}
S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{ & {[\text { SheepNoise } \rightarrow \text { SheepNoise } \underline{\text { baa }} \cdot, \underline{\text { EOF }}], } \\
& {[\text { SheepNoise } \rightarrow \text { SheepNoise } \underline{\text { baa }} \cdot, \underline{\text { baa }]\}}\} }
\end{aligned}
$$

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| 2 | SheepNoise baa |  |
| 2 |  | baa |

$S_{0}:\{[$ Goal $\rightarrow$ • SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF], [SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa], [SheepNoise $\rightarrow$ • baa, baa] \}
$S_{1}=\operatorname{Goto}\left(S_{0}\right.$, SheepNoise $)=$
$\{$ [Goal $\rightarrow$ SheepNoise • , EOF], [SheepNoise $\rightarrow$ SheepNoise • baa, EOF],
[SheepNoise $\rightarrow$ SheepNoise - baa, baa] \}
$S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow \underline{\text { baa } \cdot} \cdot \underline{\text { EOF }}]$,
[SheepNoise $\rightarrow$ baa $\cdot$, baa] $\}$
$S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow$ SheepNoise baa $\cdot, \underline{E O F}]$,
[SheepNoise $\rightarrow$ SheepNoise baa $\cdot$, baa] $\}$

## Filling in the ActiON and Goto Tables

The algorithm $\mid x$ is the state number

$$
\forall \text { set } S_{x} \in S
$$

$\forall$ item $i \in S_{x}$
case $1\left\{\begin{aligned} \text { if } i \text { is }[A \rightarrow \beta \bullet \underline{a} \delta, \underline{b}] \text { and } \operatorname{goto}\left(S_{x}, \underline{a}\right)=S_{k}, \underline{a} \in T & \cdot \text { before terminal } \\ & \Rightarrow \text { shift }\end{aligned}\right.$ then $\operatorname{ACTION}[x, \underline{a}] \leftarrow$ "shift $k$ "

$\forall n \in N T$
if $\operatorname{goto}\left(S_{x}, n\right)=S_{k}$ then GOTO $[x, n] \leftarrow k$

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| SheepNoise baa |  |  |
| 2 |  | $\underline{\text { baa }}$ |

$S_{0}:\{[$ Goal $\rightarrow$ • SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF], [SheepNoise $\rightarrow$ baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa], [SheepNoise $\rightarrow$ baa, baa] \}
$S_{1}=\operatorname{Goto}\left(S_{0}\right.$, SheepNoise $)=$
$\{$ [Goal $\rightarrow$ SheepNoise • , EOF], [SheepNoise $\rightarrow$ SheepNoise - baa, EOF],
[SheepNoise $\rightarrow$ SheepNoise - baa, baa] \}
$S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[S h e e p N o i s e \rightarrow$ baa $\cdot$, EOF $]$,
[SheepNoise $\rightarrow$ baa •, baa] \}
$S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow$ SheepNoise baa • EOF $]$,
[SheepNoise $\rightarrow$ SheepNoise baa •, baa]\}

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ | SheepNoise |
| :--- | :--- | :--- | :--- |
| 1 | SheepNoise | $\rightarrow$ | SheepNoise baa |
| 2 |  | baa |  |

$S_{0}:\{[G o a l \rightarrow$ •SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF], [SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ •SheepNoise baa, baa], [SheepNoise $\rightarrow$ • baa, baa] \}
$S_{1}=\operatorname{Goto}\left(S_{0}\right.$, SheepNoise $)=$
$\{[$ Goal $\rightarrow$ SheepNoise • , EOF], [SheepNoise $\rightarrow$ SheepNoise baa, EOF], [SheepNoise $\rightarrow$ SheepNoise
$S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow \underline{\text { baa } \cdot \text { EOF }], ~}$ [SheepNoise $\rightarrow$ baa • , baa] \} so, ACTION[S $S_{1}$,baa $]$ is "shift $S_{3} "$ (case 1)
$S_{3}=\operatorname{Goto}\left(S_{1}, \underline{b a a}\right)=\{[$ SheepNoise $\rightarrow$ SheepNoise baa •, EOF],
[SheepNoise $\rightarrow$ SheepNoise baa • , baa] \}

