

Models of Computation

Written Exam on February 1, 2012

(MOD students: Exercises 1-5, 180 minutes)

Previous TSD students: Exercises 1-3, 120 minutes)

Exercise 1 (7)

Extend IMP with the construct **either** c_0 **or** c_1 having the following operational semantics:

$$\frac{\langle c_0, \sigma \rangle \rightarrow \sigma'}{\langle \mathbf{either} \ c_0 \ \mathbf{or} \ c_1, \sigma \rangle \rightarrow \sigma'} \quad \frac{\langle c_1, \sigma \rangle \rightarrow \sigma'}{\langle \mathbf{either} \ c_0 \ \mathbf{or} \ c_1, \sigma \rangle \rightarrow \sigma'}$$

Consider then the command:

$$w_n = \mathbf{while} \ x \neq n \ \mathbf{do} \ \mathbf{either} \ x := 2 \times x; \ y := y \times y \ \mathbf{or} \ x := 2 \times x + 1; \ y := k \times y \times y.$$

Proof that for every $\sigma, \sigma' \in \Sigma$ with $\langle w_n, \sigma \rangle \rightarrow \sigma'$

$$\text{if } \sigma(y) = k^{\sigma(x)} \quad \text{then } \sigma' = \sigma[n/x, k^n/y].$$

Exercise 2 (6)

Prove that the relation $R_S = (\mathcal{P}(\omega) \setminus S, \subseteq)$ is a partial ordering for every class S of sets of natural numbers. Then exhibit a class \bar{S} such that $R_{\bar{S}}$ is not complete and has no minimum. Finally, prove that R_S is complete if S contains only finite sets.

Exercise 3 (7)

Modify HOFL, assigning the following semantics to the conditional construct:

$$\frac{t_0 \rightarrow 0 \quad t_1 \rightarrow c_1 \quad t_2 \rightarrow c_2}{\mathbf{if} \ t_0 \ \mathbf{then} \ t_1 \ \mathbf{else} \ t_2 \rightarrow c_1} \quad \frac{t_0 \rightarrow n \quad n \neq 0 \quad t_1 \rightarrow c_1 \quad t_2 \rightarrow c_2}{\mathbf{if} \ t_0 \ \mathbf{then} \ t_1 \ \mathbf{else} \ t_2 \rightarrow c_2}$$

Define the corresponding denotational semantics and proof that also for the modified semantics $t \rightarrow c$ implies $\llbracket t \rrbracket = \llbracket c \rrbracket$. Finally, derive both the operational and the denotational semantics of $(\mathit{fact} \ 0)$, with $\mathit{fact} = \mathit{rec} \ f.\lambda x. \mathbf{if} \ x \ \mathbf{then} \ 1 \ \mathbf{else} \ x \times (f \ x - 1)$, checking if they coincide or not.

Exercise 4 (5)

Define by structural induction the free names $fn(p)$ of a CCS agent p . Prove by rule induction on the operational semantics that $p \xrightarrow{\mu} q$ implies $fn(q) \subseteq fn(p)$. Show an example where $fn(q) \subset fn(p)$. Now consider the π -calculus, and show an example of $p \xrightarrow{\alpha} q$ where $fn(p) \subset fn(q)$.

Exercise 5 (5)

A reactive, probabilistic labelled transition system representing the options of a taxi driver has states s_1 (parking), s_2 (moving slowly looking for costumers) and s_3 (busy with clients); actions p (stay in the parking) and m (move); and transition function α with $\alpha_{s_1 p s_3} = 0.2$, $\alpha_{s_1 p s_1} = 0.8$, $\alpha_{s_1 m s_2} = 1$, $\alpha_{s_2 x s_2} = 0.5$, $\alpha_{s_2 x s_3} = 0.5$, $\alpha_{s_3 x s_1} = 0.6$, and $\alpha_{s_3 x s_3} = 0.4$, where x is any action p or m . Consider the two Markov chains obtained by letting the taxi driver choose always p or always m (in the former case disregard state s_2). Are they ergodic? In both cases compute the stationary probability distributions and the average costs and gains, knowing that the costs of states s_1 , s_2 and s_3 are 0, 2 and 5, while the gains are 0, 0 and 10 respectively. What is the most convenient choice?

