

# Models of Computation

Written Examination on July 16, 2013

(First part: Exercises 1 and 2, 90 minutes)

Second part: Exercises 3, 4 and 5, 90 minutes)

## Exercise 1 (8)

(Previous TSD students: Exercises 1, 2 and 3, 120 minutes)

Extend *IMP* with a *recursion* command  $c ::= \dots | X | \mathbf{rec} X.c$ , redefining memories as  $\Sigma' = Loc \rightarrow (N \cup (\Sigma \rightarrow \Sigma_{\perp}))$ . The denotational semantics of the new command is defined as follows;

$$\mathcal{C}[\![X]\!] \sigma = (\sigma(X)) \sigma \quad \mathcal{C}[\![\mathbf{rec} X.c]\!] = \mathbf{fix} \lambda \varphi. \lambda \sigma. \mathcal{C}[\![c]\!] \sigma[\varphi/X].$$

(i) Define the inference rule for (closed) commands  $\mathbf{rec} X.c$ . (Hint: analogous to the operational semantics of recursion in HOFL); (ii) state, without proof, the substitution lemma for extended IMP; (iii) prove the completeness of the denotational semantics of the new construct; and (iv) given the **repeat** command with denotational semantics:

$$\mathcal{C}[\![\mathbf{repeat} c \text{ until } b]\!] = \mathbf{fix} \Gamma \quad \Gamma \varphi \sigma = \mathbf{B}[b]^*(\mathbf{C}[c]\sigma) \rightarrow \varphi^*(\mathbf{C}[c]\sigma), \mathbf{C}[c]\sigma$$

define an equivalent command using the **rec** and **if then else** constructs and prove that it has the same denotational semantics.

## Exercise 2 (7)

Consider the inference system  $R$  corresponding to the rules of the grammar (with  $V = \{a, b\}$ ):

$$A ::= aAa|B \quad B ::= bB|b$$

where the well formed formulas are of the form  $\alpha \in A$  (resp.  $\alpha \in B$ ), with the meaning that string  $\alpha$  belongs to the language generated by the nonterminal  $A$  (resp.  $B$ ). Write down explicitly the rules in  $R$ .

Prove by rule induction - in one direction - and by mathematical induction on  $n, m$  - in the other direction - that the strings  $L_A$  generated by  $A$  (resp.  $L_B$  by  $B$ ) are all the strings of the form  $a^n b^m a^n$  (resp  $b^m$ ),  $m, n \in \omega, m \geq 1$ . Finally prove by induction on derivations that the length of the derivation of  $a^n b^m a^n \in A$  is  $n + m + 1$  (resp. the derivation of  $b^m \in B$  is  $m$ ).

## Exercise 3 (5)

Consider the closed HOFL term  $t' = \mathbf{rec} x.t : int$ . Prove that if  $\llbracket \lambda x.t \rrbracket \rho$  is not a constant, then  $\llbracket t' \rrbracket \rho = \perp_{N_{\perp}}$  (Hint:  $\llbracket \lambda x.t \rrbracket$  must be monotone, thus if it not a constant function its value on  $\perp_{N_{\perp}}$  must be  $\perp_{N_{\perp}}$ ). Give examples of  $t$  such that  $\llbracket \lambda x.t \rrbracket \rho$ , with  $x \in fv(t)$ , is a constant.

## Exercise 4 (5)

Prove that in the  $\pi$ -calculus if  $p \xrightarrow{\alpha} q$  then also  $p\rho \xrightarrow{\alpha\rho} q\rho$  for any substitution  $\rho$  on the free names of  $p$  which does not capture the bound names of  $\alpha$ . Also, show that  $p\rho \xrightarrow{\alpha\rho} q\rho$  implies  $p \xrightarrow{\alpha} q$  for any *injective* substitution  $\rho$ , while  $p\rho \xrightarrow{\alpha\rho} q\rho$  does not imply  $p \xrightarrow{\alpha} q$  when  $\rho$  is a noninjective substitution. (Hint: consider the counterexample which proves that ground bisimilarity is not a congruence.)