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| SheepNoise baa |  |  |
| 2 |  | I baa |

$S_{0}:\{[G o a l \rightarrow$ •SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF],
[SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ •SheepNoise baa, baa], [SheepNoise $\rightarrow$ • baa, baa] \}
$S_{1}=$ Goto( $S_{0}$, SheepNoise $)=$
[ [Goal $\rightarrow$ SheepNoise • EOF], [SheepNoise $\rightarrow$ SheepNoise - baa, EOF],
[SheepNoise $\rightarrow$ SheepNoise - baa, baa]\}
so, $\operatorname{ACTION}\left[S_{1}, \mathrm{EOF}\right]$
$S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow \underline{\text { baa } \cdot, ~ E O F}]$, is "accept" (case 2) [SheepNoise $\rightarrow$ baa •, baa] \}
$S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow$ SheepNoise baa • EOF $]$,
[SheepNoise $\rightarrow$ SheepNoise baa •, baa]\}

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| 2 |  | SheepNoise baa |
| 2 |  | baa |

$S_{0}:\{[$ Goal $\rightarrow$ • SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF],
[SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa],
[SheepNoise $\rightarrow$ • baa, baa] \}
$S_{1}=\operatorname{Goto}\left(S_{0}\right.$, SheepNoise $)=$
$\{$ [Goal $\rightarrow$ SheepNoise • EOF], [SheepNoise $\rightarrow$ SheepNoise - baa, EOF],

[SheepNoise $\rightarrow$ baa • , baa] \}
$S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow$ SheepNois "reduce 2" (case 3)
[SheepNoise $\rightarrow$ SheepNoise baa •, baa] \}

## Example from SheepNoise

| 0 | Goal | $\rightarrow$ |
| :--- | :--- | :--- |
| SheepNoise |  |  |
| 1 | SheepNoise | $\rightarrow$ |
| 2 | SheepNoise baa |  |
| 2 | baa |  |

$S_{0}:\{[G o a l \rightarrow$ •SheepNoise, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, EOF], [SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ • SheepNoise baa, baa], [SheepNoise $\rightarrow$ • baa, baa] \}

```
\(S_{1}=\) Goto( \(S_{n}\). SheedNoise) \(=\)
ACTION \(S_{3}\), EOF] is EOF], [SheepNoise \(\rightarrow\) SheepNoise - baa, EOF],
"reduce 1" (case 3) Noise • baa, baa] \}
\(S_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[\) SheepNoise \(\rightarrow\) baa • EOF],
    [SheepNoise \(\rightarrow\) baa •, baa] \}
\(S_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[\) SheepNoise \(\rightarrow\) SheepNoise baa • EOF \(]\),
    [SheepNoise \(\rightarrow\) SheepNoise baa •, baa]\}
\(\mathrm{ACTION}\left[\mathrm{S}_{3}\right.\),baa] is
```


## Example from SheepNoise

| Goal | $\rightarrow$ SheepNoise |
| :--- | :--- |
| SheepNoise | $\rightarrow$ SheepNoise baa |
|  | 1 |
|  | baa |

The GOTO Table records Goto transitions on NTs
$s_{0}:\{[G o a l \rightarrow \cdot$ SheepNoise, EOF], [SheepNoise $\rightarrow$ •SheepNoise baa, EOF],
[SheepNoise $\rightarrow$ • baa, EOF], [SheepNoise $\rightarrow$ •SheepNoise baa, baa],
[SheepNoise $\rightarrow$ • baa, baa] \}
$s_{1}=$ Goto $\left(S_{0}\right.$, SheepNoise $)=\sim$ Puts $s_{1}$ in GOTO [ $s_{0}$, SheepNoise]
$\{[G o a l \rightarrow$ SheepNoise •, EOF], [SheepNoise $\rightarrow$ SheepNoise - baa, EOF],
[SheepNoise $\rightarrow$ SheepNoise - baa, baa] \}
$s_{2}=\operatorname{Goto}\left(S_{0}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow \underline{\text { baa }} \cdot$, EOF],
Based on T, not NT and written into the ACTION table
$s_{3}=\operatorname{Goto}\left(S_{1}, \underline{\text { baa }}\right)=\{[$ SheepNoise $\rightarrow$ SheepNoise baa $\cdot$, EOF $]$,
[SheepNoise $\rightarrow$ SheepNoise baa •, baa]\}
Only 1 transition in the entire GOTO table
Remember, we recorded these so we don't need to recompute them.