Correzione Prova Scritta del 01/02/2012

Esercizio 1

Dimostrazione per induzione sulle prove

$$P(\langle w_n, \sigma \rangle \rightarrow \sigma') \stackrel{\text{def}}{=} \sigma(x) = K^{\sigma(x)} \Rightarrow \sigma' = \sigma \left[\frac{n}{x}, K^{\frac{w}{y}} \right]$$

$$\frac{\sigma(x) = w}{\langle w_n, \sigma \rangle \rightarrow \sigma} \quad P(\langle w_n, \sigma \rangle \rightarrow \sigma) \stackrel{\text{def}}{=} \sigma(y) = K^{\sigma(x)} \Rightarrow \sigma = \sigma \left[\frac{n}{x}, K^{\frac{w}{y}} \right] \text{ ovvio da } \sigma(x) = w \text{ CVD.}$$

• Prima regola di eiter-or

$$\langle \text{eiter}(x := 2 \times x; y := y \times y) \text{ or } (x := 2x + 1; y := K^x y \times y), \sigma \rangle \rightarrow \sigma'' \leftarrow$$

$$\langle x := 2 \times x; y := y \times y, \sigma \rangle \rightarrow \sigma'' \quad \sigma'' = \sigma \left[\frac{2\sigma(x)}{x}, \frac{\sigma(y)^2}{y} \right]$$

$$\frac{\sigma(x) \neq w \quad \sigma'' = \sigma \left[\frac{2\sigma(x)}{x}, \frac{\sigma(y)^2}{y} \right] \langle w_n, \sigma'' \rangle \rightarrow \sigma'}{\langle w_n, \sigma \rangle \rightarrow \sigma'}$$

Assumiamo: $\sigma(x) \neq w$ (che però non servirà)

$$\sigma''(y) = K^{\sigma''(x)} \Rightarrow \sigma' = \sigma'' \left[\frac{n}{x}, K^{\frac{w}{y}} \right] \text{ ipotesi induttiva}$$

Dobbiamo dimostrare

$$\sigma(y) = K^{\sigma(x)} \stackrel{?}{\Rightarrow} \sigma' = \sigma \left[\frac{n}{x}, K^{\frac{w}{y}} \right]$$

Assumiamo la premessa: $\sigma(y) = K^{\sigma(x)}$

Resta da dimostrare $\sigma' \stackrel{?}{=} \sigma \left[\frac{n}{x}, K^{\frac{w}{y}} \right]$

$$\sigma''(y) = \sigma(y)^2 \quad \sigma''(x) = 2\sigma(x)$$

$$\sigma(y)^2 = \left(K^{\sigma(x)} \right)^2 \text{ ancora la premessa}$$

$$\sigma''(y) = K^{2\sigma(x)} = \sigma''(x) \text{ quindi } \sigma' = \sigma'' \left[\frac{n}{x}, K^{\frac{w}{y}} \right] \text{ dalla ipotesi ind. CVD.}$$

(2)

• Seconda regola di Eiter-or-

$$\sigma'' = \sigma \left[\frac{2\sigma(x)+1}{x}, \frac{K \sigma(y)^2}{y} \right]$$

$$\sigma(x) \neq u \quad \sigma'' = \sigma \left[\frac{2\sigma(x)+1}{x}, \frac{K \cdot \sigma(y)^2}{y} \right] \langle u, \sigma'' \rangle \rightarrow \sigma'$$

$$\langle u, \sigma \rangle \rightarrow \sigma'$$

Cambia sob:

$$\sigma''(y) = K \sigma(y)^2$$

$$\sigma''(x) = 2\sigma(x)+1$$

$$\sigma(y)^2 = \left(x^{\sigma(x)} \right)^2$$

$$K \sigma(y)^2 = K 2\sigma(x)+1$$

$$\sigma''(y) = K \sigma''(x)$$

quindi $\sigma' = \sigma'' \left[\frac{u}{x}, \frac{u}{y} \right]$
dall'ipotesi induttiva

CVD

Esercizio 2

Le proprietà:

Reflessiva $\forall I, I \subseteq I$

Antisimmetrica $\forall I, J, I \subseteq J, J \subseteq I \Rightarrow I = J$

Transitiva $\forall I, J, K, I \subseteq J, J \subseteq K \Rightarrow I \subseteq K$

che valgono per $I, J, K \in P(\omega)$, valgono anche per $I, J, K \in P(\omega) \setminus S$, essendo I, J, K qualificati universalmente.