## Exercise 5 (5)

A probabilistic system has four possible states, *idle*, *working slow*, *working fast* and *failure*. From *idle*, the system can move with probability  $p$  to *working slow* and with probability  $1 - p$  to *working fast*, where  $0 \leq p \leq 1$  is a parameter. From *working fast*, the system returns to *idle* with 80% probability and otherwise moves to *failure*, while from *working slow*, the system returns to *idle* with 95% probability and otherwise moves to *failure*. Finally, from *failure* the system moves with 50% probability to *idle*, or otherwise remains in the same state. Define the DTMC corresponding to the description above, observe that the chain is ergodic, and compute the stationary probabilities in terms of the parameter  $p$ . Finally, assuming that the gain for state *working fast* is 2 and for *working slow* is 1 (0 for the other states), compute the total gain in terms of  $p$  and determine the best value of  $p$ .

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Exercise 1

(i)  $\frac{\langle c[\text{rec } X.c/x], \sigma \rangle \rightarrow \sigma'}{\langle \text{rec } X.c, \sigma \rangle \rightarrow \sigma'}$

$\mathcal{E}[\text{rec } X.c] = \text{fix } \lambda x. \lambda \sigma. \mathcal{E}[c][\sigma][\rho/x]$   
 $\mathcal{E}[X]\sigma = \sigma(X)$

(ii)  $\langle \text{rec } X.c, \sigma \rangle \rightarrow \sigma' \stackrel{?}{=} \mathcal{E}[\text{rec } X.c]\sigma = \sigma'$

$\mathcal{E}[c[\text{rec } X.c/x]]\sigma = \sigma'$  by the premise

$\mathcal{E}[\text{rec } X.c] = \lambda \sigma. \mathcal{E}[c][\sigma][\mathcal{E}[\text{rec } X.c/x]]$  by the substitution lemma  
 $= \lambda \sigma. \mathcal{E}[c[\text{rec } X.c]]$

$\mathcal{E}[\text{rec } X.c]\sigma = \mathcal{E}[c[\text{rec } X.c]]\sigma = \sigma'$  QED

(ii) Substitution Lemma

Instead of  $\llbracket t[t'/x] \rrbracket \rho = \llbracket t \rrbracket \rho[\llbracket t' \rrbracket \rho/x]$

we have  $\mathcal{E}[c[c'/x]]\sigma = \mathcal{E}[c]\sigma[\mathcal{E}[c']\sigma/x]$

(2)

(iv) rec X.c; if b then X else skip = c' X ∈ fn(c)

$$\begin{aligned}
\llbracket c' \rrbracket &= \text{fix } \Gamma' \quad \Gamma' \varphi \sigma = \llbracket c; \text{if } b \text{ then } X \text{ else skip} \rrbracket \sigma \llbracket \varphi/x \rrbracket \\
&= \llbracket \text{if } b \text{ then } X \text{ else skip} \rrbracket^* (\llbracket c \rrbracket \sigma \llbracket \varphi/x \rrbracket) \\
&= (\lambda \sigma. \llbracket b \rrbracket \sigma \rightarrow (\sigma(x)) \sigma, \sigma)^* (\llbracket c \rrbracket \sigma \llbracket \varphi/x \rrbracket) \\
&= \llbracket b \rrbracket^* (\llbracket c \rrbracket \sigma) \rightarrow \llbracket c \rrbracket^* \sigma, \llbracket c \rrbracket \sigma
\end{aligned}$$

Notice that  $\varphi^*(\llbracket c \rrbracket \sigma \llbracket \varphi/x \rrbracket) = \varphi^*(\llbracket c \rrbracket \sigma)$  since  $\varphi: \tilde{x} \rightarrow \tilde{x}^*$

$$\begin{aligned}
\llbracket \text{repeat } c \text{ while } b \rrbracket &= \text{fix } \Gamma \\
\Gamma \varphi \sigma &= \llbracket b \rrbracket^* (\llbracket c \rrbracket \sigma) \rightarrow \varphi^*(\llbracket c \rrbracket \sigma), \llbracket c \rrbracket \sigma
\end{aligned}$$

Since  $\Gamma' = \Gamma$  then  $\text{fix } \Gamma' = \text{fix } \Gamma$  QED.