## ACTION \& GOTO Tables

| 0 | Goal |
| :--- | :--- |
| 1 | SheepNoise |
| 2 | SheepNoise |
|  | $\rightarrow$ SheepNoise baa |
|  | $\mid$ baa |

Here are the tables for the augmented left-recursive SheepNoise grammar

The tables

| ACTION TABLE |  |  |
| :---: | :---: | :---: |
| State | EOF | baa |
| 0 | - | shift 2 |
| 1 | accept | shift 3 |
| 2 | reduce 2 | reduce 2 |
| 3 | reduce 1 | reduce 1 |


| GOTO TABLE |  |
| :---: | :---: |
| State | SheepNoise |
| 0 | 1 |
| 1 | 0 |
| 2 | 0 |
| 3 | 0 |

## What can go wrong?

What if set $s$ contains $[A \rightarrow \beta \cdot \underline{a} \gamma, \underline{b}]$ and $[B \rightarrow \beta \cdot, \underline{a}]$ ?

- First item generates "shift", second generates "reduce"
- Both define ACTION[s,a] - cannot do both actions
- This is a fundamental ambiguity, called a shift/reduce error
- Modify the grammar to eliminate it
(if-then-else)
- Shifting will often resolve it correctly

What if set $s$ contains $\left[A \rightarrow \gamma^{\bullet}, \underline{a}\right]$ and $\left[B \rightarrow \gamma^{\bullet}, \underline{a}\right]$ ?

- Each generates "reduce", but with a different production
- Both define ACTION[s, $\underline{]}$ ] - cannot do both reductions
- This is a fundamental ambiguity, called a reduce/reduce conflict
- Modify the grammar to eliminate it

In either case, the grammar is not $L R(1)$

## LR(k) versus LL(k)

Finding Reductions
$L R(k) \Rightarrow$ Each reduction in the parse is detectable with
$\rightarrow$ the complete left context,
$\rightarrow$ the reducible phrase, itself, and
$\rightarrow$ the $k$ terminal symbols to its right longer lookaheads
$L L(k) \Rightarrow$ Parser must select the reduction based on
$\rightarrow$ The complete left context
$\rightarrow$ The next $k$ terminals
Thus, LR(k) examines more context

## Non-LL Grammars

$$
\begin{array}{llll}
0 & B \rightarrow & R \\
1 & & \mid & (B) \\
2 & R \rightarrow E=E \\
3 & E \rightarrow & \underline{a} \\
4 & & \underline{\mathrm{~b}} \\
5 & & (E+E) \\
\hline
\end{array}
$$

Example from D.E Knuth, "Top-Down Syntactic Analysis," Acta Informatica, 1:2 (1971), pages 79-110


Example from Lewis, Rosenkrantz, \& Stearns book, "Compiler Design Theory," (1976), Figure 13.1

This grammar is actually $\operatorname{LR}(0)$

## Summary

|  | Advantages | Disadvantages |
| :---: | :--- | :--- |
| Top-down <br> Recursive <br> descent, <br> LL(1) | Good locality <br> Simplicity <br> Good error detection | Hand-coded |
|  | High maintenance |  |
| LR(1) | Fast associativity <br> Deterministic langs. <br> Automatable <br> Left associativity | Large working sets <br> Poor error messages <br> Large table sizes |
|  |  |  |

## Exercise

Consider the following grammar:

| Start | $\rightarrow$ |
| :--- | :--- |
| $S$ | $\rightarrow$ |
| $A$ | $A$ a |
| $A$ | $B C$ |
| $B$ | $\rightarrow$ |
| $C$ | $\rightarrow$ |
| $C$ |  |

a. Construct the canonical collection of sets of $\operatorname{LR}(1)$ items for this grammar.
b. Derive the Action and Goto tables.
c. Is the grammar $\operatorname{LR}(1)$ ?

Parse the string bcfa and the string bca