Poniamo $\bar{S} = \{I, \omega\}$. Allora $P(\omega) \setminus S$ non ha minimo, essendo tutti i singleton $\{0\}, \{1\}, \{2\}, \dots$ minimali ma non minimi.

Inoltre la catena

$$\{0\} \subseteq \{0, 1\} \subseteq \{0, 1, 2\} \subseteq \dots$$

non ha nessun maggiorante e quindi non ha limite.

Dimostrare che \bar{S} contiene lo insieme finito allora $(P(\omega) \setminus S, \subseteq)$ è completo.

Sia $I_0 \subseteq I_1 \subseteq I_2 \subseteq \dots$ una catena. Se $\cup I_i$ in $P(\omega)$ è un insieme finito, allora $\{I_i\}$ è una catena finita, e quindi ha limite anche in $P(\omega) \setminus S$. Invece se $\{I_i\}$ è una catena infinita, allora $\cup I_i$ è un insieme infinito, e quindi esiste in $P(\omega) \setminus S$ per costruzione.

Esercizio 3

Semantica denotazionale modificata

$$\llbracket \text{if } t_0 \text{ then } t_1 \text{ else } t_2 \rrbracket \rho = \text{Cond}(\llbracket t_0 \rrbracket \rho, \llbracket t_1 \rrbracket \rho, \llbracket t_2 \rrbracket \rho)$$

$$\text{Cond} : D_{\perp} \times D_{\perp} \times D_{\perp} \rightarrow D_{\perp}$$

$$\text{Cond}(z_0, z_1, z_2) = \perp_{D_{\perp}} \text{ se } z_0 = \perp_{D_{\perp}} \vee z_1 = \perp_{D_{\perp}} \vee z_2 = \perp_{D_{\perp}}$$

besta da un elemento z_1 se $z_0 = \llbracket 0 \rrbracket$ e $z_2 \neq \perp_{D_{\perp}}$
+ a \perp , e vale \perp z_2 se $z_0 = \llbracket n \rrbracket, n \neq 0$, e $z_1 \neq \perp_{D_{\perp}}$

Cond è continuo essendo continuo su ogni argomento:

$$\text{Cond}(\perp_{D_{\perp}}, z_1, z_2) = \perp_{D_{\perp}}$$

$$\text{Cond}(\llbracket 0 \rrbracket, z_1, \perp_{D_{\perp}}) = \perp_{D_{\perp}}$$

$$\text{Cond}(\llbracket 0 \rrbracket, z_1, \llbracket y_2 \rrbracket) = z_1$$

$$\text{Cond}(\llbracket n \rrbracket, \perp_{D_{\perp}}, z_2) = \perp_{D_{\perp}}$$

$$\text{Cond}(\llbracket n \rrbracket, \llbracket y_1 \rrbracket, z_2) = z_2$$

qui funzione è una costante oppure l'identità

$z_1 \backslash z_2$	$\perp_{D_{\perp}}$	$\llbracket y_2 \rrbracket$	$z_1 \backslash z_2$	$\perp_{D_{\perp}}$	$\llbracket y_2 \rrbracket$	$z_1 \backslash z_2$	$\perp_{D_{\perp}}$	$\llbracket y_2 \rrbracket$
$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$
$\llbracket 0 \rrbracket$	$\perp_{D_{\perp}}$	$\perp_{D_{\perp}}$	$\llbracket 0 \rrbracket$	$\perp_{D_{\perp}}$	$\llbracket y_1 \rrbracket$	$\llbracket 0 \rrbracket$	$\perp_{D_{\perp}}$	$\llbracket y_2 \rrbracket$