Exercise 2

$$\frac{x \in A}{axa \in A}$$

$$\frac{x \in B}{x \in A}$$

$$\frac{x \in B}{bx \in B}$$

$$b \in B$$

$$P(x \in A) \stackrel{\text{def}}{=} \exists n, m. x = a^n b^m a^n$$

$$P(x \in B) \stackrel{\text{def}}{=} \exists m. x = b^m$$

$$\frac{x \in A}{axa \in A}$$

$$x = a^n b^m a^n$$

$$axa = a^{n+1} b^m a^{n+1}$$

QED.

$$\frac{x \in B}{x \in A}$$

$$x = b^m$$

$$x = a^0 b^m a^0$$

QED.

$$\frac{x \in B}{bx \in B}$$

$$x = b^m$$

$$bx = b^{m+1}$$

$$b \in B$$

$$b = b^1$$

QED

$$L_A = \{a^n b^m a^n \mid n \geq 0, m \geq 1\} \quad L_B = \{b^m \mid m \geq 1\}$$

•  $b^1 \in B$  is a theorem?  $\overline{b \in B}$  QED.

• Assume  $b^n \in B, b^{n+1} \in B$ ?  $\frac{b^n \in B}{bb^n \in B}$  is a rule QED.

• Assume  $b^n \in B, a^0 b^n a^0 \in A$ ?  $\frac{b^n \in B}{a^0 b^n a^0 \in A}$  QED.

• Assume  $a^n b^m a^n \in A, a^{n+1} b^m a^{n+1} \in A$ ?  $\frac{a^n b^m a^n \in A}{a^{n+1} b^m a^{n+1} \in A}$  QED.

(4)

Induction on derivations

$$P(d/a^n b^m a^n \in L) \stackrel{def}{=} n+m+1$$

$$\frac{a^n b^m a^n}{a^{n+1} b^m a^{n+1}}$$

$$P(d/a^n b^m a^n / a^{n+1} b^m a^{n+1}) =$$

$$P(d/a^n b^m a^n) + 1 = (n+m+1) + 1 \\ = m+(n+1) + 1 \quad \text{QED.}$$

$$\frac{b^m \in B}{a^0 b^m a^0 \in A}$$

$$P(d/b^m / a^0 b^m a^0) =$$

$$P(d/b^m) + 1 = m+1 = (m+0) + 1 \quad \text{QED}$$

$$\frac{b^m \in B}{b^{m+1} \in B}$$

$$P(d/b^m / b^{m+1}) =$$

$$P(d/b^m) + 1 = m+1 \quad \text{QED}$$

$$b \in B$$

$$P(d/b) = 1$$

QED

### Exercise 3

- If  $\llbracket dx.t \rrbracket_P$  is not a constant, then

$$\llbracket dx.t \rrbracket_P \perp_{N_1} = \perp_{N_1}$$

In fact,  $\llbracket dx.t \rrbracket_P$  is a monotone (continuous)

function, and  $\llbracket dx.t \rrbracket_P \llbracket L \rrbracket = \llbracket h \rrbracket$

$$\llbracket dx.t \rrbracket_P \llbracket M \rrbracket = \llbracket K \rrbracket$$

then  $\llbracket dx.t \rrbracket_P \perp_{N_1} = x$  with  $x \in \llbracket h \rrbracket$  and  $x \in \llbracket K \rrbracket$

$$\text{i.e. } x = \perp_{N_1}$$

- $\llbracket rec\ x.t \rrbracket_P = \text{fix } dd. \llbracket t \rrbracket_P [dx]$

$$d_0 = \perp_{N_1}$$

$$d_1 = dd. \llbracket t \rrbracket_P [dx] = \llbracket dx.t \rrbracket_P \perp_{N_1} = \perp_{N_1}$$

QED.

