# Models of Computation 

Written Exam on June 8, 2011

(First part: Exercises 1 and 2, 90 minutes
Second part: Exercises 3 and 4, 90 minutes)
(Previous TSD students: Exercises 1, 2 and 3, 135 minutes)

## Exercise 1 (8)

Extend IMP with a restricted version of pointers as follows:
(i) $\sigma: \Sigma=L o c \rightarrow(N+L o c \times L o c)$, namely a location can contain either an integer or a pair of (pointers
to) locations;
(ii) $a::=(x, y)|a::=f s t(a)| a::=\operatorname{snd}(a)$, namely an arithmetic expression can be a pair of locations or can return the content of the first (second) location of a pair;
(iii) the denotational semantics of arithmetic expressions is modified as follows:
$\mathcal{A}: \operatorname{Aexp} \rightarrow \Sigma \rightarrow(N+$ Loc $\times$ Loc $)$;
$\mathcal{A} \llbracket n \rrbracket \sigma=n, \mathcal{A} \llbracket(x, y) \rrbracket \sigma=(x, y), \mathcal{A} \llbracket x \rrbracket \sigma=\sigma(x)$,
$\mathcal{A} \llbracket a_{0}+a_{1} \rrbracket \sigma=\mathbf{c a s e}\left(\mathcal{A} \llbracket a_{0} \rrbracket \sigma, \mathcal{A} \llbracket a_{1} \rrbracket \sigma\right):\left(n_{0}, n_{1}\right) \rightarrow n_{0}+n_{1}$, otherwise $\rightarrow 0$ and similarly for $\times$, etc.,
$\mathcal{A} \llbracket f s t(a) \rrbracket \sigma=$ case $\mathcal{A} \llbracket a \rrbracket \sigma: n \rightarrow 0,(x, y) \rightarrow \sigma(x)$,
$\mathcal{A} \llbracket \operatorname{snd}(a) \rrbracket \sigma=\mathbf{c a s e} \mathcal{A} \llbracket a \rrbracket \sigma: n \rightarrow 0,(x, y) \rightarrow \sigma(y)$,
$\mathcal{B} \llbracket a_{0} \neq a_{1} \rrbracket \sigma=\mathbf{c a s e}\left(\mathcal{A} \llbracket a_{0} \rrbracket \sigma, \mathcal{A} \llbracket a_{1} \rrbracket \sigma\right):\left(n_{0}, n_{1}\right) \rightarrow n_{0} \neq n_{1}$, otherwise $\rightarrow$ true and similarly for $\leq$, etc.
Define the operational semantics of the new/modified constructs and evaluate the command:
$x:=(y, x) ; y:=(x, x)$; while $x \neq 0$ do $x:=f s t(x)$ according to operational semantics. Finally, prove the equivalence between operational and denotational semantics.

## Exercise 2 (7)

A preorder is a pair $(\mathcal{S}, \sqsubseteq)$, where $\sqsubseteq$ is a relation on set $\mathcal{S}$ with the properties of reflexivity and transitivity (not necessarily antisymmetry). Let $S_{1} \equiv S_{2}$ iff $S_{1} \sqsubseteq S_{2}$ e $S_{2} \sqsubseteq S_{1}$ and prove that $\equiv$ is an equivalence relation.

Preorders on the same $\mathcal{S}$ are themselves ordered by inclusion, namely: $(\mathcal{S}, \sqsubseteq) \subseteq\left(\mathcal{S}, \sqsubseteq^{\prime}\right)$ if $\sqsubseteq \subseteq \sqsubseteq^{\prime}$. Prove that preorders ordered by inclusion form a complete partial ordering with bottom. Given two preorders, their lub (least upper bound) and their glb (greatest lower bound) are always defined? How?