$$z_0 = \perp_{D_{\perp}}$$

$$z_1 = \llbracket 0 \rrbracket$$

$$z_1 = \llbracket 1 \rrbracket$$

$$P(t \rightarrow c) \stackrel{\text{def}}{=} \llbracket t \rrbracket \rho = \llbracket c \rrbracket \rho \quad t: \bar{v}$$

$$\frac{t_0 \rightarrow 0 \quad t_1 \rightarrow c_1 \quad t_2 \rightarrow c_2}{\text{if } t_0 \text{ then } t_1 \text{ else } t_2 \rightarrow c_1}$$

$$P(t_0 \rightarrow 0) \stackrel{\text{def}}{=} \llbracket t_0 \rrbracket \rho = \llbracket 0 \rrbracket \rho$$

$$P(t_2 \rightarrow c_2) \stackrel{\text{def}}{=} \llbracket t_2 \rrbracket \rho = \llbracket c_2 \rrbracket \rho$$

$$P(t_1 \rightarrow c_1) \stackrel{\text{def}}{=} \llbracket t_1 \rrbracket \rho = \llbracket c_1 \rrbracket \rho$$

$$P(\text{if } t_0 \text{ then } t_1 \text{ else } t_2 \rightarrow c_1) = \llbracket \text{if } t_0 \text{ then } t_1 \text{ else } t_2 \rrbracket \rho = \llbracket c_1 \rrbracket \rho \quad ?$$

$$\llbracket \text{if } t_0 \text{ then } t_1 \text{ else } t_2 \rrbracket \rho = \text{cond}(\llbracket t_0 \rrbracket \rho, \llbracket t_1 \rrbracket \rho, \llbracket t_2 \rrbracket \rho)$$

Essendo $\llbracket t_0 \rrbracket \rho = \llbracket 0 \rrbracket \rho$ e $\llbracket c_2 \rrbracket \rho = \perp(\bar{v}_2)$ abbiamo

$$\text{cond}(\llbracket 0 \rrbracket \rho, \llbracket t_1 \rrbracket \rho, \llbracket \bar{v}_2 \rrbracket \rho) = \llbracket t_1 \rrbracket \rho = \llbracket c_1 \rrbracket \rho$$

Stessa prova per la 2^a regola

C.V.D.

$$(\text{fact } 0) \rightarrow c \leftarrow \text{fact} \rightarrow dx.t \quad t[0/x] \rightarrow c \leftarrow$$

$$(\text{if } x \text{ then } t \text{ else } x \times (\text{fact } x - 1)) [0/x] \rightarrow c \leftarrow$$

$$0 \rightarrow 0 \quad 1 \rightarrow c \quad 0 \times (\text{fact } -1) \rightarrow c' \xleftarrow{c=1} 0 \times (\text{fact } -1) \rightarrow c'$$

$$\xleftarrow{c=c_1 \times c_2} 0 \rightarrow c_1 \quad (\text{fact } -1) \rightarrow c_2 \xleftarrow{c_1=0} (\text{fact } -1) \rightarrow c_2 \leftarrow \dots$$

non c'è prova: (fact 0) usa la formula canonica

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$$\llbracket \text{fact } 0 \rrbracket \rho = \text{let } \psi \leftarrow \llbracket \text{fact} \rrbracket \rho . \psi \llbracket 0 \rrbracket$$

$$\llbracket \text{fact} \rrbracket = \text{fix } \lambda d . \llbracket \lambda d' . \text{Coud}d(d', \llbracket 1 \rrbracket), d' \leq \perp \text{ let } \psi \leftarrow d . \psi (d' = \llbracket 1 \rrbracket) \rrbracket$$

$$d_0 = \perp \llbracket N_{\perp} \rightarrow N_{\perp} \rrbracket_{\perp}$$

beste de un
approuvé
sur \perp

$$d_1 = \llbracket \lambda d' . \text{Coud}d(d', \llbracket 1 \rrbracket), \perp_{N_{\perp}} \rrbracket = \llbracket \perp \llbracket N_{\perp} \rightarrow N_{\perp} \rrbracket \rrbracket$$