- Case analysis:

op has a natural extension  $\Rightarrow$  on bottom evaluates to  $\perp$

if  $t_0$  then  $t_1$  else  $t_2$  has a natural extension to

$t_0$  but not to  $t_1$  and  $t_2$  dx. if  $t_0$  then  $\perp$  else  $x$  is constant and symmetrically

$(t_1\ t_2)$  has a natural extension on  $dx\ t_1$  but not on  $dx\ t_2$

$((\lambda x.3)x)$  is constant

$dx.t$  cannot have type int

### Exercise 4

- $P \xrightarrow{\alpha} Q \Rightarrow \mathbb{P}P \xrightarrow{\alpha} \mathbb{Q}P$

Given a proof of  $P \xrightarrow{\alpha} Q$ , it is possible to derive a proof of  $\mathbb{P}P \xrightarrow{\alpha} \mathbb{Q}P$  by applying substitution  $\rho$  on the free names of  $P$ . Notice that bound names of  $\lambda$  cannot be free names of  $P$  and thus are not involved in its substitution, but substitutions capturing them must be excluded

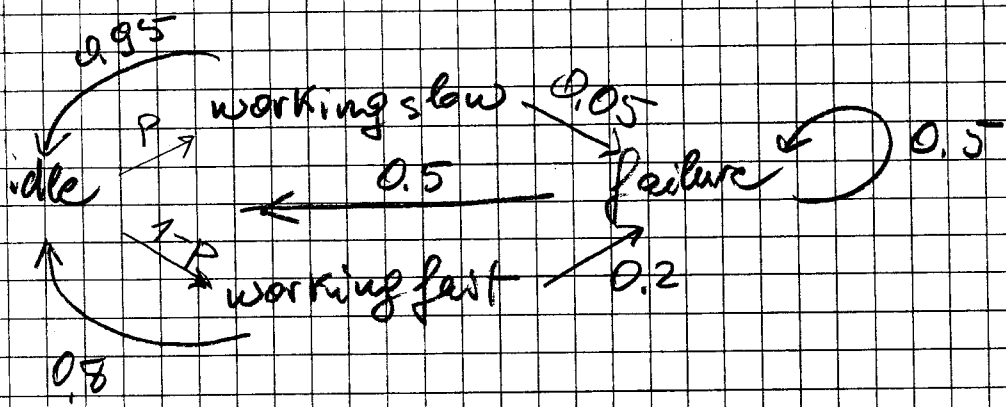
- $\mathbb{P}P \xrightarrow{\alpha} \mathbb{Q}P \Rightarrow P \xrightarrow{\alpha} Q$

If  $\rho$  is injective then we have  $\rho \circ \rho^{-1} = \text{id}$ . Thus we can apply the previous result with  $\rho^{-1}$ .

- If  $\rho$  is not injective, we have the counterexample!

given  $\rho = (x' / x) \cdot \text{id} / \bar{x}x, \text{id}$   
 we have  $\rho \left[ \frac{x'}{x} \right] \xrightarrow{\tau} \text{id} / \text{id}$   
 while  $\rho \not\xrightarrow{\tau}$ .

### Exercise 5



$$\begin{cases} i = 0.95s + 0.8f + 0.5k \\ s = pi \\ f = (1-p)i \\ k = 0.05s + 0.2f + 0.5k \\ i + s + f + k = 1 \end{cases}$$

$$k = 0.1s + 0.4f = (0.1p + 0.4(1-p))i = (0.4 - 0.3p)i$$

$$(1 + p + 1 - p + 0.4 - 0.3p)i = 1$$

$$i = \frac{1}{2.4 - 0.3p} \quad s = \frac{p}{2.4 - 0.3p}$$

$$f = \frac{1-p}{2.4 - 0.3p} \quad k = \frac{0.4 - 0.3p}{2.4 - 0.3p}$$

$$\text{Gain} = \frac{p + 2(1-p)}{2.4 - 0.3p} = \frac{2-p}{2.4 - 0.3p}$$

$$p = 0 \text{ (fast)} \quad \text{Gain} = \frac{2}{2.4} = 0.833$$

$$p = 1 \text{ (slow)} \quad \text{Gain} = \frac{1}{2.1} = 0.476$$

$$\text{Derivative of Gain: } \frac{-1}{2.4 - 0.3p} - \frac{2-p}{(2.4 - 0.3p)^2} \cdot (-0.3)$$

$= \frac{-1.8}{(2.4 - 0.3p)^2}$  always negative: max gain for  $p = 0$  fast