## Exercise 3 (7)

Let us consider CCS with prefix, sum, nil, parallel composition and the additional operations 」 and \|. The axiomatization of this calculus consists of the following axioms:

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\begin{aligned}
& \left.\left.E_{1} \mid E_{2}=E_{1}\right\rfloor E_{2}+E_{2}\right\rfloor E_{1}+E_{1} \| E_{2} \quad E_{1}\left|E_{2}=E_{2}\right| E_{1} \quad\left(E_{1} \mid E_{2}\right)\left|E_{3}=E_{1}\right|\left(E_{2} \mid E_{3}\right) \\
& \left.\mu \cdot E_{1}\right\rfloor E_{2}=\mu \cdot\left(E_{1} \mid E_{2}\right) \quad \lambda \cdot E_{1}\left\|\bar{\lambda} \cdot E_{2}=\tau\left(E_{1} \mid E_{2}\right) \quad \mu_{1} \cdot E_{1}\right\| \mu_{2} \cdot E_{2}=\text { nil } \text { if } \mu_{1} \neq \overline{\mu_{2}} \\
& \left.\left.\left.\left(E_{1}+E_{2}\right)\right\rfloor E=E_{1}\right\rfloor E+E_{2}\right\rfloor E \quad\left(E_{1}+E_{1}^{\prime}\right)\left\|\left(E_{2}+E_{2}^{\prime}\right)=E_{1}\right\| E_{2}+E_{1}\left\|E_{2}^{\prime}+E_{1}^{\prime}\right\| E_{2}+E_{1}^{\prime} \| E_{2}^{\prime} \\
& \text { nil }\rfloor E=\text { nil\|E E E\|nil nil nil } \\
& E+\text { nil }=E \quad E_{1}+E_{2}=E_{2}+E_{1} \quad\left(E_{1}+E_{2}\right)+E_{3}=E_{1}+\left(E_{2}+E_{3}\right) \quad E+E=E .
\end{aligned}
$$

(i) Prove using the axioms that $a . b . n i l|c . n i l+c . a . b . n i l=a . b . n i l| c . n i l$, where $a, b$ and $c$ are all different;
(ii) define inference rules also for the new operators 」 and \|;
(iii) prove using the rules just defined that the axioms $\left.\left.E_{1} \mid E_{2}=E_{1}\right\rfloor E_{2}+E_{2}\right\rfloor E_{1}+E_{1} \| E_{2}$ and $\left.\left(E_{1}+E_{2}\right)\right\rfloor E=$ $\left.\left.E_{1}\right\rfloor E+E_{2}\right\rfloor E$ do bisimulate. Namely, given generic transitions of $E_{1}, E_{2}$ and $E$ (in the second case), every transition of the left hand side of the axiom can be matched by a transition of the right hand side (and viceversa) with the same action and with continuations which can be proved equivalent using (all) the axioms.

## Exercise 4(8)

A water pump can be described by the following control model.


Round boxes describe the states of the pump (working or not working) and of the control ( $q_{0}$ or $q_{1}$ ). Arcs out of the round boxes represent the possible control actions. While unlabeled, they can be assumed as labelled by the action in the square box they end up in. For instance, the pump can be made working Fast, or Slow, or it can be turned Off. Out of the square boxes there are probability distributions: e.g. if the pump works fast it is more likely to break down. Number pairs in the square boxes represent (repair) cost and gain (amount of water pumped) respectively, in each condition. Notice that, in the presence of a failure, there are two possibilities: either try to repair the pump while keeping it operative, or turn it off. In the former case, the cost of the repair is smaller (10 instead of 20 ), but so it is the likelihood that the repair is effective ( $80 \%$ instead of $90 \%$ ).
(i) Define a Markov Decision Process, MDP (also reactive probabilistic labeled transition system in the terminology used in the course) corresponding to the given control model.
A strategy is an assignment of a unique control action to every round box. Given any strategy, the MDP is straightforwardly transformed in a DTMC with costs and gains associated to every state. For instance, if a strategy assigns the action Slow to the state (working, $q_{0}$ ), the corresponding state of the DTMC has a transition with probability $1 \%$ to the state (not working, $q_{0}$ ) and a probability of $99 \%$ of remaining in the same state.
(ii) Define the DTMC corresponding to the strategy which assigns Slow to the state (working, $q_{0}$ ), Off to (not working, $q_{0}$ ) and Repair to the remaining state. Compute the stationary probabilities (ergodic?) and the average global cost and gain.
(iii) Do the same assigning the action Fast to the state (working, $q_{0}$ ) and Repair to the state (not working, $q_{0}$ ).
(iv) Discuss which is the best strategy.