$$d_2 = \llbracket \lambda d' . \text{Coud}d(d', \llbracket 1 \rrbracket), d' \leq \perp \text{ let } \psi \leftarrow \llbracket \perp \rrbracket . \psi (d' = \llbracket 1 \rrbracket) \rrbracket \\ = \llbracket \lambda d' . \text{Coud}d(d', \llbracket 1 \rrbracket), \perp_{N_{\perp}} \rrbracket = \llbracket \perp \llbracket N_{\perp} \rightarrow N_{\perp} \rrbracket \rrbracket$$

$$\llbracket \text{fact } 0 \rrbracket \rho = \left(\lambda d' . \perp \llbracket N_{\perp} \rightarrow N_{\perp} \rrbracket \right) \rho = \perp_{N_{\perp}} \quad \text{CRD.}$$

Exercise 4

$$f_w(x) = f_w(\ulcorner x \urcorner) = \emptyset$$

$$f_w(\text{rec } x, P) = f_w(\tau, P) = f_w(P)$$

$$f_w(P+Q) = f_w(P|Q) \\ \equiv f_w(P) \cup f_w(Q)$$

$$f_w(\ulcorner x \urcorner, P) = f_w(\bar{\ulcorner x \urcorner}, P) = \{x\} \cup f_w(P)$$

$$f_w(P|x) = f_w(P) - \{x\}$$

$$f_w(P[\Phi]) = \phi(f_w(P)) = \{ \phi(x) \mid x \in f_w(P) \}$$

$$P(P \xrightarrow{u} Q) \stackrel{\text{def}}{=} f_w(P) \supseteq f_w(Q)$$

• $\mu.P \xrightarrow{u} P$ obvious, $f_w(\mu.P) = f_w(P) \cup \dots$

• $\frac{P \xrightarrow{u} Q}{P|x \xrightarrow{u} Q|x}$ obvious, $f_w(P) \supseteq f_w(Q)$ implies $f_w(P) - x \supseteq f_w(Q) - x$

• $\frac{P \xrightarrow{u} Q}{P[\Phi] \xrightarrow{\phi(u)} Q[\Phi]}$ obvious $f_w(P) \supseteq f_w(Q)$ implies $\phi(f_w(P)) \supseteq \phi(f_w(Q))$, ϕ injective

• $\frac{P \xrightarrow{u} Q}{P+r \xrightarrow{u} Q}$ obvious $f_w(P) \supseteq f_w(Q)$ implies $f_w(P) \cup \dots \supseteq f_w(Q)$ and symmetric

• $\frac{P \xrightarrow{u} Q}{P|r \xrightarrow{u} Q|r}$ obvious $f_w(P) \supseteq f_w(Q)$ implies $f_w(P) \cup f_w(r) \supseteq f_w(Q) \cup f_w(r)$ and symmetric

• $\frac{P_1 \xrightarrow{u} Q_1 \quad P_2 \xrightarrow{u} Q_2}{P_1|P_2 \xrightarrow{u} Q_1|Q_2}$ $f_w(P_1) \supseteq f_w(Q_1)$ implies $f_w(P_1) \cup f_w(P_2) \supseteq f_w(Q_1) \cup f_w(Q_2)$
 $f_w(P_2) \supseteq f_w(Q_2)$

• $\frac{P[\text{rec } x, P/x] \xrightarrow{u} Q}{\text{rec } x, P \xrightarrow{u} Q}$ notice that $f_w(P[\text{rec } x, P/x]) = f_w(P) \cup f_w(\text{rec } x, P) = f_w(P)$

Thus $f_w(P[\text{rec } x, P/x]) \supseteq f_w(Q)$ implies $f_w(\text{rec } x, P) = f_w(P) \supseteq f_w(Q)$

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An example: $x, \text{nil} \xrightarrow{\alpha} \text{nil}$

$$f_u(x, \text{nil}) = \{x\} \supset f_u(\text{nil}) = \emptyset$$

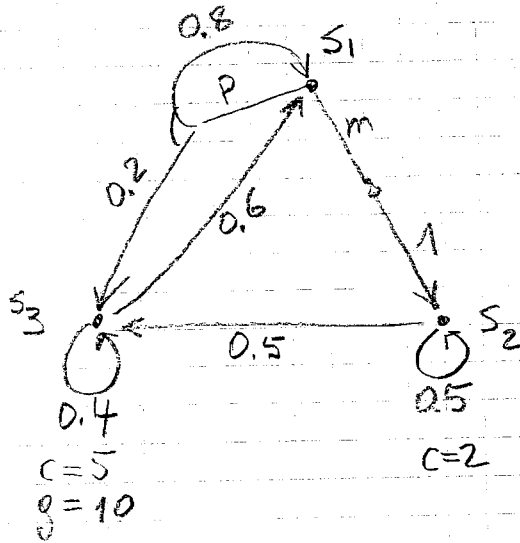
The π -calculus:

$$(x) \bar{y}x, \bar{x}y, \text{nil} \xrightarrow{\bar{y}(z)} \bar{z}y, \text{nil}$$

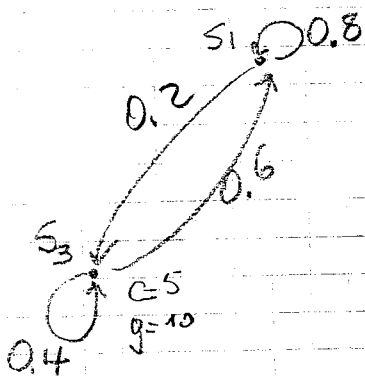
$$f_u((x) \bar{y}x, \bar{x}y, \text{nil}) = \{y\}$$

$$f_u(\bar{z}y, \text{nil}) = \{y, z\}$$

Exercise 5



Case P is chosen:



$$x_1 = 0.8x_1 + 0.6x_3 \quad x_1 + x_3 = 1$$

$$x_3 = 0.2x_1 + 0.4x_3$$

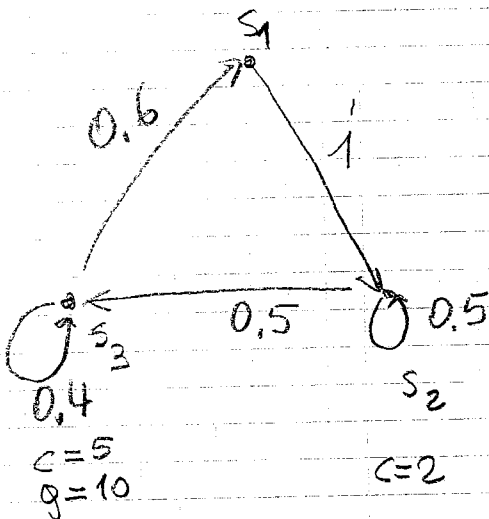
$$0.2x_1 = 0.6x_3 \quad x_1 = 3x_3$$

$$x_1 = 0.75 \quad x_3 = 0.25$$

$$c_3 = 1.25 \quad g_3 = 2.5$$

$$\boxed{diff = 1.25}$$

Case m is chosen



$$x_1 = 0.6x_3$$

$$x_1 + x_2 + x_3 = 1$$

$$x_2 = x_1 + 0.5x_2$$

$$x_3 = 0.5x_2 + 0.4x_3$$

$$0.6x_3 = 0.5x_2 \quad x_2 = 1.2x_3$$

$$0.6x_3 + 1.2x_3 + x_3 = 1 \quad x_3 = 10/28$$

$$x_2 = \frac{12}{28} = \frac{3}{7} \quad x_1 = \frac{0.6}{2.8} = \frac{6}{28}$$

$$c_3 = \frac{50}{28} \quad g_3 = \frac{100}{28}$$

$$c_2 = \frac{24}{28}$$

$$\boxed{diff = \frac{26}{28} = 0.93}$$

Pis better